

算法设计与分析

Lecture 12: Backtracking

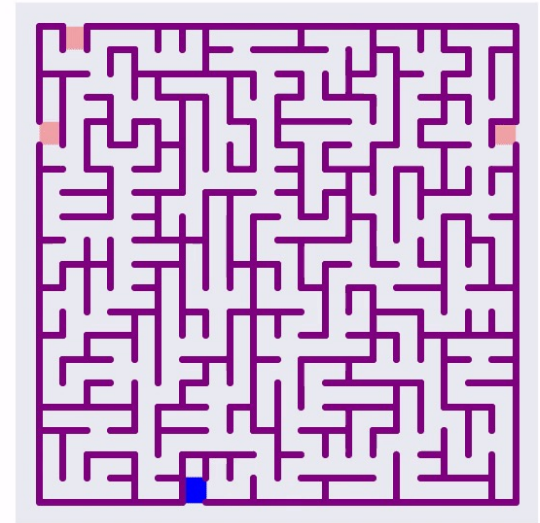
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Backtracking

- A simple and straightforward strategy to escape from a maze is:
 - Go as deep as possible until reach a dead end.
 - Go back to the last fork and choose another path.
- If we have a sign at the fork to show dead ends, we can avoid that path to save time.
- This is the idea of **backtracking (回溯)**. It is a refinement of the brute force approach by **avoiding dead ends in advance**.

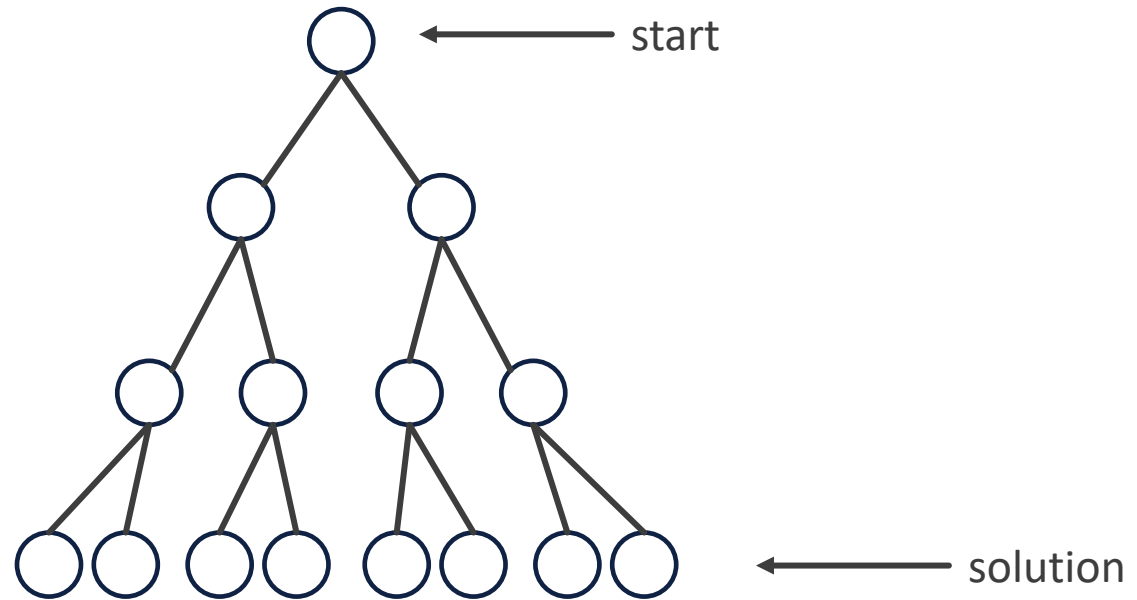


A maze

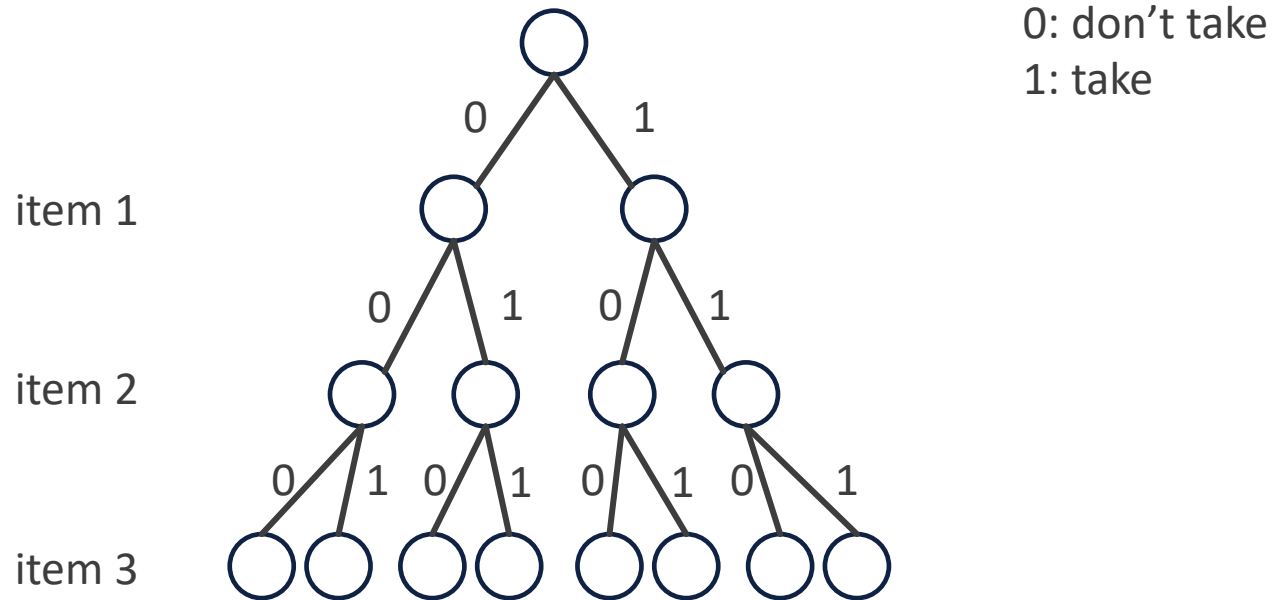


Backtracking

- Given the an optimization problem, we usually make a sequence of decisions. It can be represented as a tree.
- We start from the root and the solutions are the leaves.



Backtracking

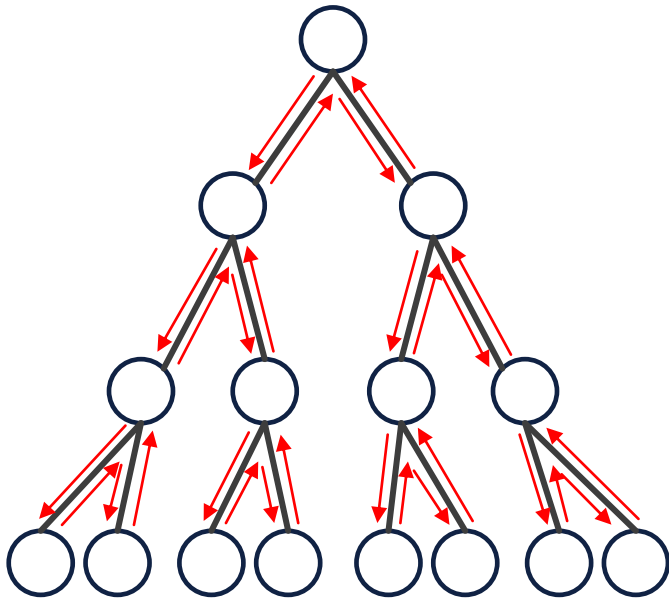


Solution space for 0/1 knapsack problem with 3 items

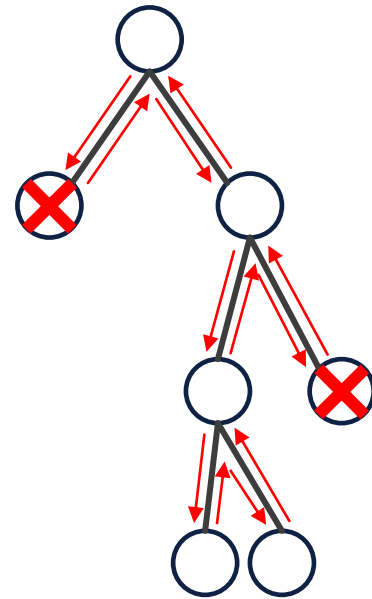


DFS vs. Backtracking

If we know that going along this branch has no hope, we don't need to try! It will save a lot of time.



DFS



Backtracking



Backtracking

- Backtracking is all about **HOPE!**
- We only continue to search solutions only if there is still hope!



Backtracking

- In the backtracking method, the solutions are represented by vectors (x_1, x_2, \dots, x_n) .
- In step $i + 1$, we start from a partial solution (x_1, x_2, \dots, x_i) and try to extend it by adding another element x_{i+1} .
- After extending it, we will test whether $(x_1, x_2, \dots, x_i, x_{i+1})$ is still possible as a partial solution (check hope).



Backtracking

The steps involved in the backtracking method are:

1. Define a **solution space (解空间)** for the problem. This space must include at least one (optimal) solution to the problem.
 - If S_i is the domain of x_i , then $S_1 \times S_2 \times \dots \times S_n$ is the solution space of the problem.
 - Generally, the solution space is very huge, so the cost of searching a objective solution are often unimaginable.
 - For backtracking to be efficient, we must **prune (剪枝) the search space.**



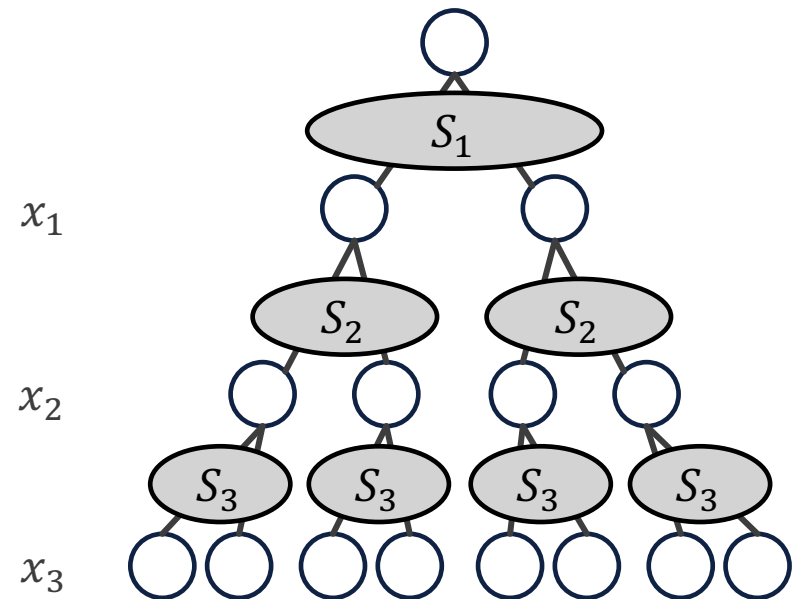
Backtracking

2. Organize the solution space so that it can be searched easily. The typical organization is either a graph or a tree.
3. Searched the solution space in a DFS manner and avoid moving into subspaces that cannot possibly lead to the answer.



Solution Space Tree

- We set up a tree structure such that the leaves represent members of the solution space.
- So we organize solution space as a **solution space tree** (解空间树).
- Backtracking can easily be used to iterate through all subsets or permutations of a set.

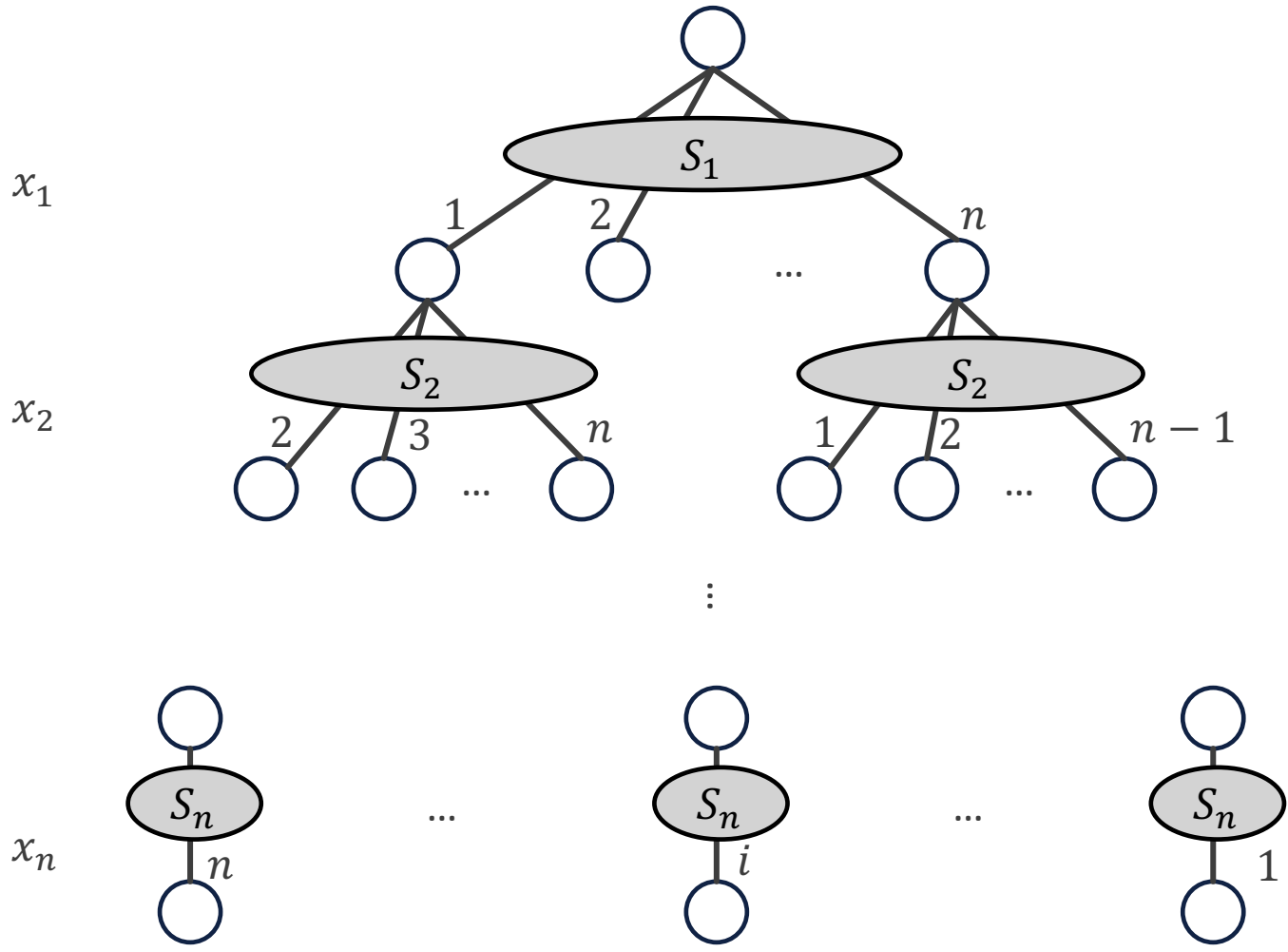


Example

- When the problem asks for an n -element permutation that optimizes some function, the solution space tree is a **permutation tree**.
- How many permutations are there of an n -element set?
 - There are n choices for x_1 .
 - There are $n - 1$ choices for x_2 .
 - ...
 - There is only 1 choices for x_n .



S_{i+1} depends on the choice of x_i



General Backtracking Template

Backtrack(i)

```
1  if  $i > n$  then Update( $x$ )
2  else
3    for each  $a \in S_i$  do
4       $x_i \leftarrow a$ 
5      if  $C(i)$  and  $B(i)$  then
6        Backtrack( $i + 1$ )
```

Reaching leaf means that it is a feasible solution.

Hope checking condition, key of backtracking. Without it, it is just brute-force.



Pruning

- In backtracking, we have a **constraint function (约束函数)** $C(i)$ and a **bounding function (限界函数)** $B(i)$, to **prune invalid branches and to focus the search on branches that appear most promising.**
 - Keep in mind, we don't waste time on hopeless branches.
- In order to improve the performance of search, applying backtracking requires specifying at least the following three points:
 - How to choose an the constraint function.
 - How to compute upper bounds (for maximum problem) and lower bounds (for minimum problem).
 - How to make use of the constraint function and the bounding function to prune.



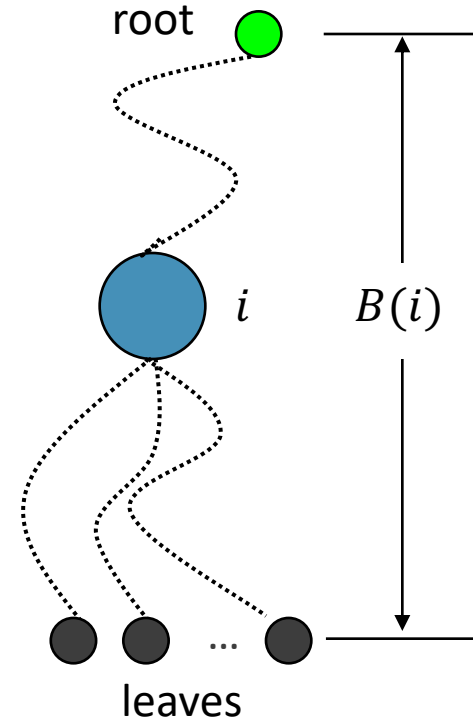
Constraint Function

- Constraint function is to check the feasibility of the current solution.
- Usually, it can be easily built by the problem requirement. For example:
 - 0/1 knapsack problem: check if adding the next item exceeds W .
 - Permutation problem: check if the number has been selected.
 - Hamiltonian cycle problem: check (1) if next vertex is connected to the current vertex; (2) if the last vertex is connected to the first vertex; (3) if there exist duplicated vertex in the path.
 - Coloring problem: check if the color for the next vertex is same as its neighbors.

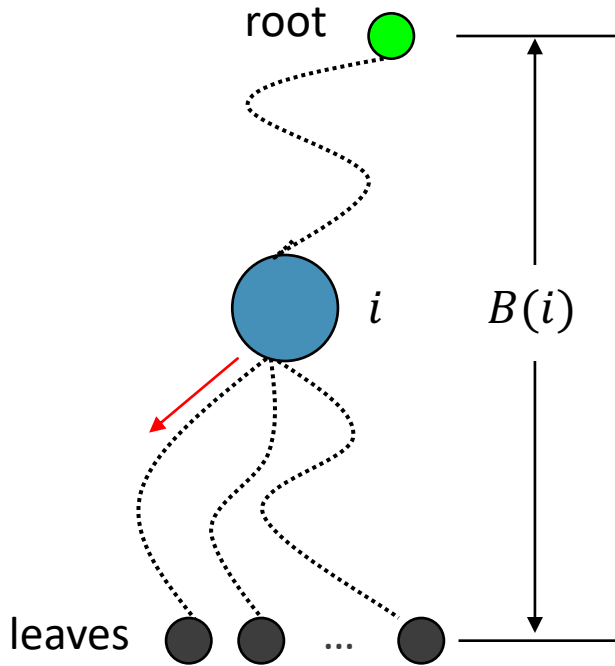


Bounding Function

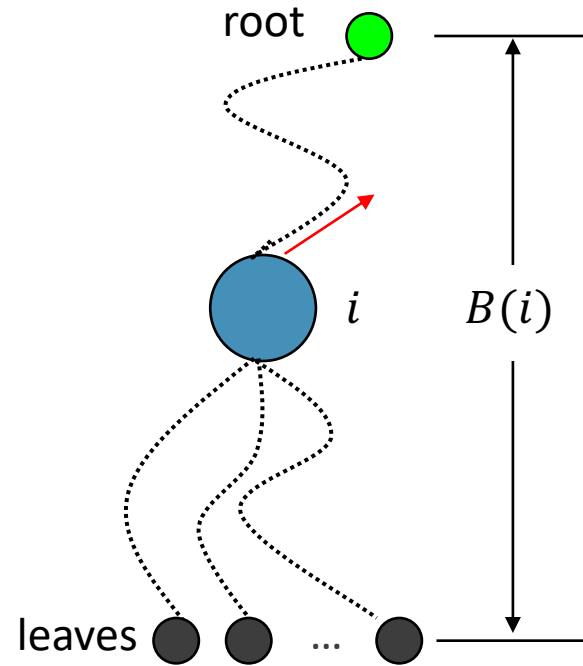
- Bounding function is for optimization problem.
- For maximization problem, it calculates the upper bound of this branch $B(i)$ and compare with the existing best solution $bestc$.
 - If $B(i) > bestc$, there is still hope, keep searching!
 - If $B(i) \leq bestc$, all solutions along this branch will not better than the existing best solution, stop!



Bounding Function



$B(i) > bestc$, go ahead,
there is still hope!



$B(i) \leq bestc$, go back, it
is hopeless!





CONTAINER LOADING PROBLEM

Container Loading Problem

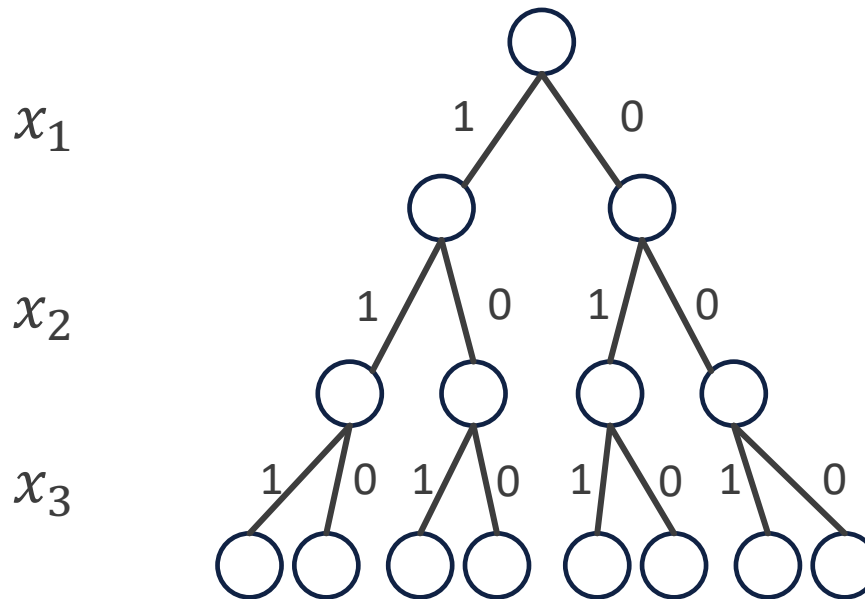
- Given n containers (集装箱), container i has weight w_i . The ship can hold containers of total weight up to W .
- Container Loading problem is to load as many containers as is possible without sinking the ship.
- Assuming that the solutions are represented by vectors (x_1, x_2, \dots, x_n) , where $x_i \in \{0, 1\}$. 1 denotes taking container i and 0 denotes not taking container i .
- The container loading problem can be formally stated as follows:

$$\max \sum_{i=1}^n w_i x_i \quad s. t. \quad \sum_{i=1}^n w_i x_i \leq W$$



Container Loading Problem

- Each x_i has two options to choose: take and not take.
- Therefore, $|S_i| = 2$ and the size of the solution space is 2^n . It also means that the solution space tree has 2^n leaves.



Solution space tree with $n = 3$



Container Loading Problem

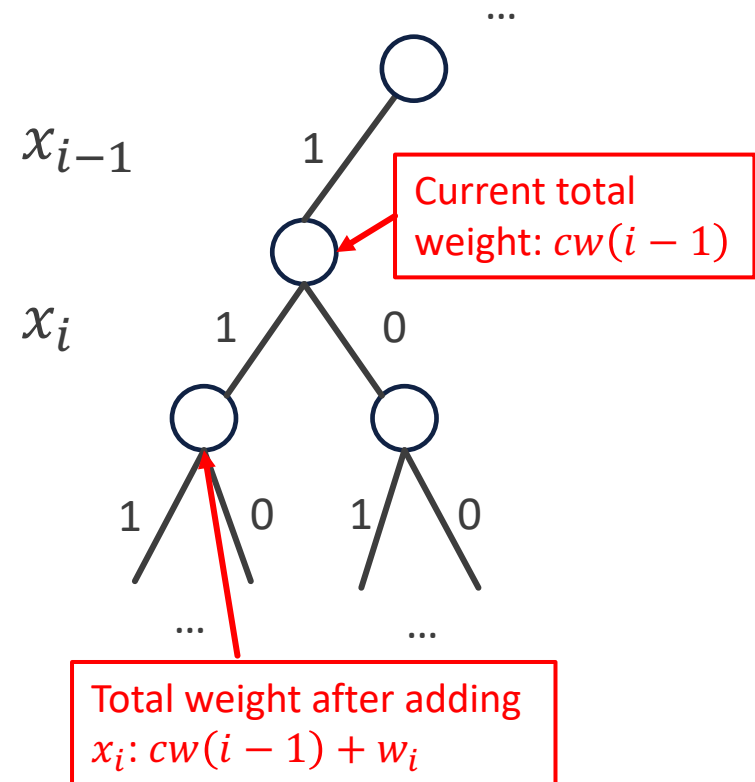
- We first design the constraint function.
- Let $cw(i)$ denote the current weight up to level i , namely

$$cw(i) = \sum_{j=1}^i w_j x_j$$

then the constraint function is

$$C(i) = cw(i - 1) + w_i$$

- The pruning condition is $C(i) > W$, which means there is no capacity to take container i .



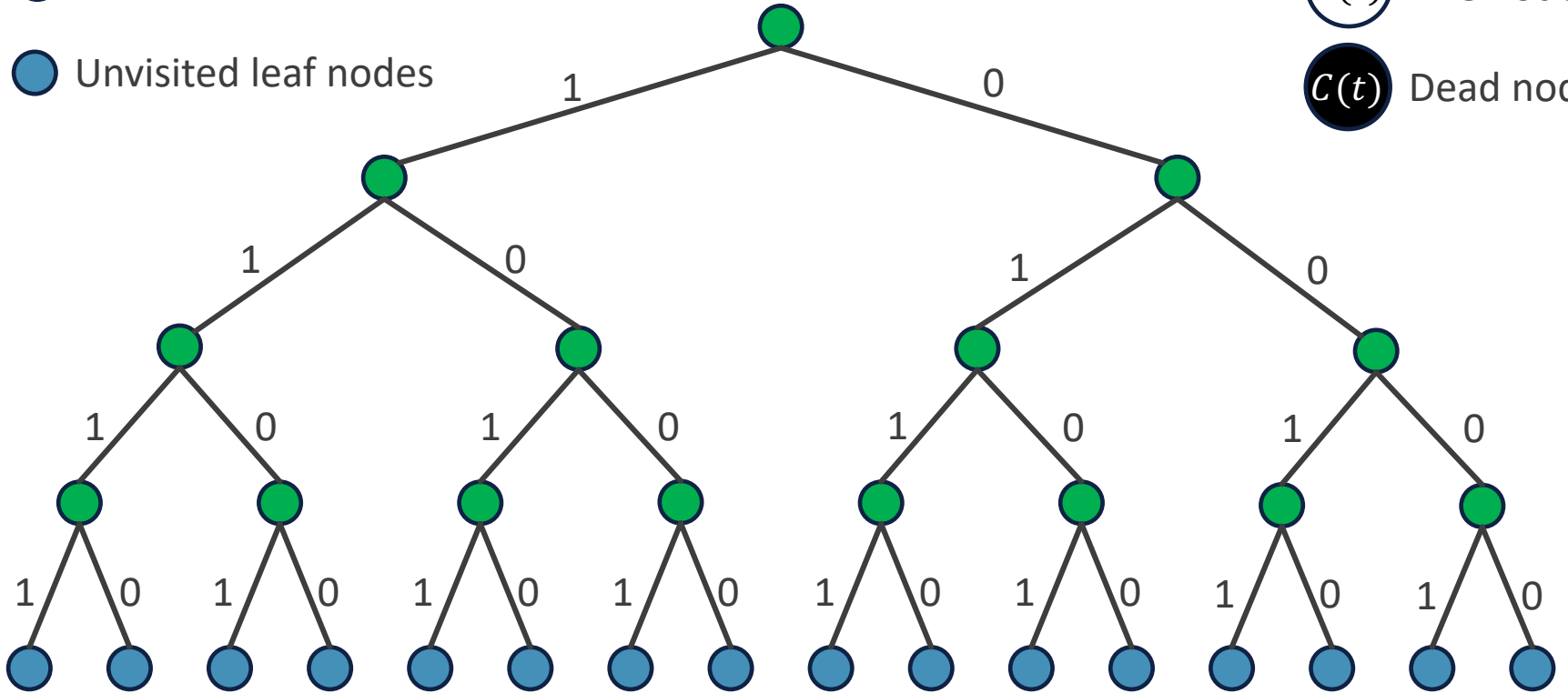
Example

● Unvisited internal nodes

● Unvisited leaf nodes

$C(t)$ Live nodes

\ominus Dead nodes



Backtracking for $n = 4, w = [8,6,2,3], W = 12$



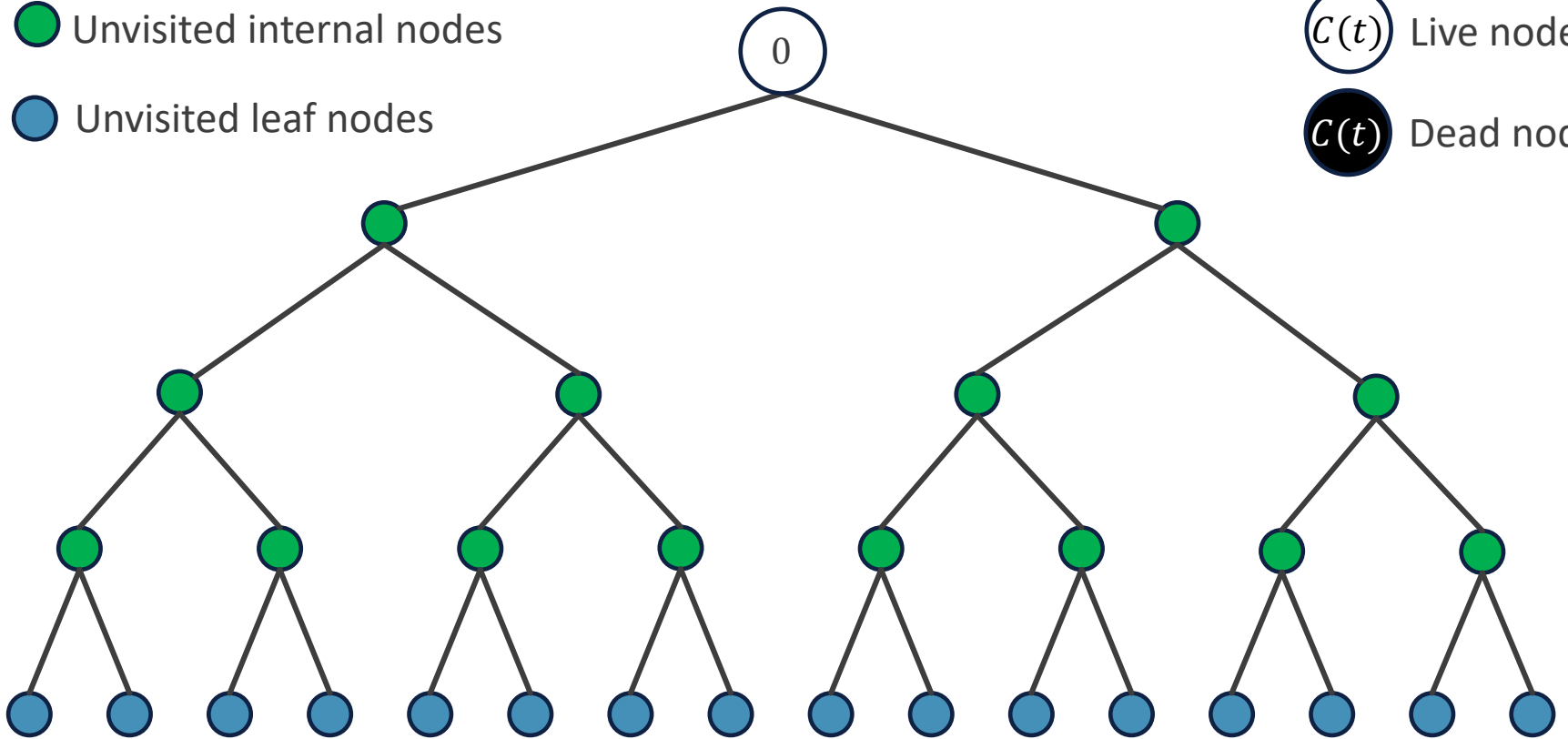
Example

● Unvisited internal nodes

● Unvisited leaf nodes

○ $C(t)$ Live nodes

● $C(t)$ Dead nodes



Backtracking for $n = 4, w = [8,6,2,3], W = 12$



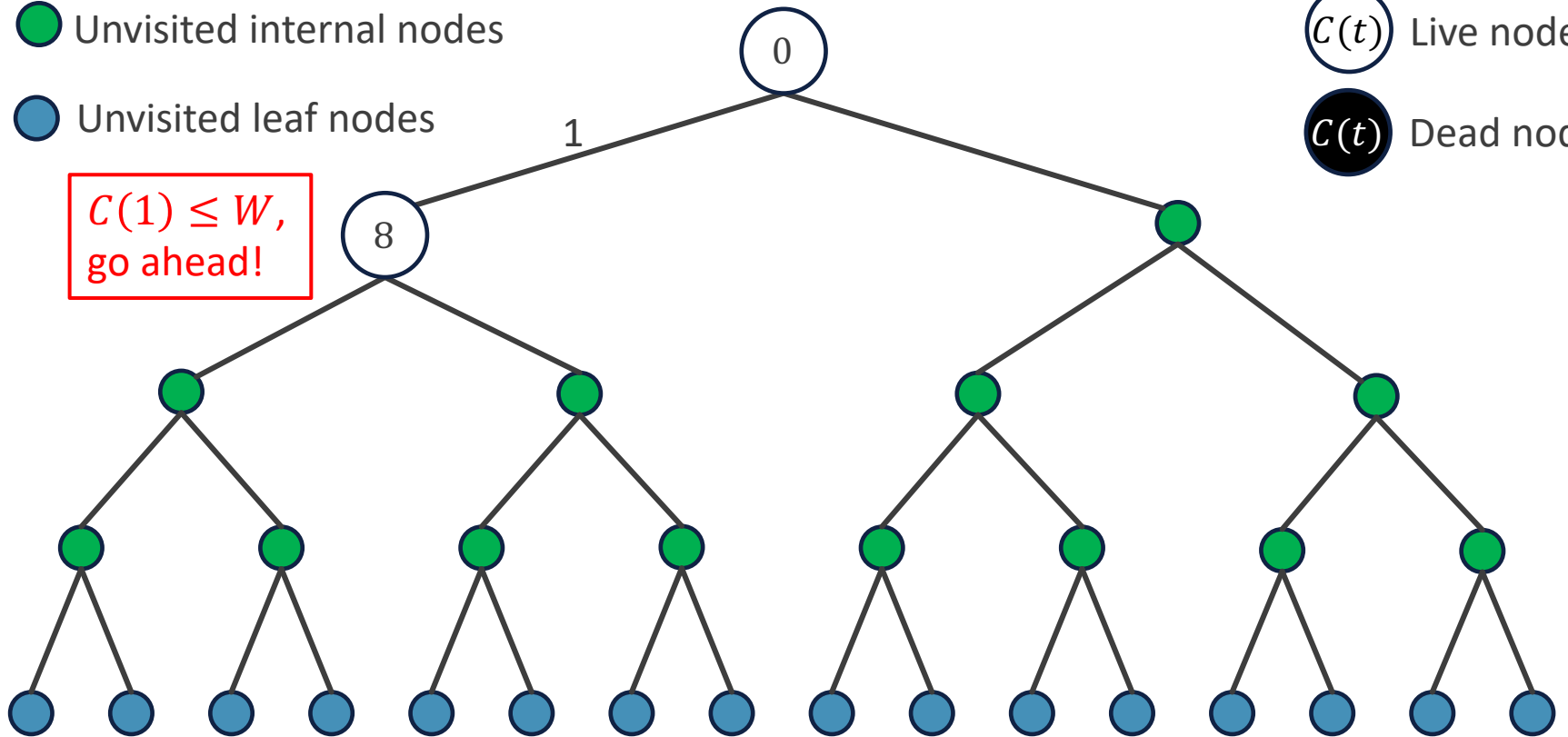
Example

● Unvisited internal nodes

● Unvisited leaf nodes

○ $C(t)$ Live nodes

● $C(t)$ Dead nodes



Backtracking for $n = 4, w = [8,6,2,3], W = 12$



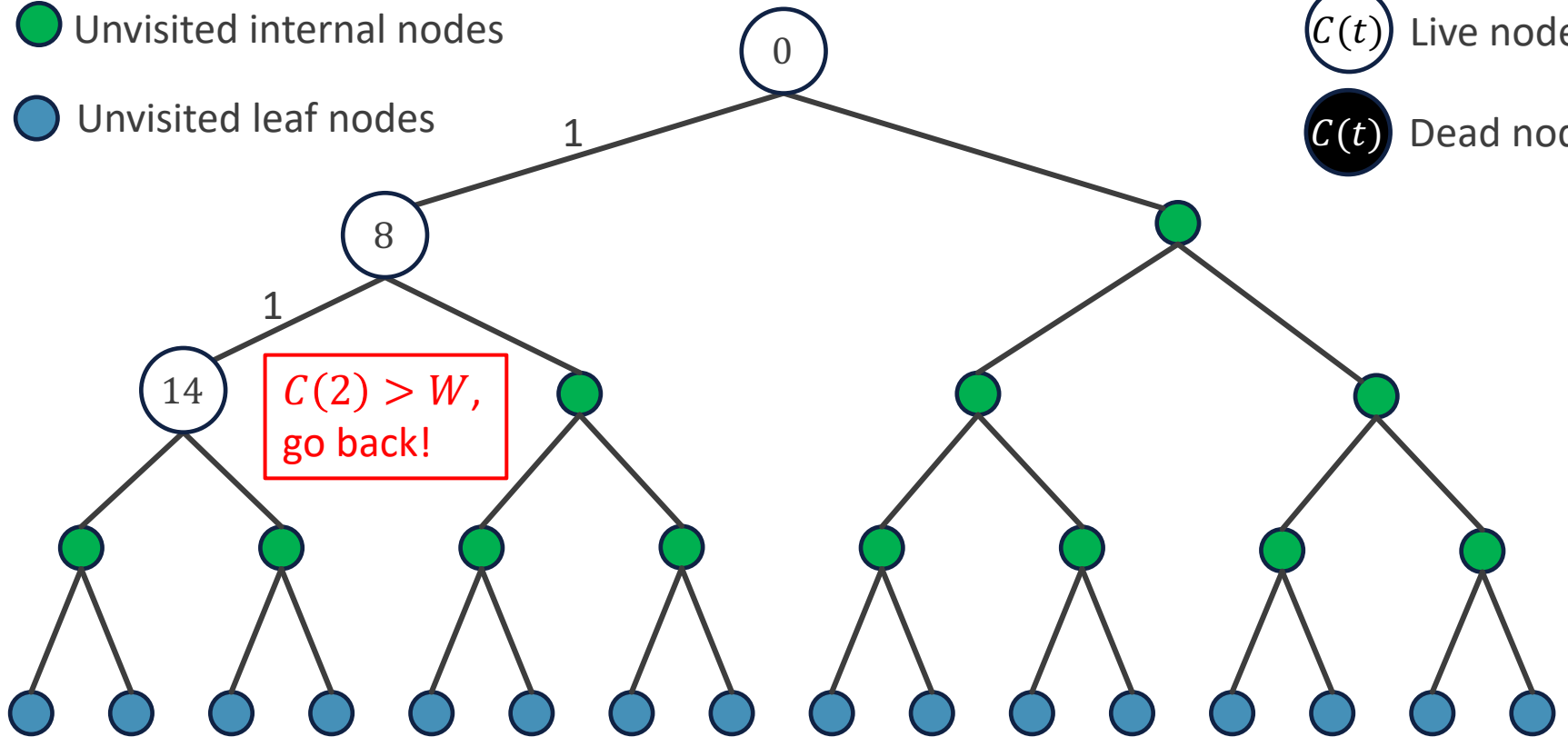
Example

● Unvisited internal nodes

● Unvisited leaf nodes

○ $C(t)$ Live nodes

● $C(t)$ Dead nodes



Backtracking for $n = 4, w = [8,6,2,3], W = 12$



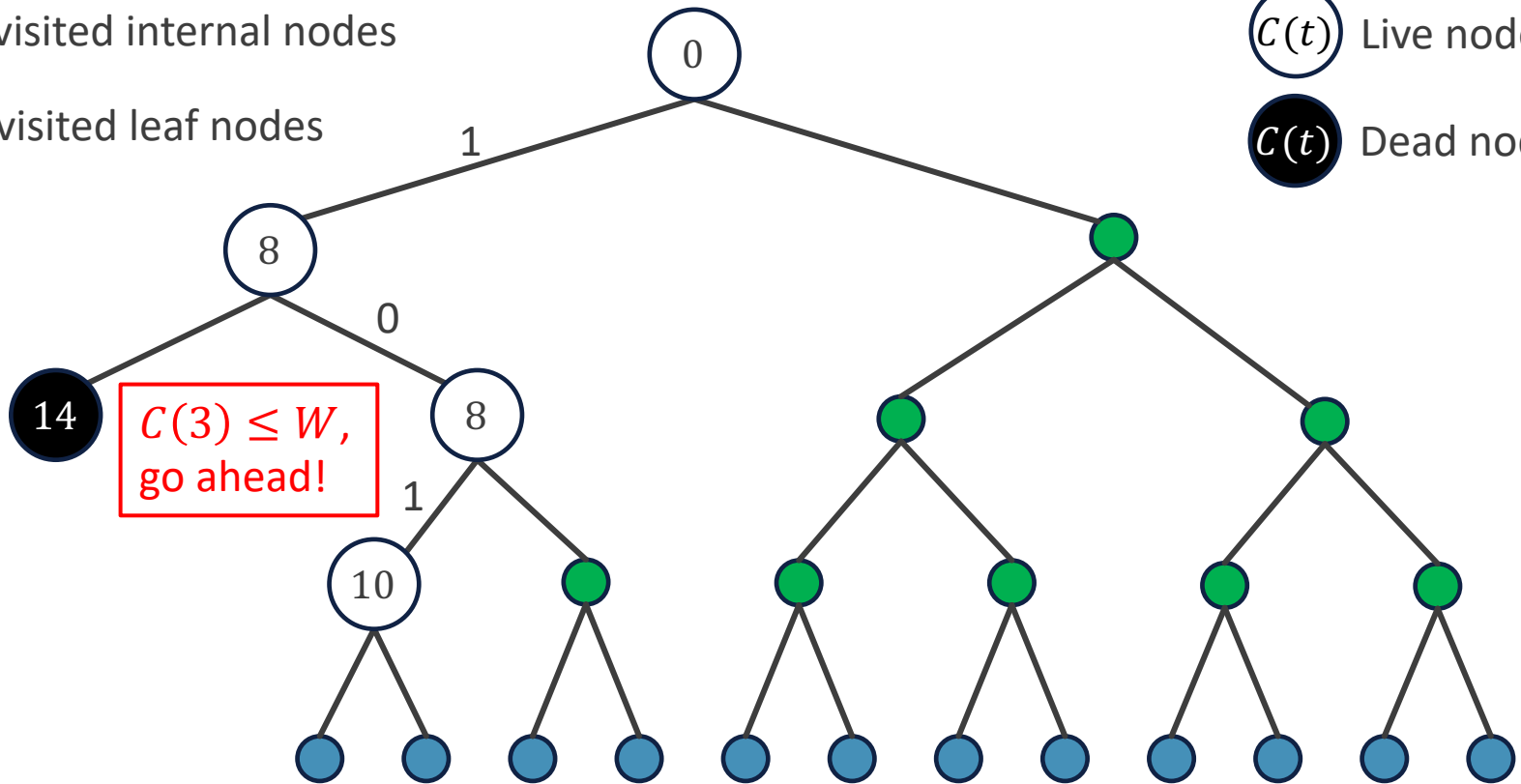
Example

● Unvisited internal nodes

● Unvisited leaf nodes

○ $C(t)$ Live nodes

● $C(t)$ Dead nodes



Backtracking for $n = 4, w = [8,6,2,3], W = 12$



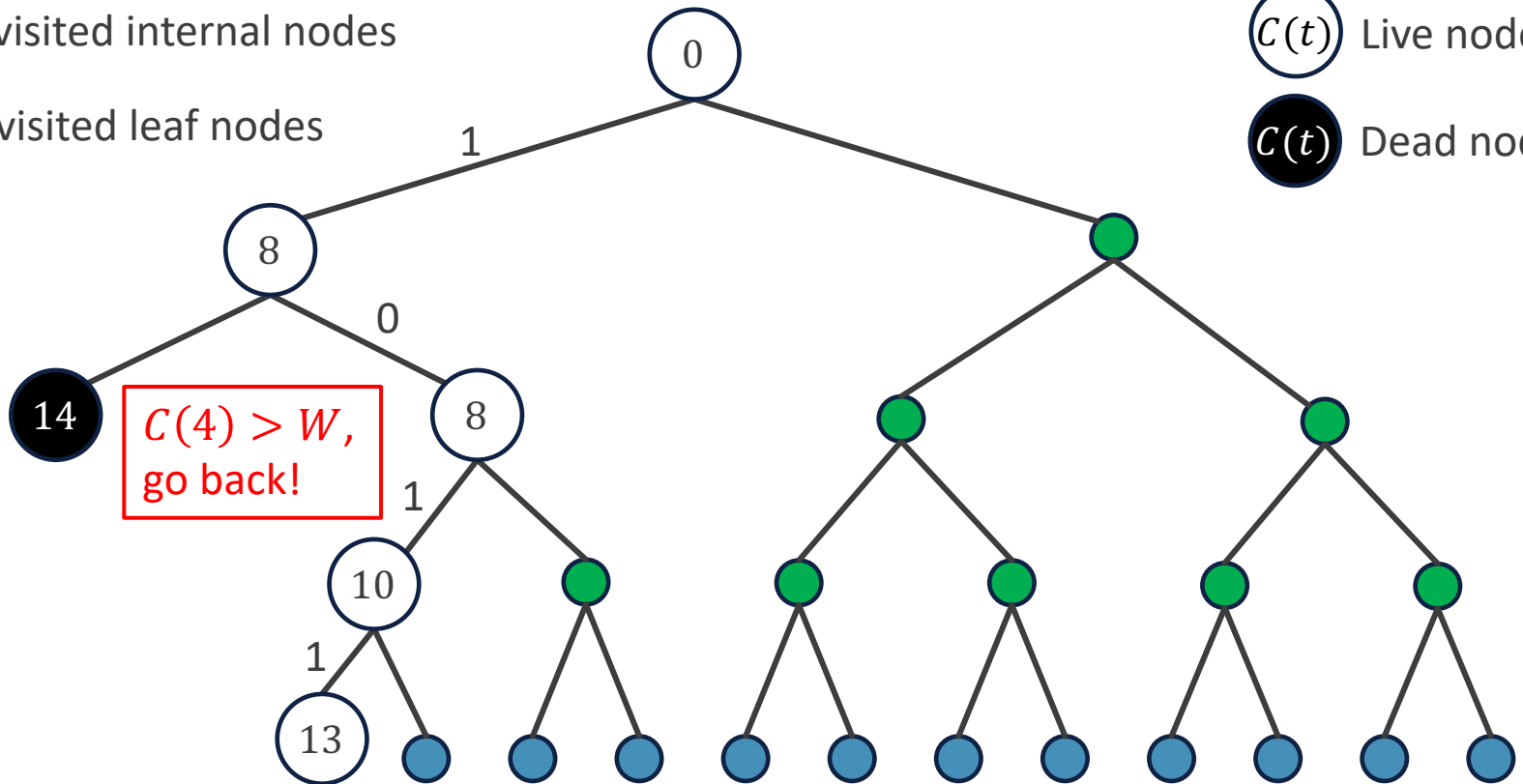
Example

● Unvisited internal nodes

● Unvisited leaf nodes

○ $C(t)$ Live nodes

● $C(t)$ Dead nodes



Backtracking for $n = 4, w = [8, 6, 2, 3], W = 12$



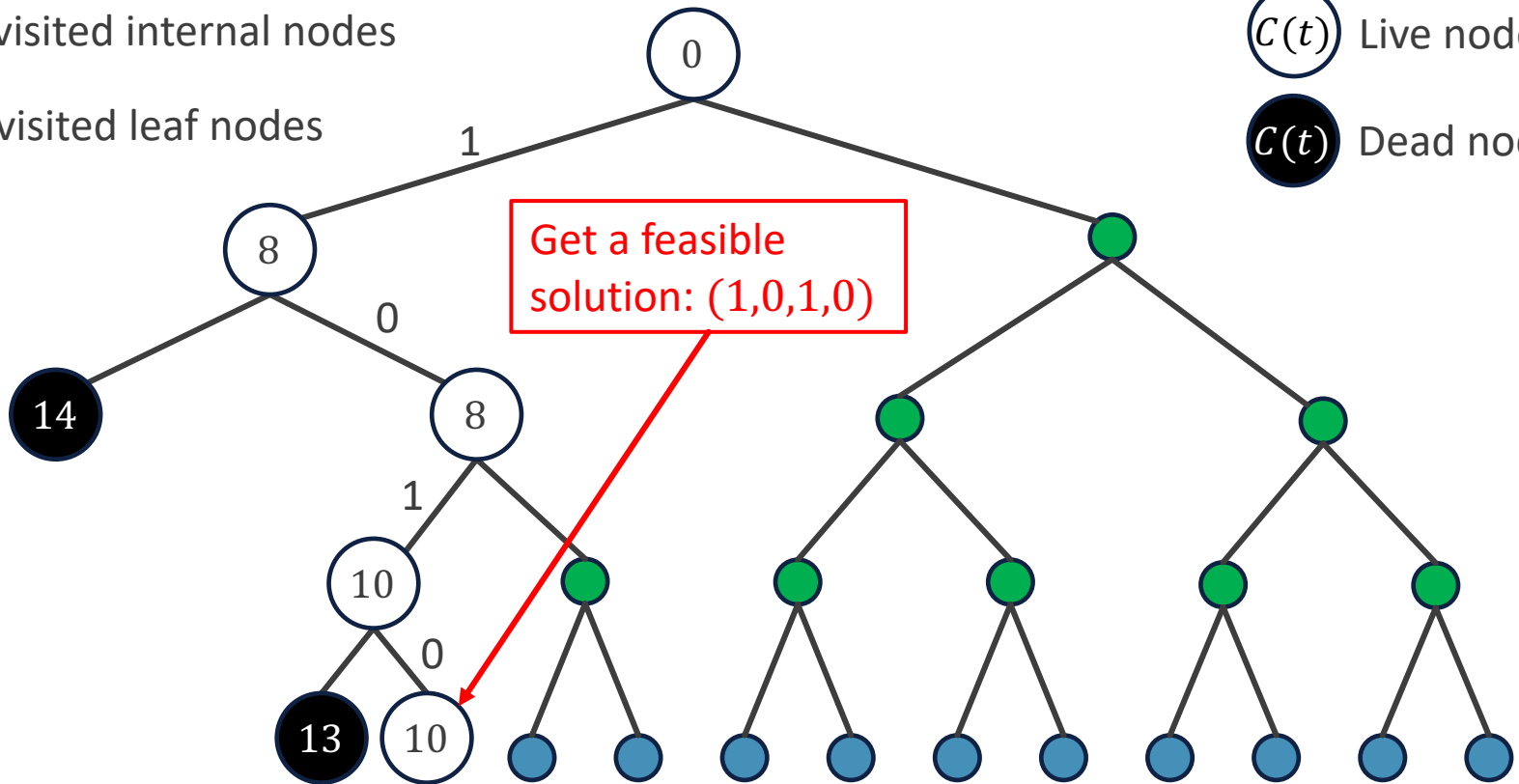
Example

● Unvisited internal nodes

● Unvisited leaf nodes

○ $C(t)$ Live nodes

● $C(t)$ Dead nodes



Backtracking for $n = 4, w = [8,6,2,3], W = 12$



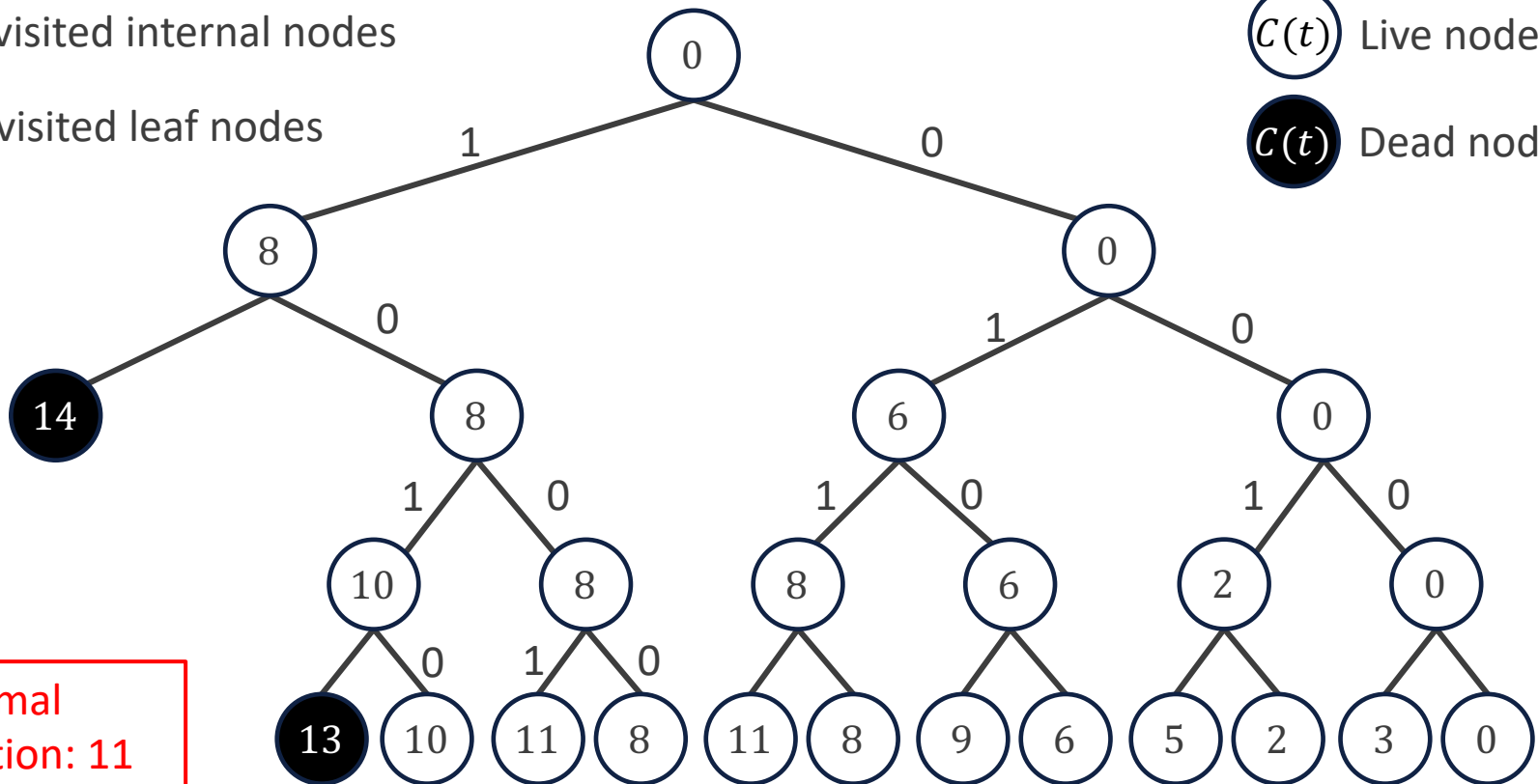
Example

● Unvisited internal nodes

● Unvisited leaf nodes

○ $C(t)$ Live nodes

● $C(t)$ Dead nodes



Optimal solution: 11

Backtracking for $n = 4, w = [8,6,2,3], W = 12$

Pseudocode

BacktrackLoading(i)

1 **if** $i > n$ **then**

2 **if** $cw > bestw$ **then**

3 $bestw \leftarrow cw$

4 **else**

5 **if** $C(i) \leq W$ **then**

6 $cw \leftarrow cw + w[i]$

7 BacktrackLoading($i + 1$)

8 $cw \leftarrow cw - w[i]$

9 **0** BacktrackLoading($i + 1$)

Note: we don't actually build a tree structure. Instead, we simply use recursion.

Store best solution so far.

Go ahead by taking container i .

Subtract the weight of container i before we go back.



Example

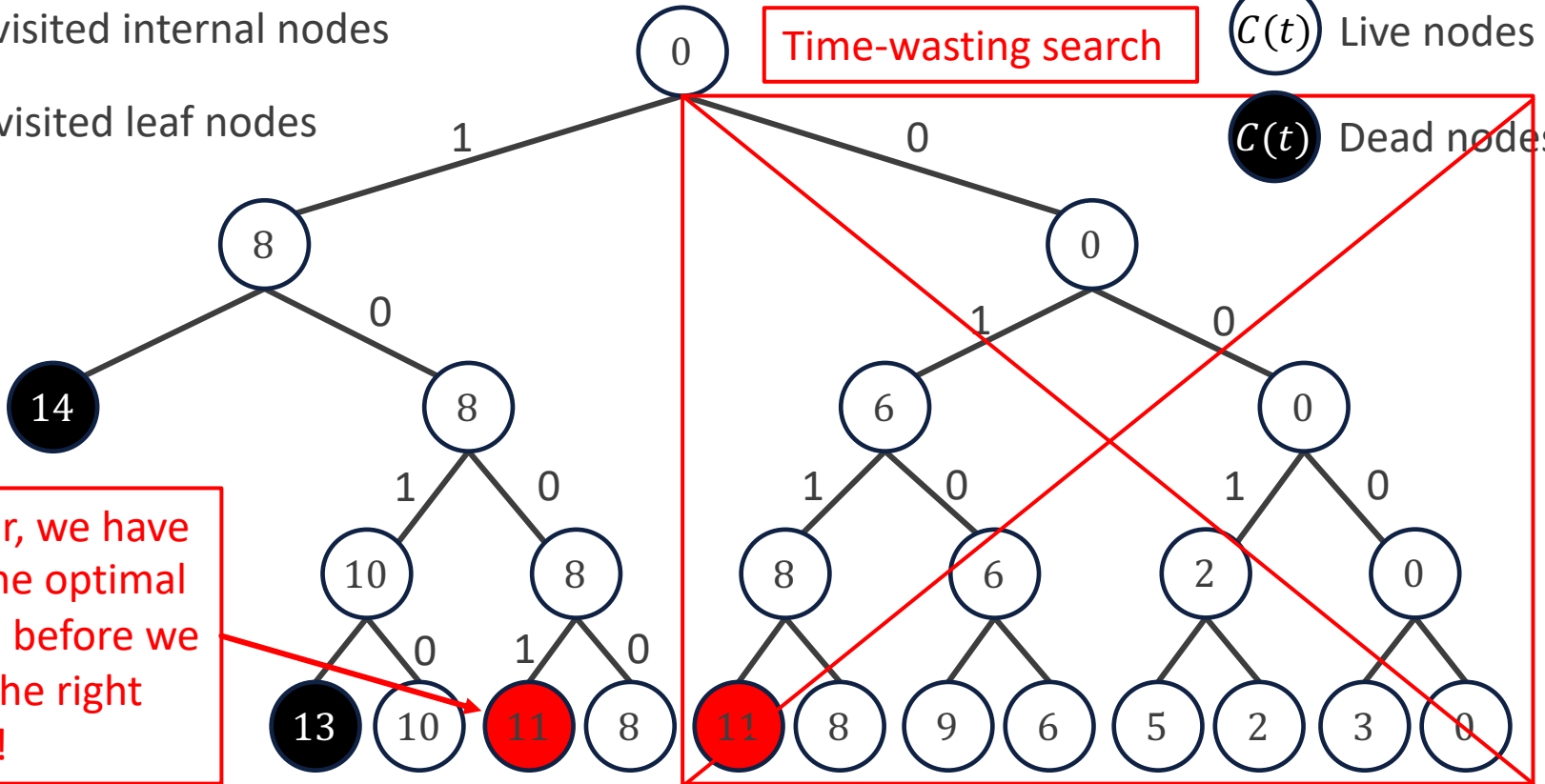
● Unvisited internal nodes

● Unvisited leaf nodes

Time-wasting search

○ $C(t)$ Live nodes

● $C(t)$ Dead nodes



However, we have found the optimal solution before we search the right subtree!

Backtracking for $n = 4, w = [8,6,2,3], W = 12$



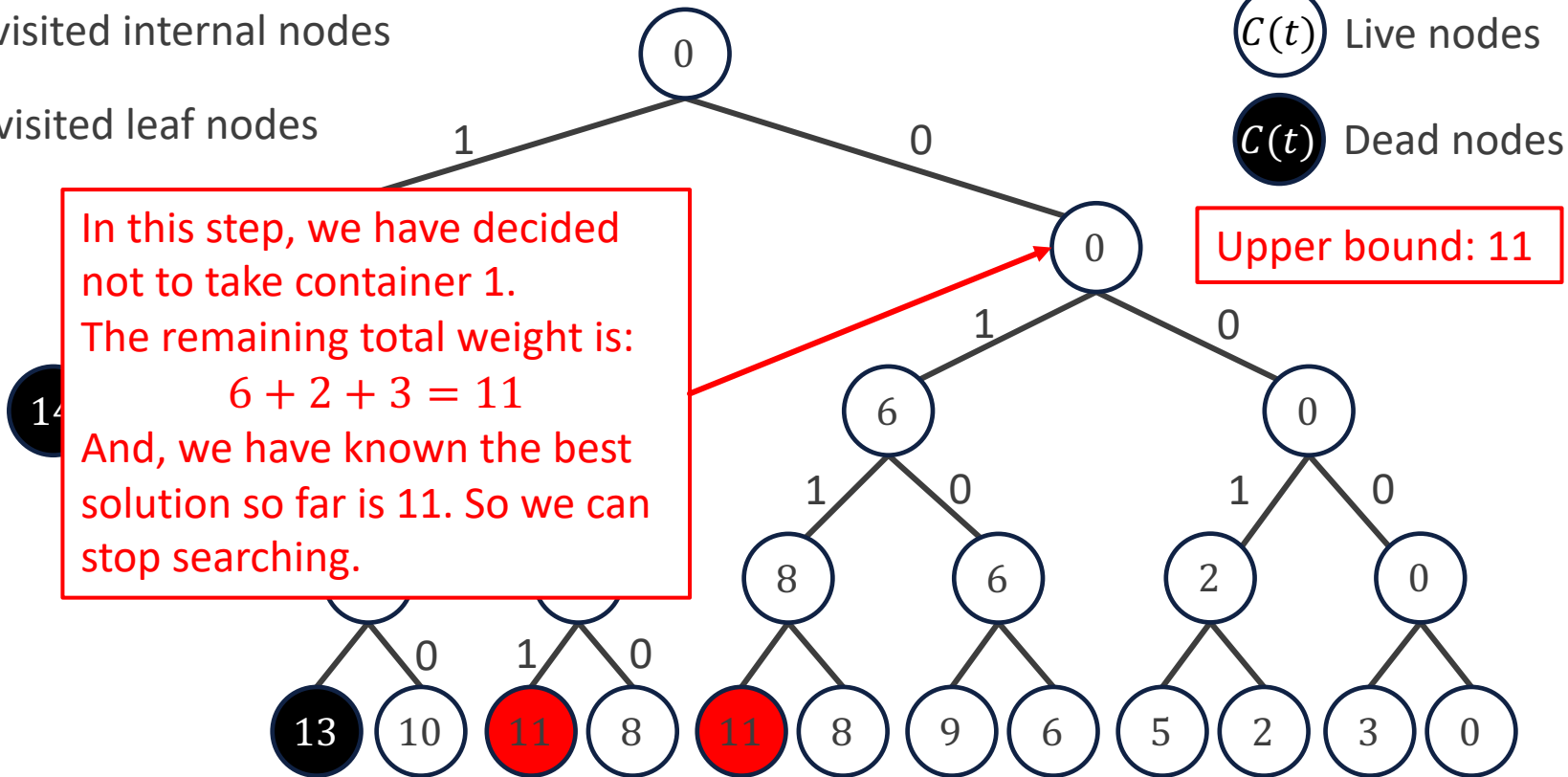
Example

● Unvisited internal nodes

● Unvisited leaf nodes

○ $C(t)$ Live nodes

● $C(t)$ Dead nodes



Backtracking for $n = 4, w = [8, 6, 2, 3], W = 12$

Container Loading Problem

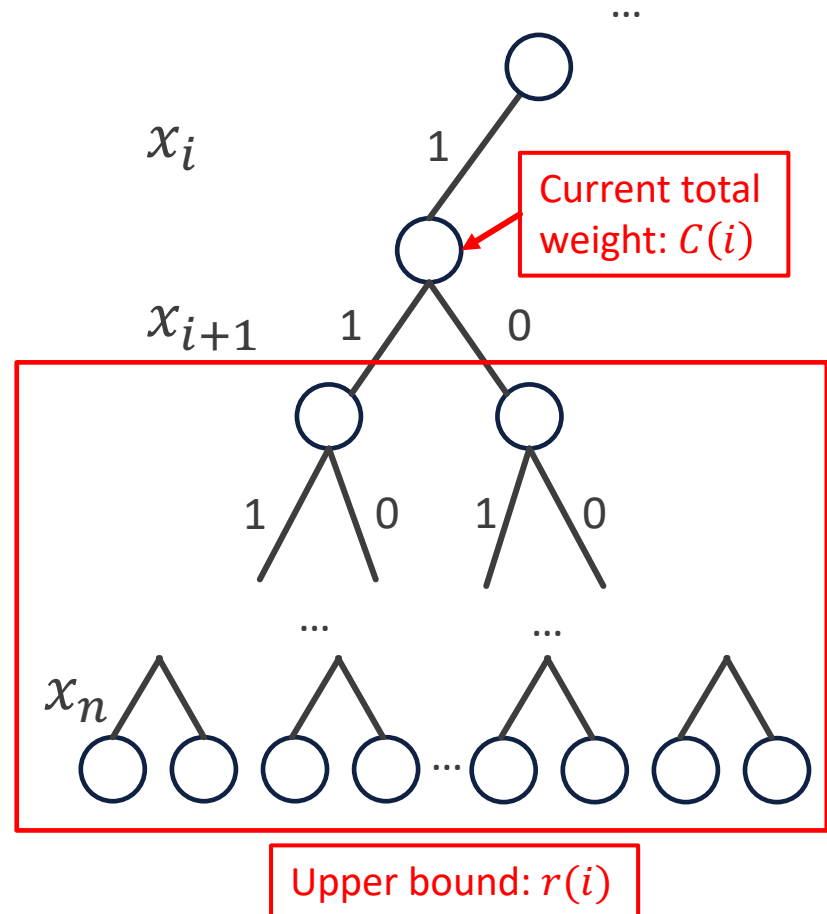
- Now, as an improvement, we add the bounding function:

$$B(i) = C(i) + r(i)$$

where, $r(i)$ denotes the weight sum of the remaining containers, namely,

$$r(i) = \sum_{j=i+1}^n w_j$$

- The pruning condition is $B(i) \leq bestw$, which means the continuing searching along this branch will not give better solution.



Example

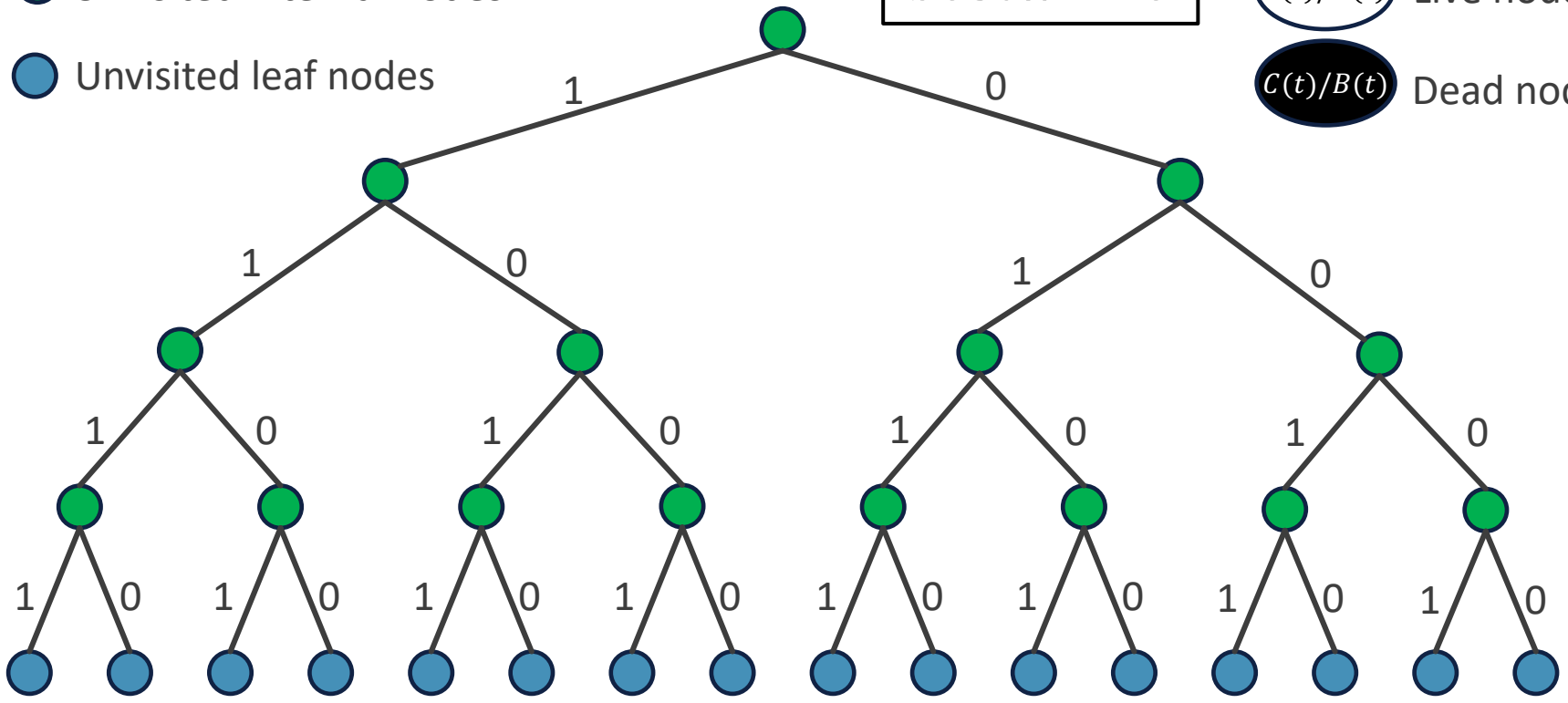
● Unvisited internal nodes

● Unvisited leaf nodes

$bestw = 0$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, w = [8,6,2,3], W = 12$

Example

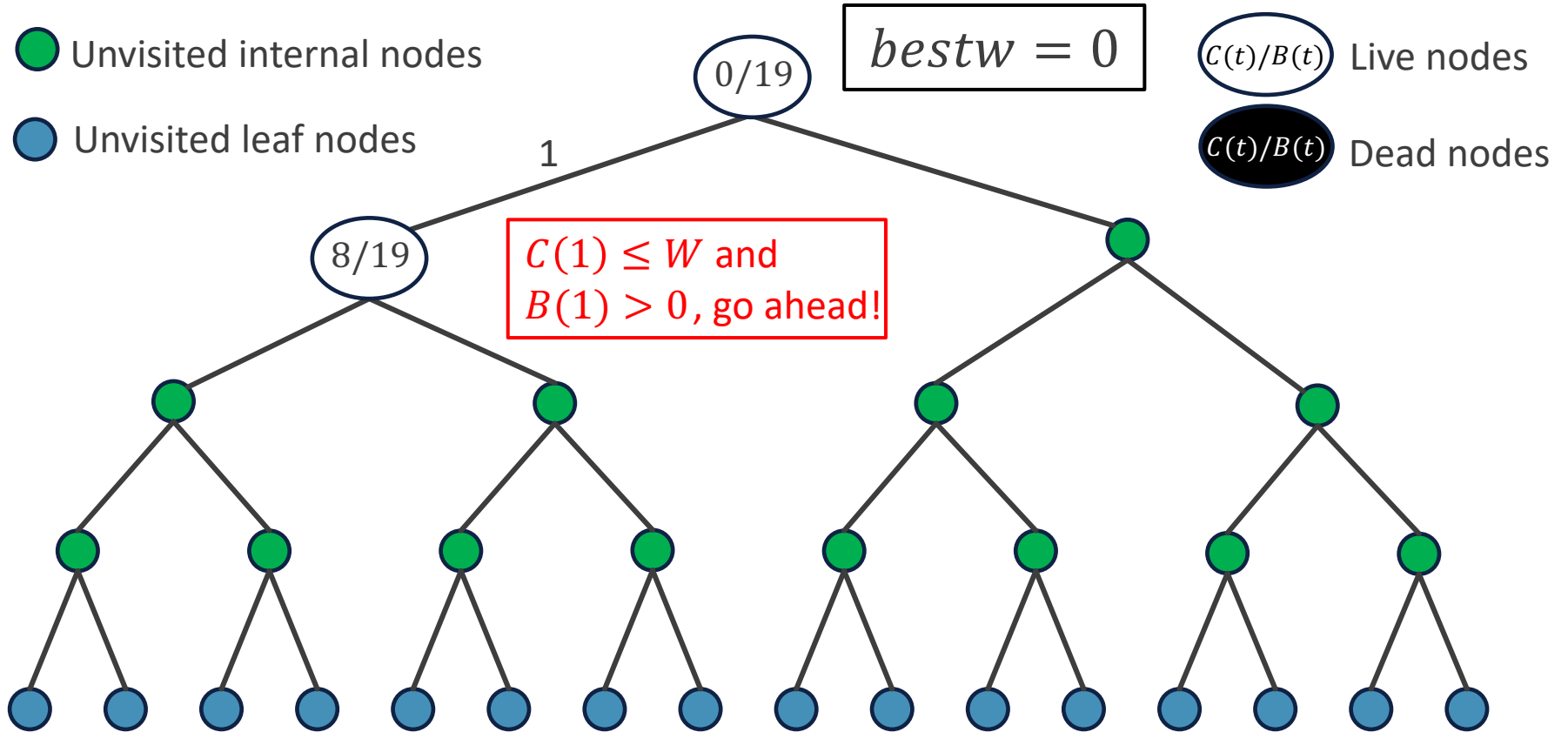
● Unvisited internal nodes

● Unvisited leaf nodes

$bestw = 0$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, w = [8,6,2,3], W = 12$



Example

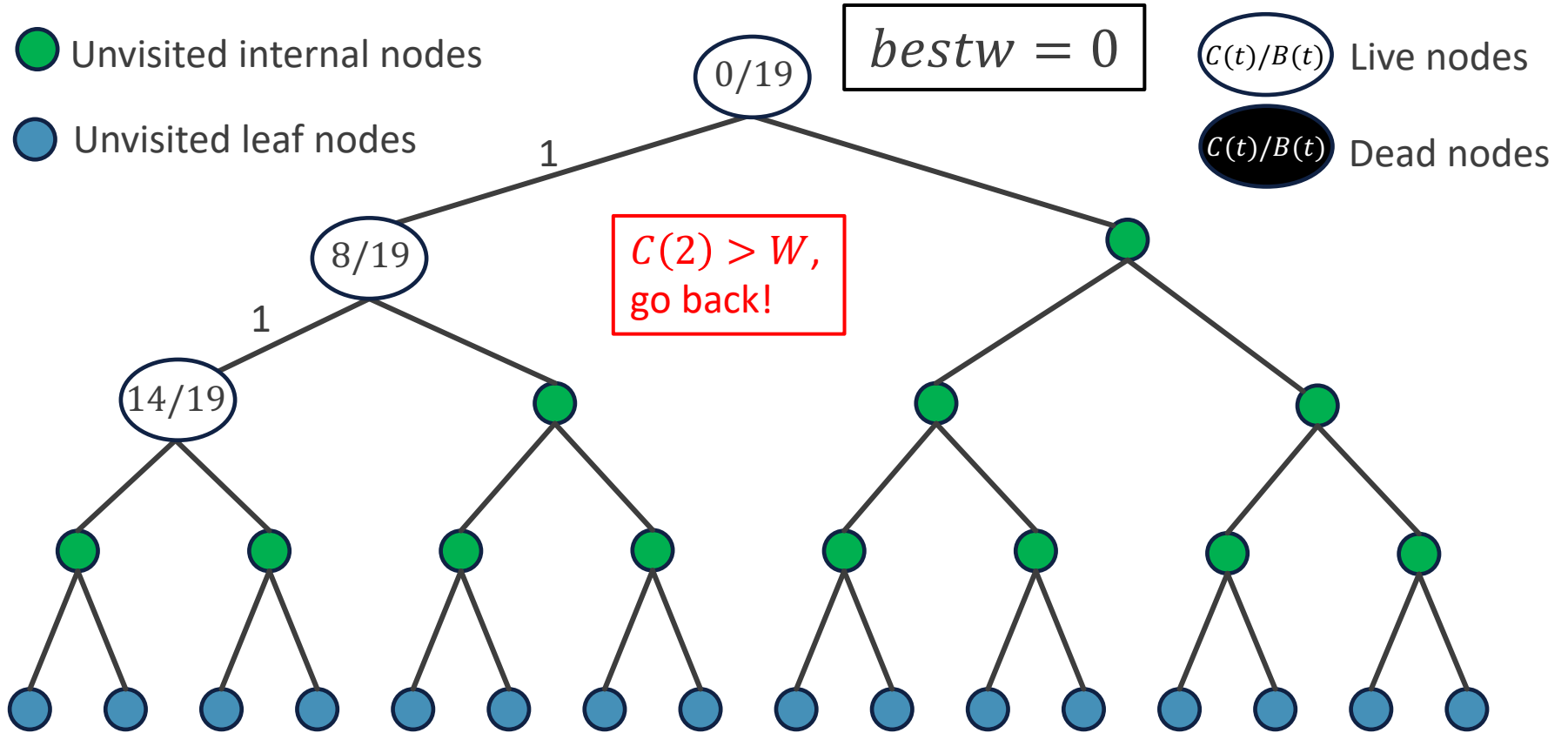
● Unvisited internal nodes

● Unvisited leaf nodes

$bestw = 0$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, w = [8,6,2,3], W = 12$



Example

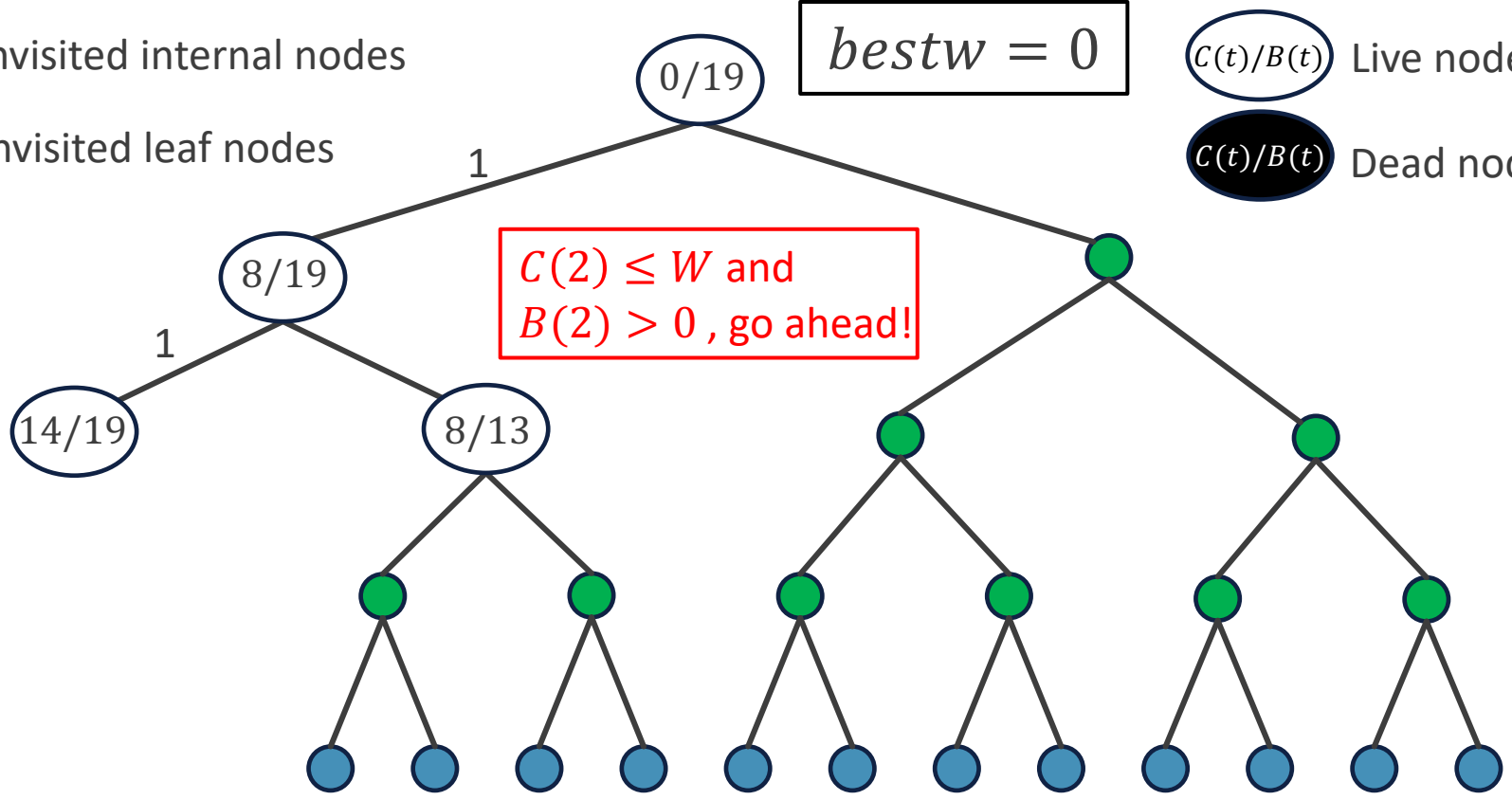
● Unvisited internal nodes

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$bestw = 0$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, w = [8,6,2,3], W = 12$

Example

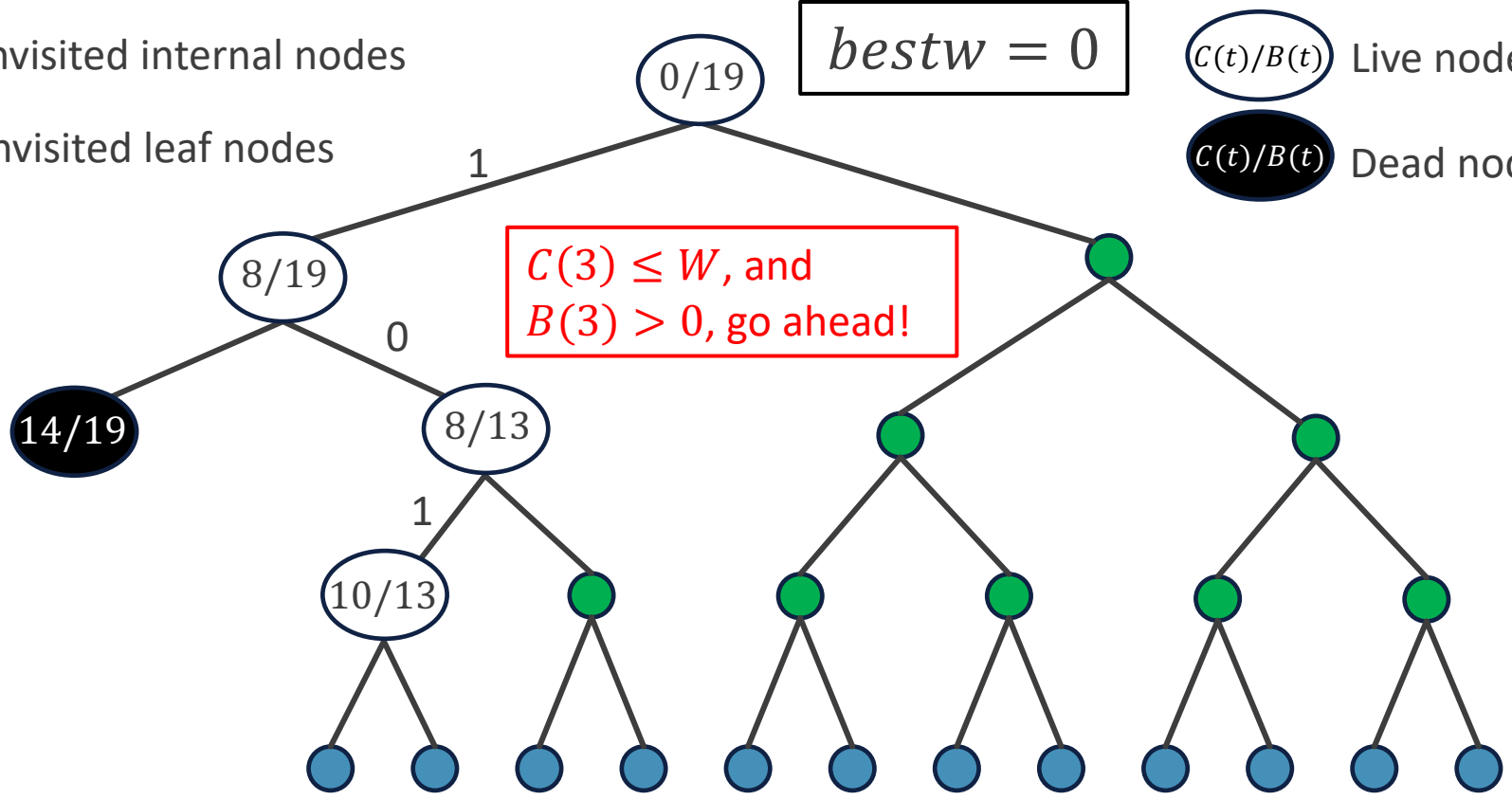
● Unvisited internal nodes

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$bestw = 0$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, w = [8,6,2,3], W = 12$

Example

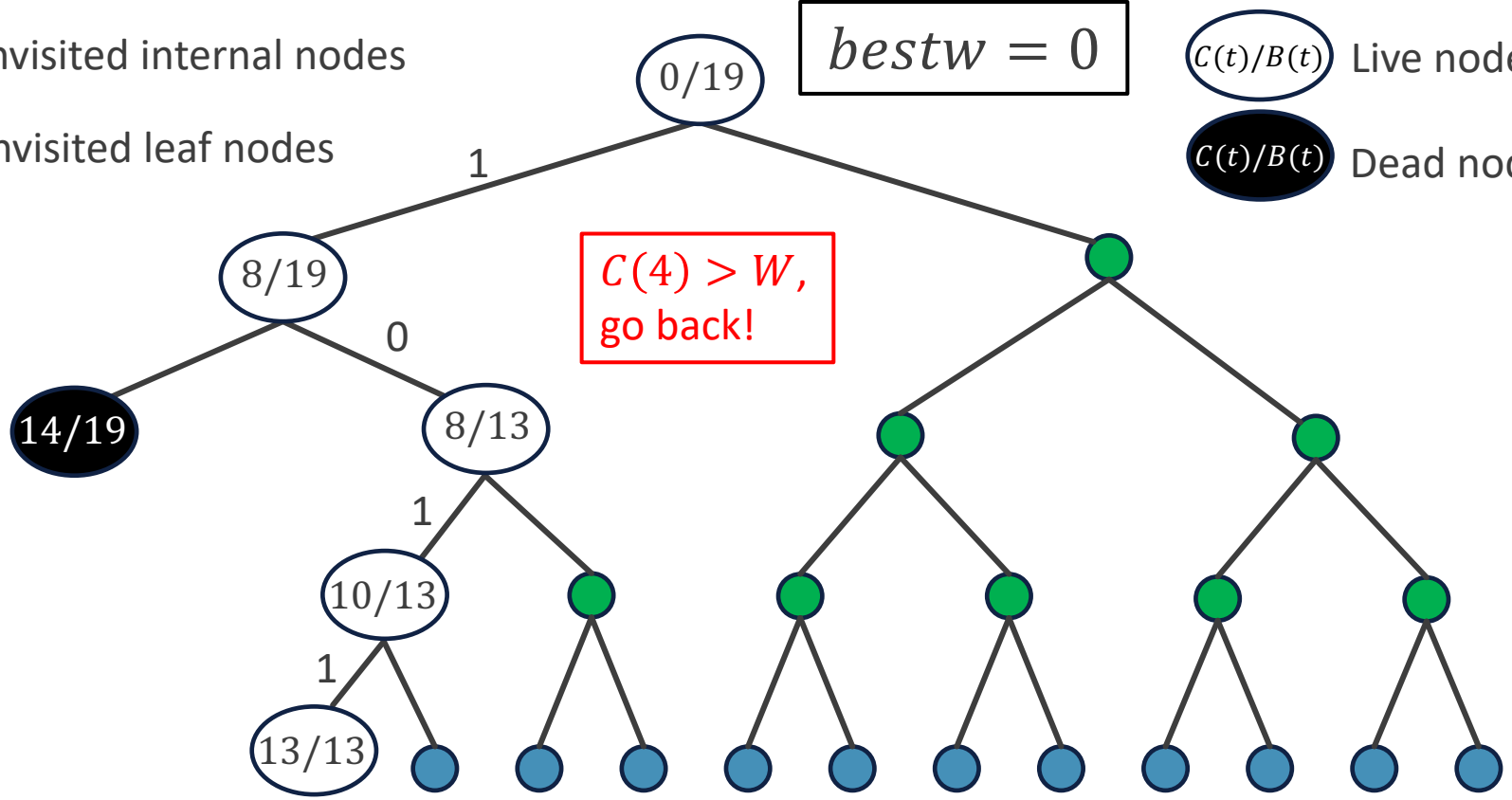
● Unvisited internal nodes

● Unvisited leaf nodes

$bestw = 0$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, w = [8, 6, 2, 3], W = 12$

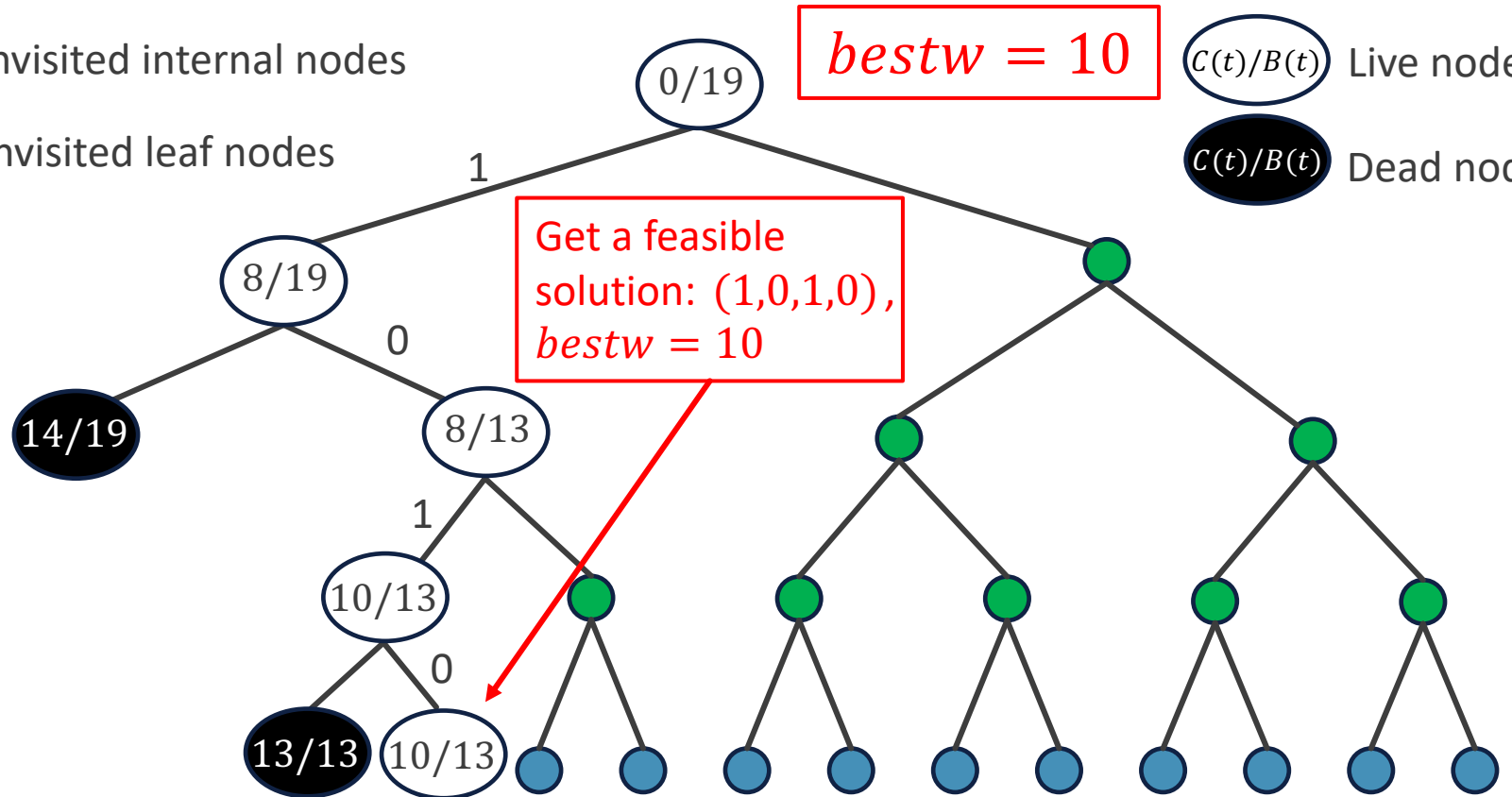
Example

● Unvisited internal nodes

● Unvisited leaf nodes

$C(t)/B(t)$ Live nodes

$C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, w = [8,6,2,3], W = 12$



Example

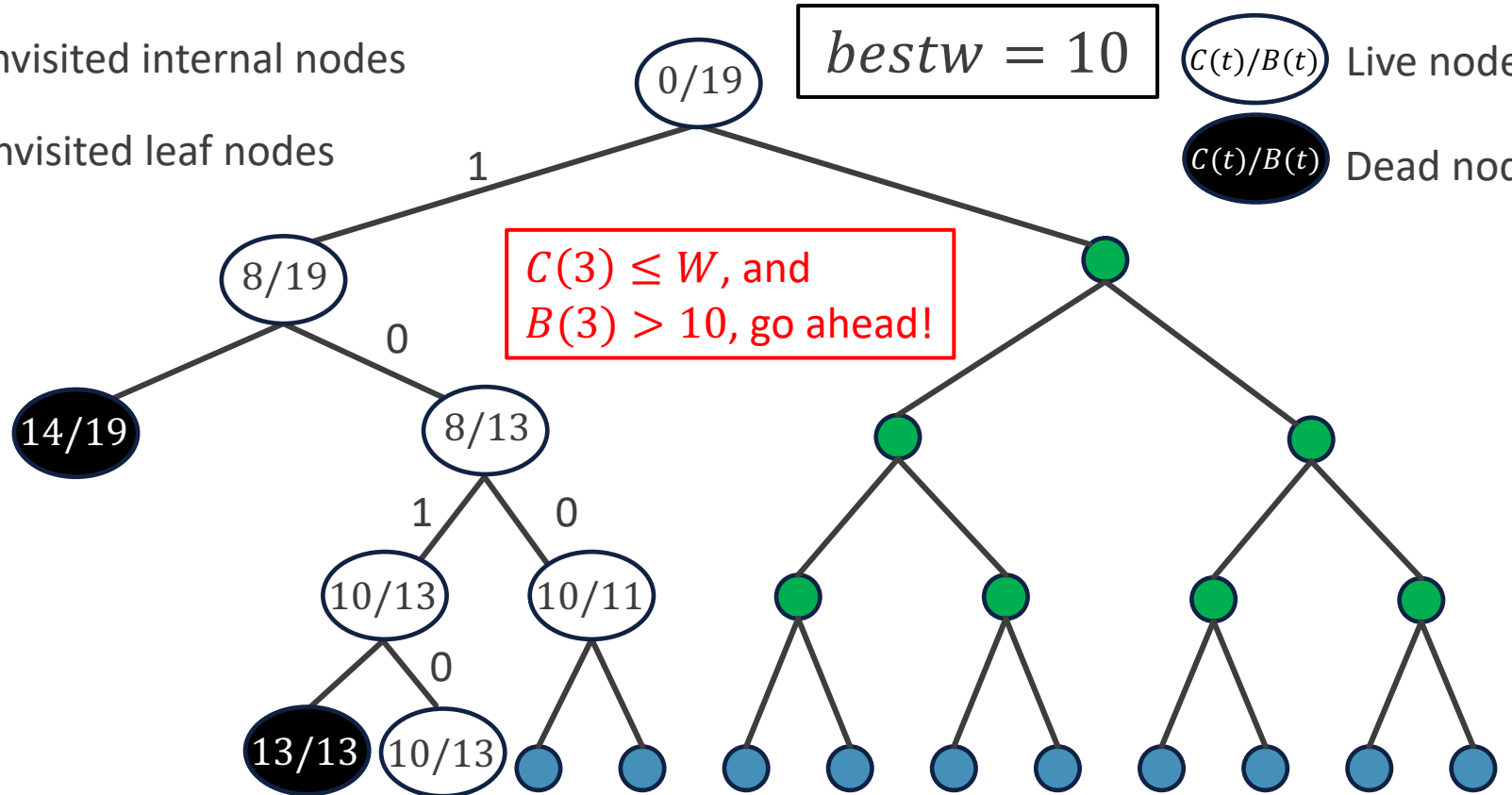
● Unvisited internal nodes

● Unvisited leaf nodes

$bestw = 10$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4$, $w = [8,6,2,3]$, $W = 12$

Example

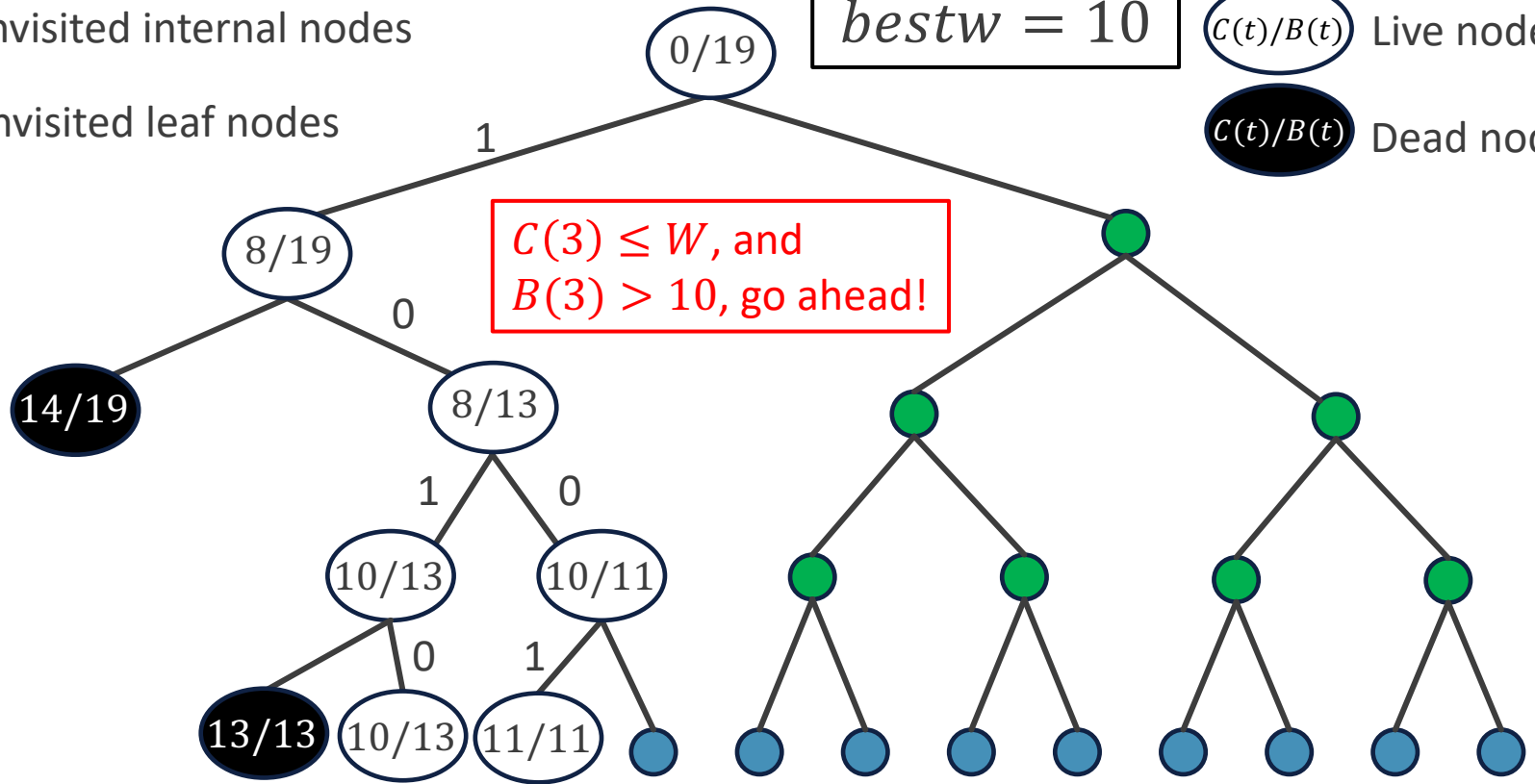
● Unvisited internal nodes

● Unvisited leaf nodes

$bestw = 10$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



$C(3) \leq W$, and
 $B(3) > 10$, go ahead!

Backtracking for $n = 4, w = [8,6,2,3], W = 12$

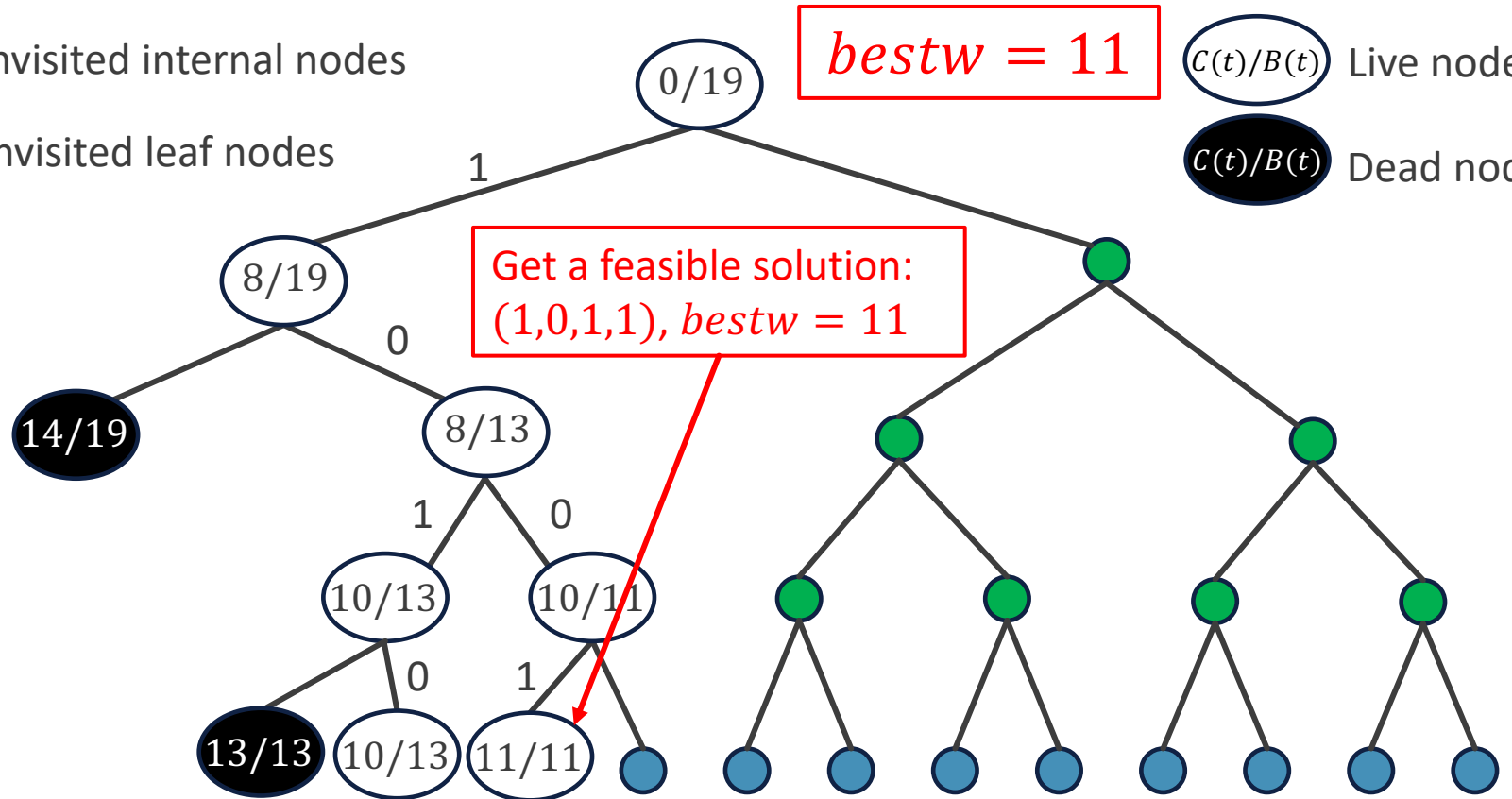
Example

● Unvisited internal nodes

● Unvisited leaf nodes

$C(t)/B(t)$ Live nodes

$C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, w = [8,6,2,3], W = 12$



Example

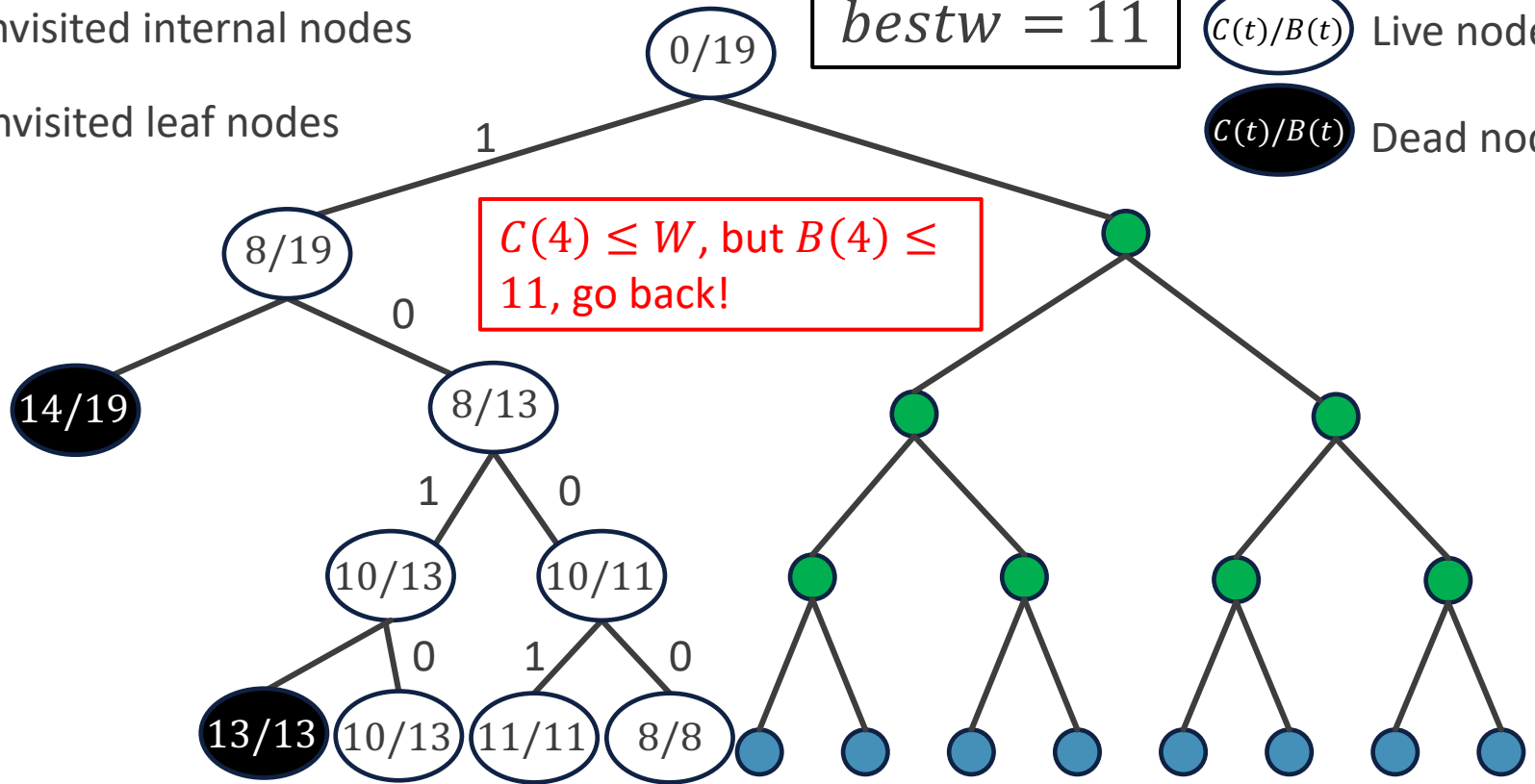
● Unvisited internal nodes

● Unvisited leaf nodes

$bestw = 11$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, w = [8,6,2,3], W = 12$

Example

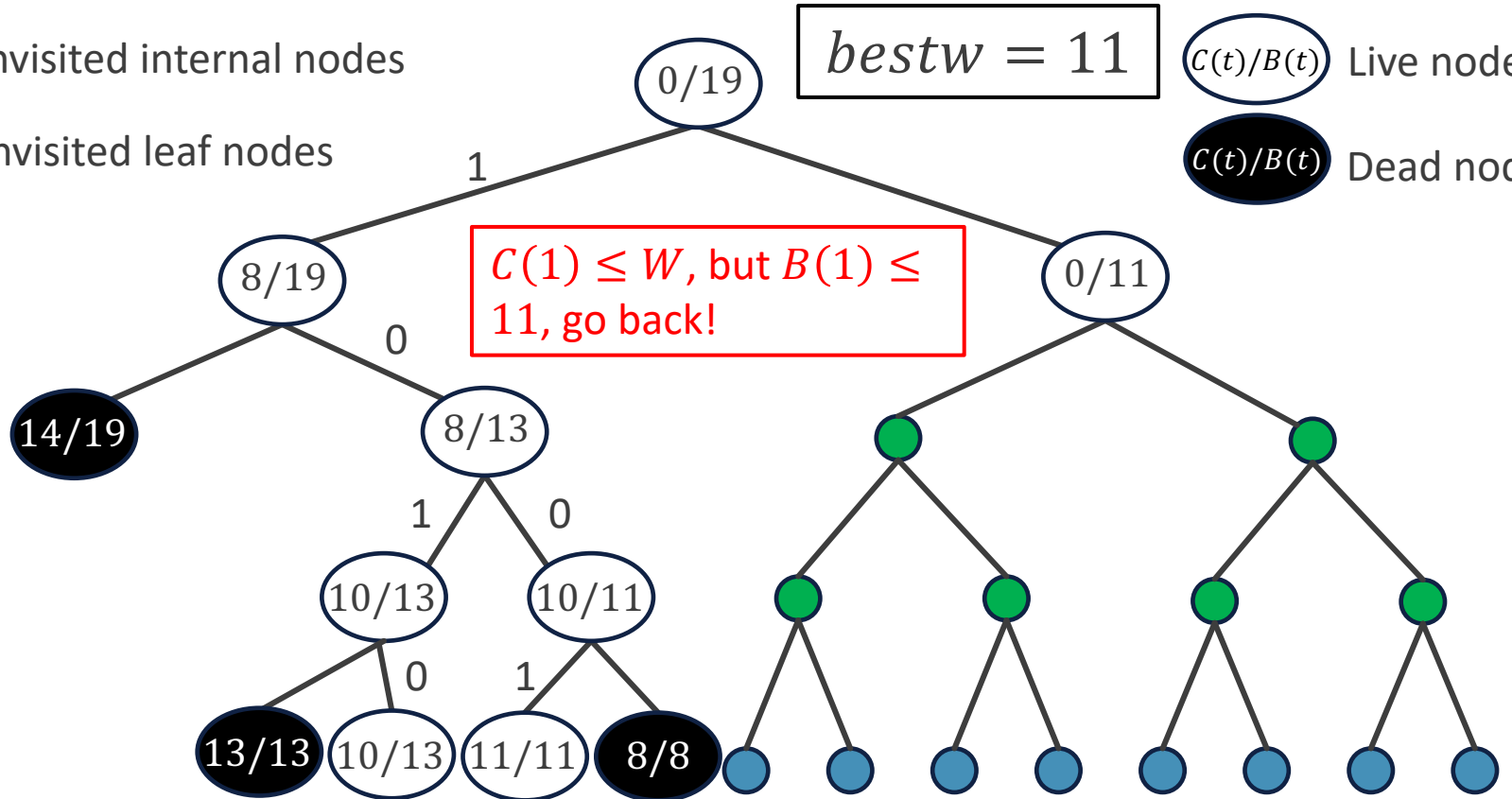
● Unvisited internal nodes

● Unvisited leaf nodes

$bestw = 11$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, w = [8,6,2,3], W = 12$



Example

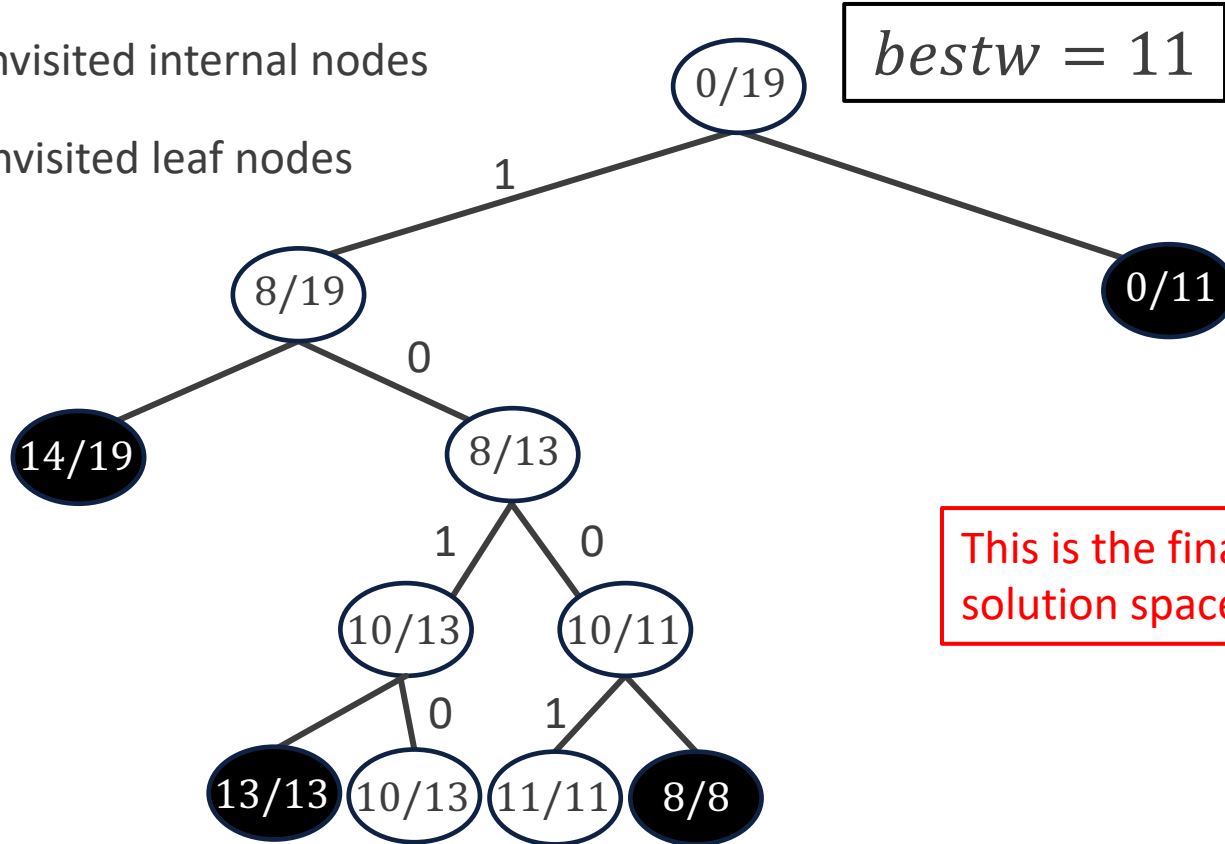
● Unvisited internal nodes

● Unvisited leaf nodes

$bestw = 11$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



This is the final pruned solution space tree.

Backtracking for $n = 4, w = [8,6,2,3], W = 12$

Pseudocode

ImprovedBacktrackLoading(*i*)

```
1  if  $i > n$  then
2    if  $cw > bestw$  then
3       $bestw \leftarrow cw$ 
4      for  $j \leftarrow 1$  to  $n$  do
5         $bestx[j] \leftarrow x[j]$ 
6  else
7     $r \leftarrow r - w[i]$ 
8    if  $C(i) \leq W$  then
9       $x[i] \leftarrow 1$ 
10      $cw \leftarrow cw + w[i]$ 
11     ImprovedBacktrackLoading( $i + 1$ )
12      $cw \leftarrow cw - w[i]$ 
13     if  $B(i) > bestw$  then
14        $x[i] \leftarrow 0$ 
15     ImprovedBacktrackLoading( $i + 1$ )
16    $r \leftarrow r + w[i]$ 
```

Record the best solution

Record the current solution

r is initialized as the total weight sum and reduced at the beginning of each recursive call. After each recursive call, we add the weight back for going back.



Time Complexity

- Although backtracking seems very efficient. The time complexity for this algorithm is $O(n2^n)$.
 - 2^n is the time for searching the solution space.
 - n is the time to store the best solution.
- This is a sad story...



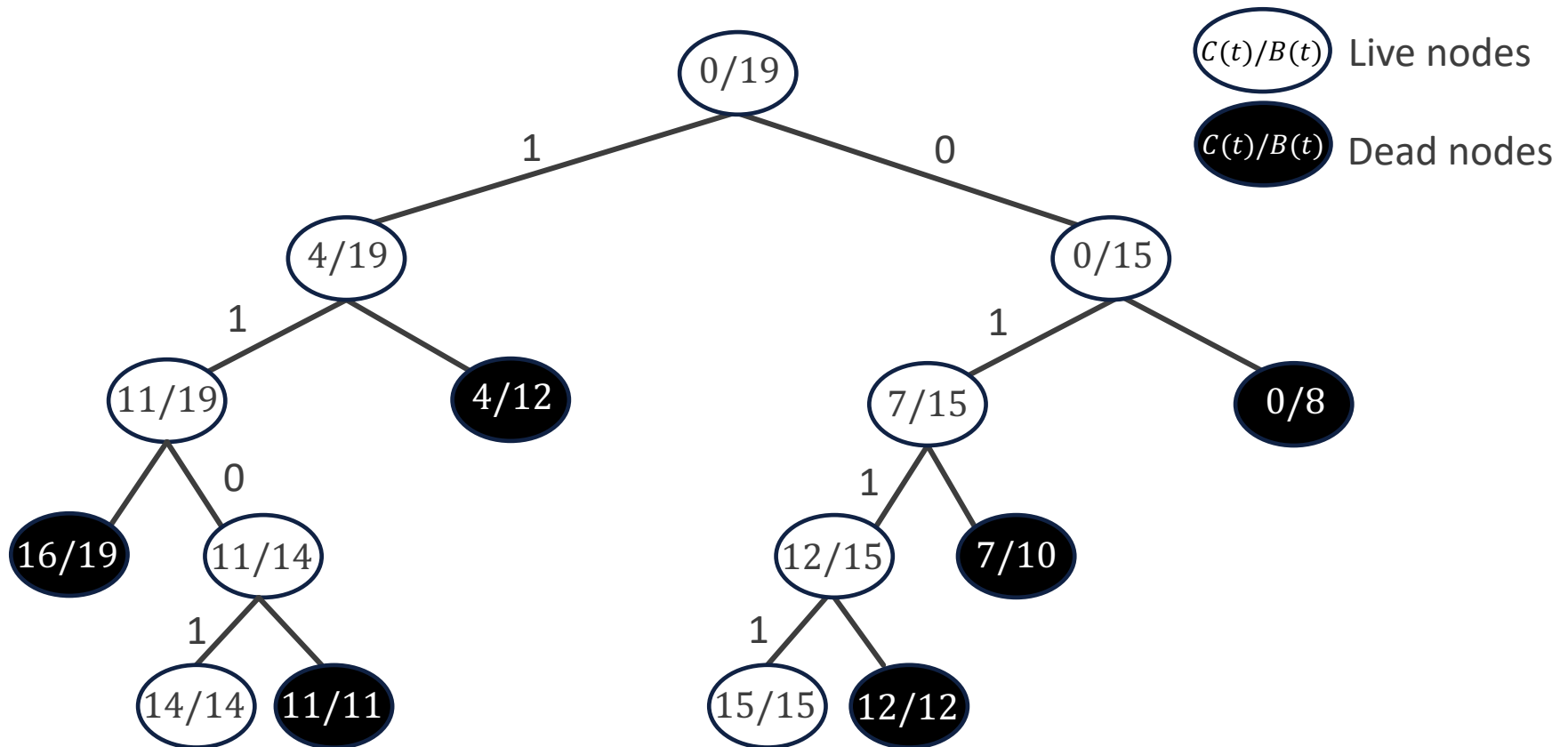
Classroom Exercise

- Draw the pruned solution space tree for the following container loading problem instance.

$$n = 4, w = [4,7,5,3], W = 15$$



Classroom Exercise



Backtracking for $n = 4, w = [4, 7, 5, 3], W = 15$



Classroom Exercise

- In the Sum-of-Subsets problem, there are n positive integers (weights) w_i and a positive integer W .
- The goal is to find all subsets of the integers that sum to W .
- Example:
 - Suppose that $n = 4$, $W = 13$, and $w = [3,4,5,6]$.
 - The solutions is $[1,1,0,1]$ because $w_1 + w_2 + w_4 = 3 + 4 + 6 = 13$,
- Design the constraint function and bounding function, and the corresponding condition.
- Draw the pruned solution space tree of the above example.



Classroom Exercise

- The constraint function $C(i)$ and its condition are same as the container loading problem:

$$C(i) > W$$

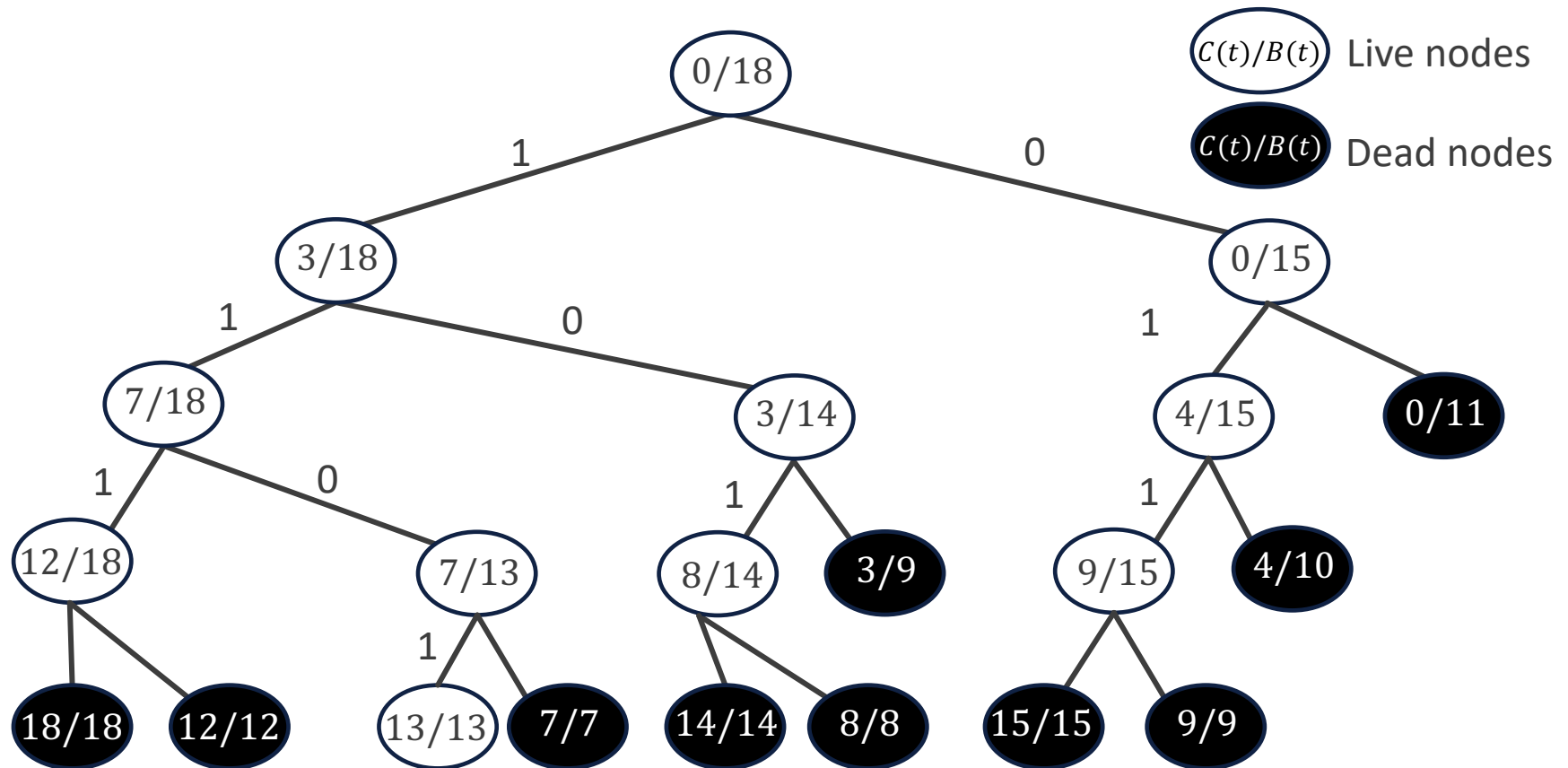
- The bounding function $B(i)$ is same as the container loading problem, but the condition is different:

$$B(i) < W$$

- Instead of comparing with $bestw$ in the container loading problem.



Classroom Exercise



Backtracking for $n = 4$, $w = [3,4,5,6]$, $W = 13$





0/1 KNAPSACK PROBLEM

0/1 Knapsack Problem

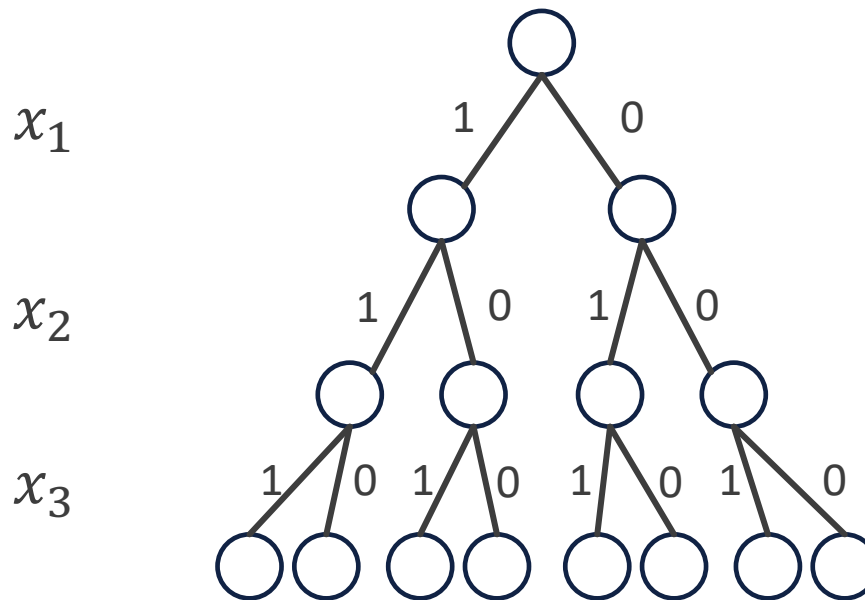
- There are n items: the i th item is worth v_i dollars and weights w_i kg. The capacity of knapsack is W kg.
- Assuming that the solutions are represented by vectors (x_1, x_2, \dots, x_n) , where $x_i \in \{0,1\}$. 1 denotes taking item i and 0 denotes not taking item i .
- The 0/1 knapsack problem can be formally stated as follows:

$$\max \sum_{i=1}^n v_i x_i \quad \text{s. t.} \quad \sum_{i=1}^n w_i x_i \leq W$$



0/1 Knapsack Problem

- It is nothing but a high-level container loading problem.
- The size of solution space and the solution space tree are exactly same as the container loading problem.



Solution space tree with $n = 3$



0/1 Knapsack Problem

- Constraint function: also exactly same as the container loading problem!
- Let $cw(i)$ denote the current weight up to level i , namely

$$cw(i) = \sum_{j=1}^i w_j x_j$$

then the constraint function is

$$C(i) = cw(i - 1) + w_i$$

- The pruning condition is $C(i) > W$, which means there is no capacity to take container i .



0/1 Knapsack Problem

- The bounding function:

$$B(i) = C(i) + r(i)$$

However, different from the bounding function in the container loading problem, $r(i)$ denotes the **value sum** of the remaining items, namely,

$$r(i) = \sum_{j=i+1}^n v_j$$

- The pruning condition is $B(i) \leq \mathit{bestv}$, which means the continuing searching along this branch will not give better solution.



Example

● Unvisited internal nodes

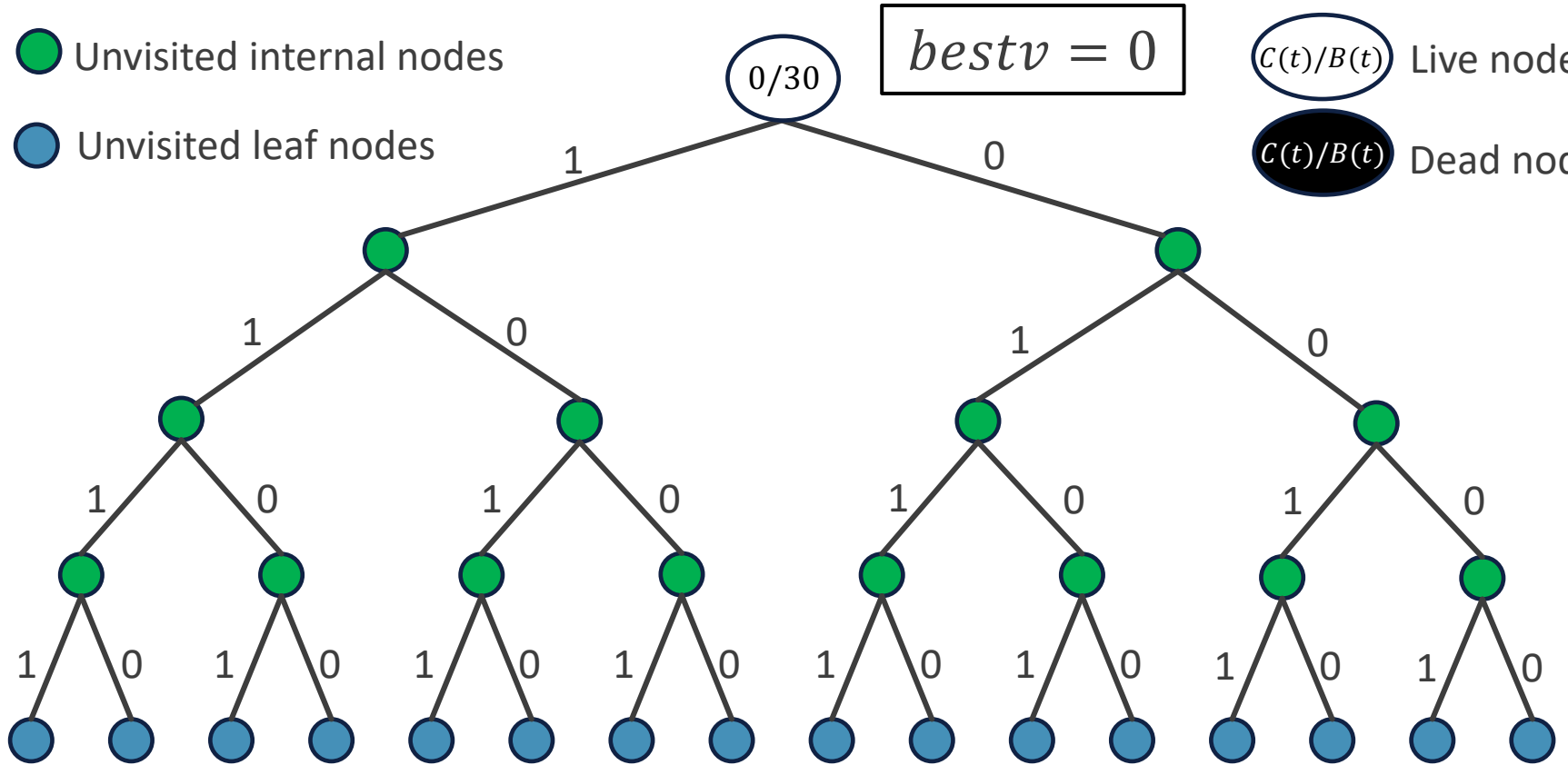
● Unvisited leaf nodes

0/30

$bestv = 0$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4$, $v = [4,7,9,10]$, $w = [1,2,3,5]$, $W = 7$



Example

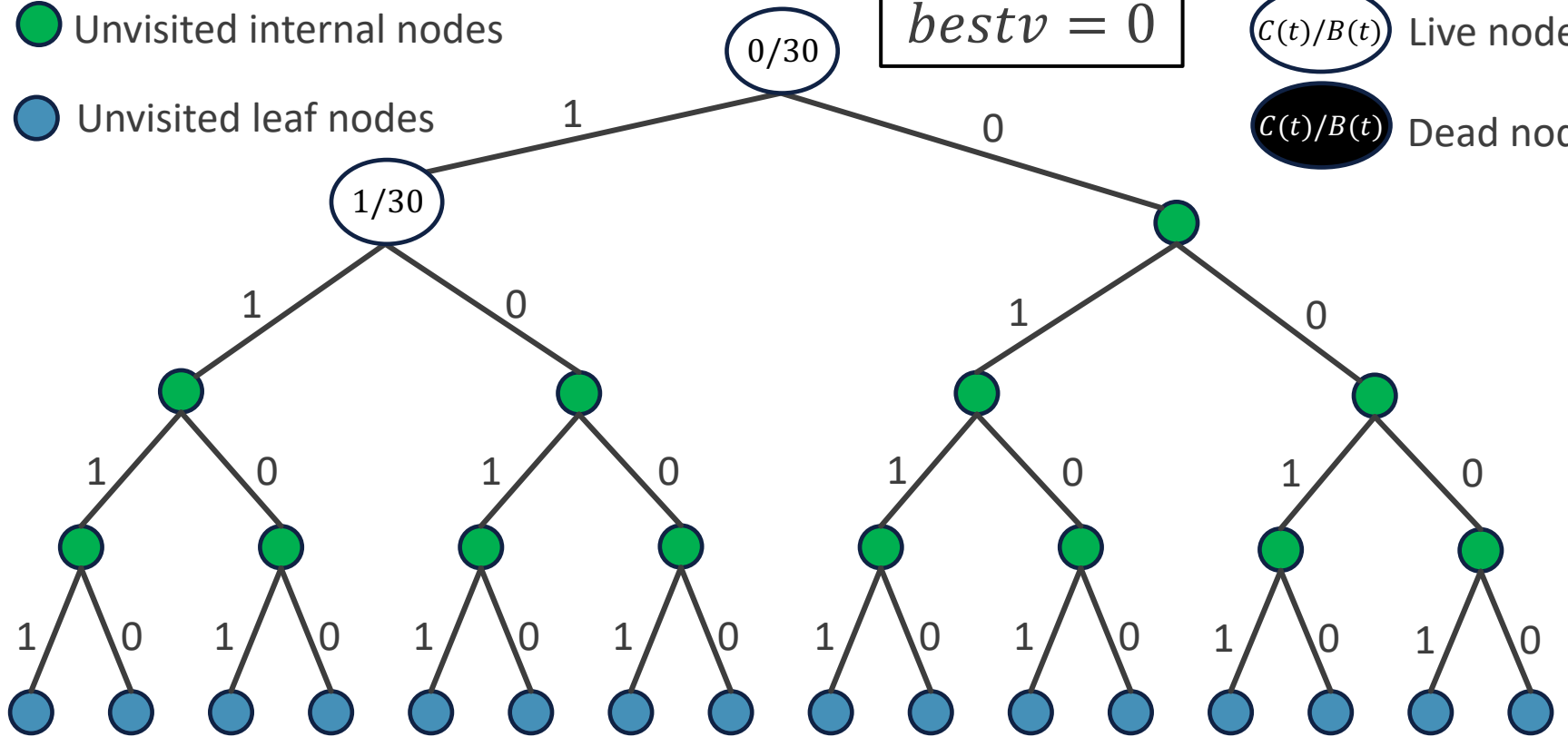
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 0$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4$, $v = [4,7,9,10]$, $w = [1,2,3,5]$, $W = 7$



Example

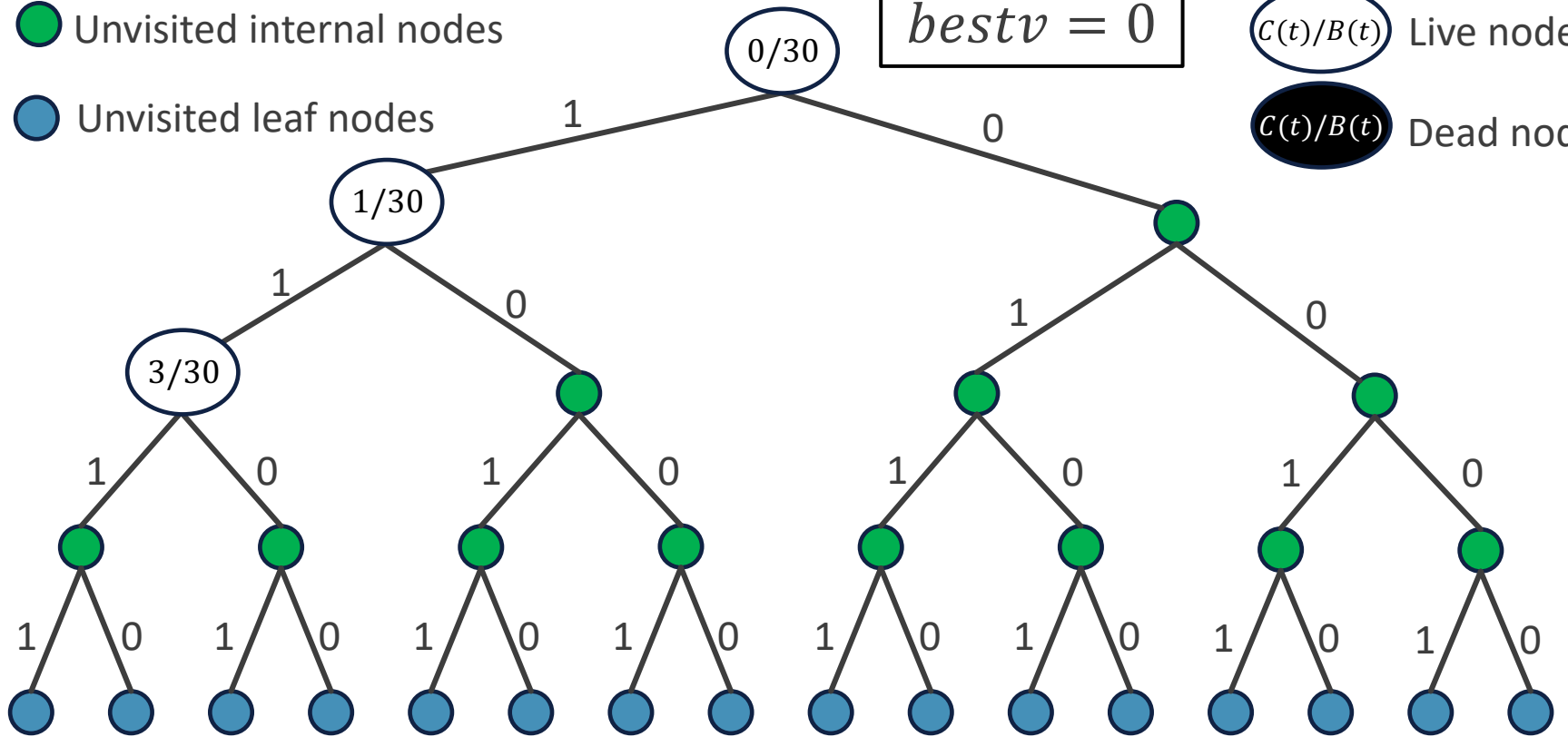
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 0$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4$, $v = [4,7,9,10]$, $w = [1,2,3,5]$, $W = 7$

Example

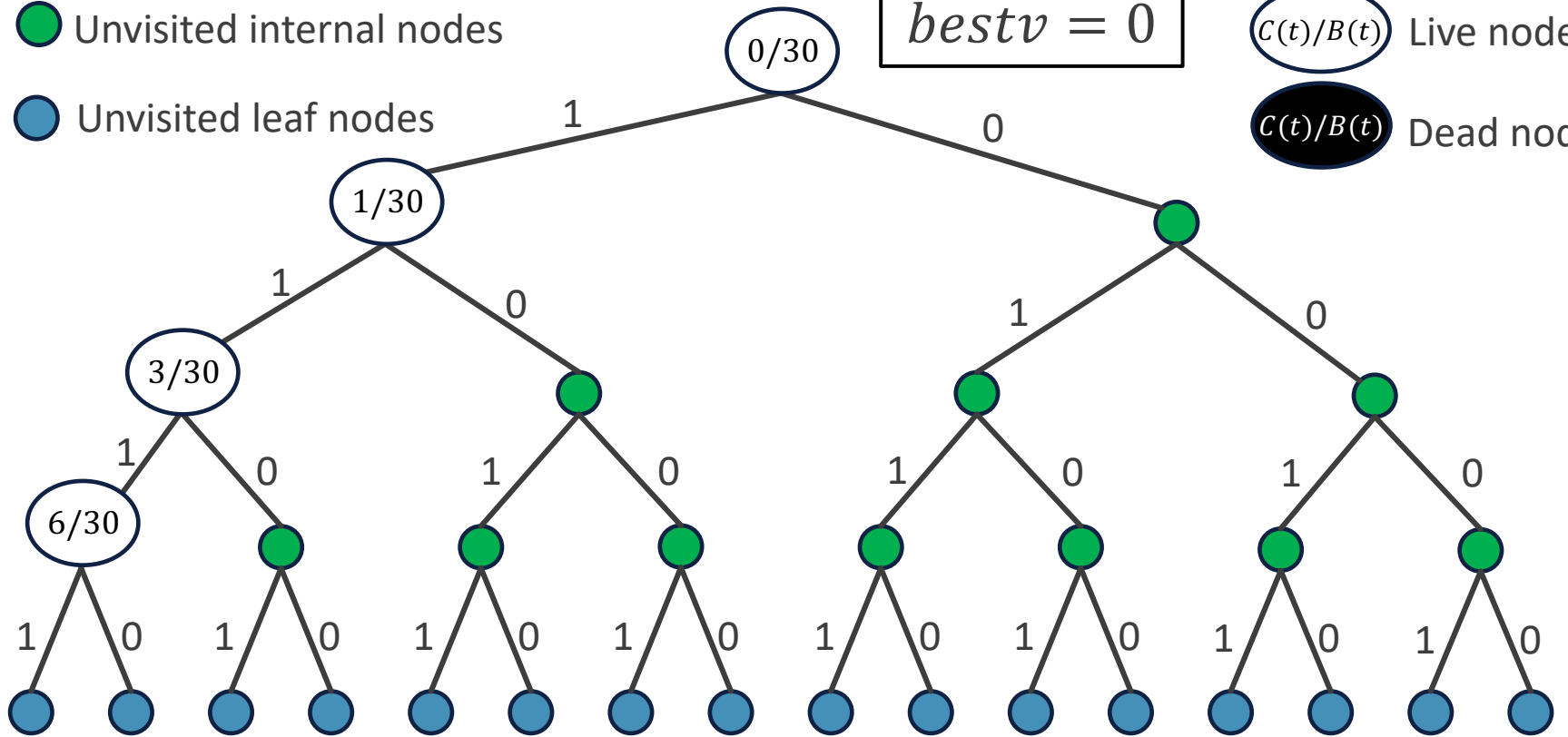
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 0$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4$, $v = [4,7,9,10]$, $w = [1,2,3,5]$, $W = 7$

Example

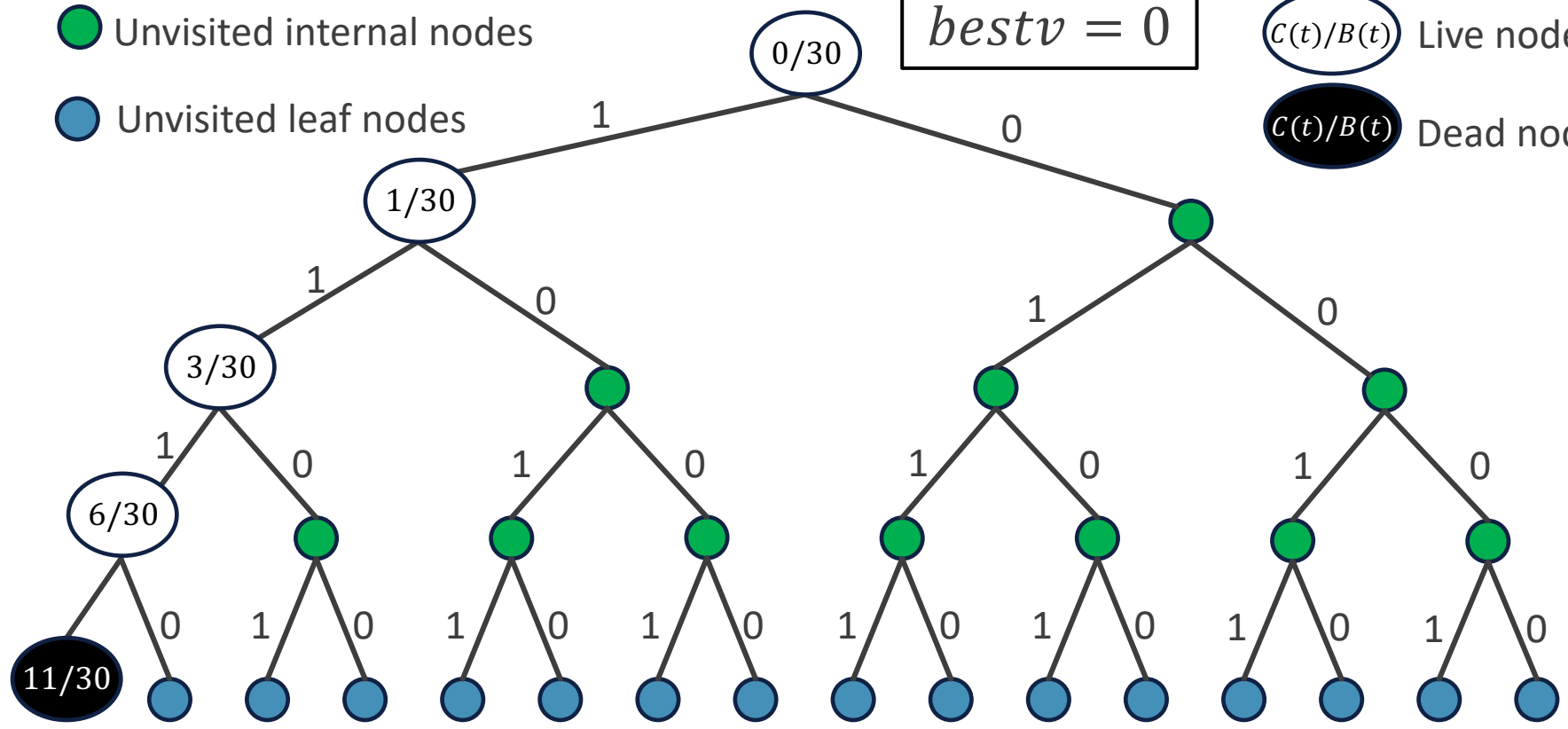
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 0$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, v = [4,7,9,10], w = [1,2,3,5], W = 7$

Example

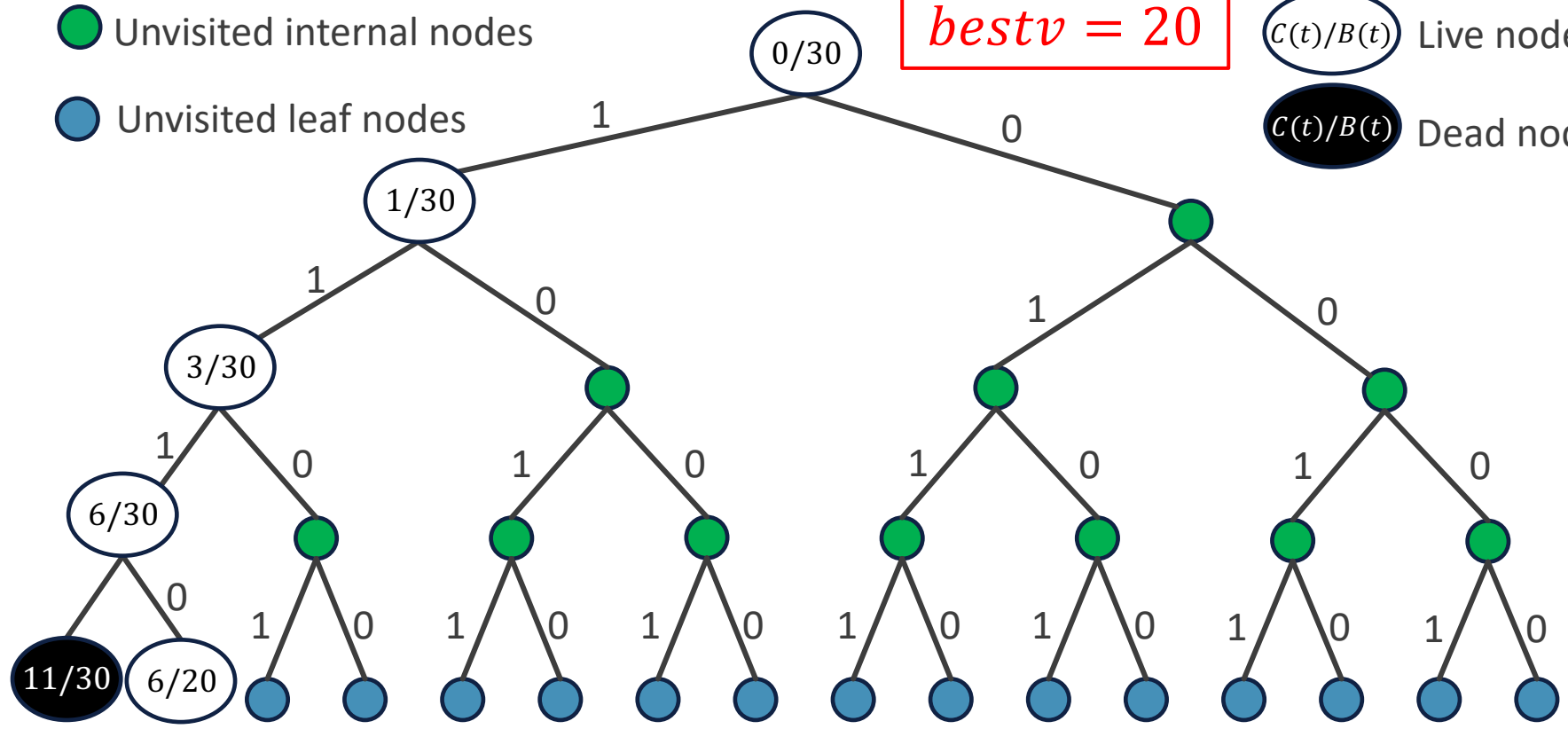
● Unvisited internal nodes

● Unvisited leaf nodes

bestv = 20

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, v = [4,7,9,10], w = [1,2,3,5], W = 7$

Example

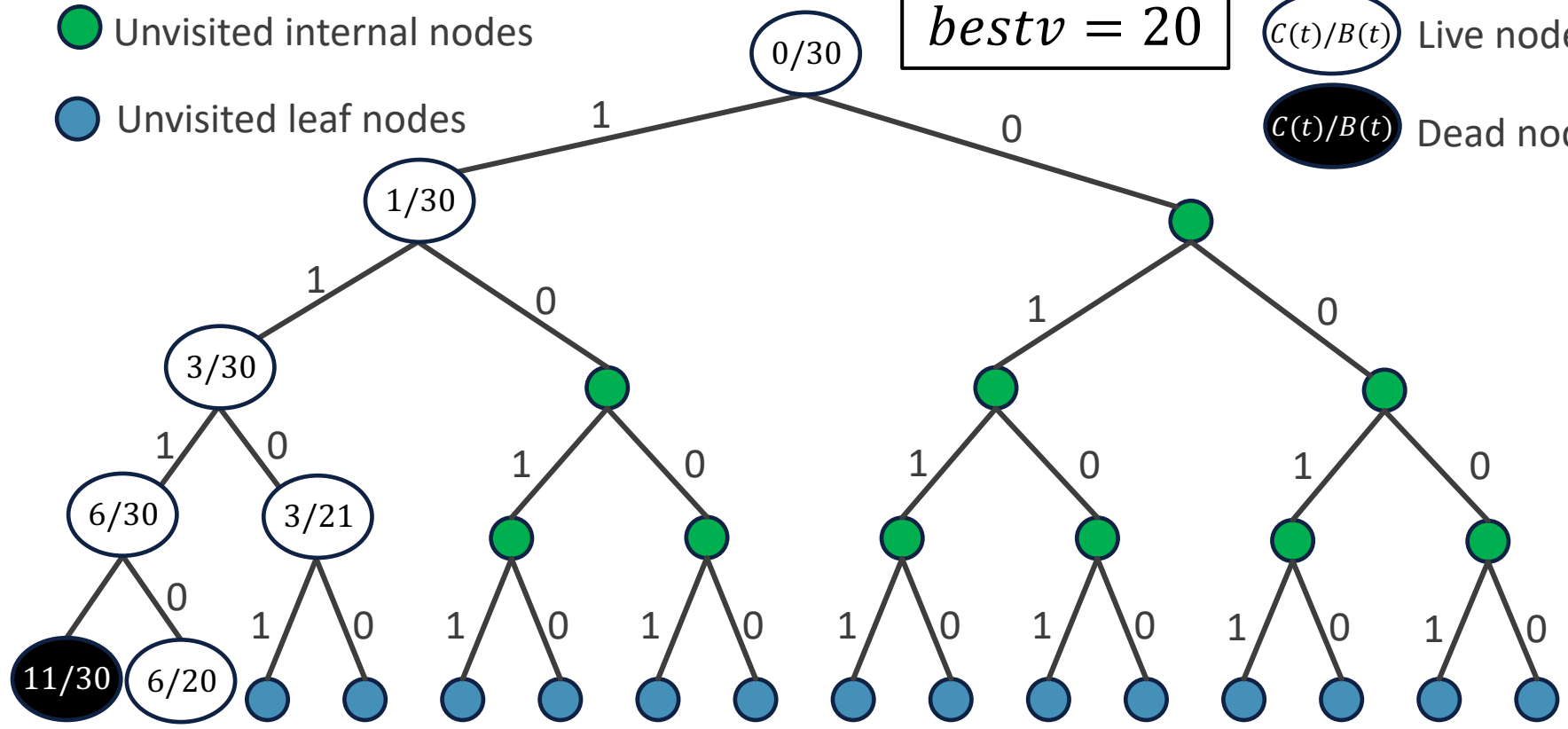
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 20$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, v = [4,7,9,10], w = [1,2,3,5], W = 7$

Example

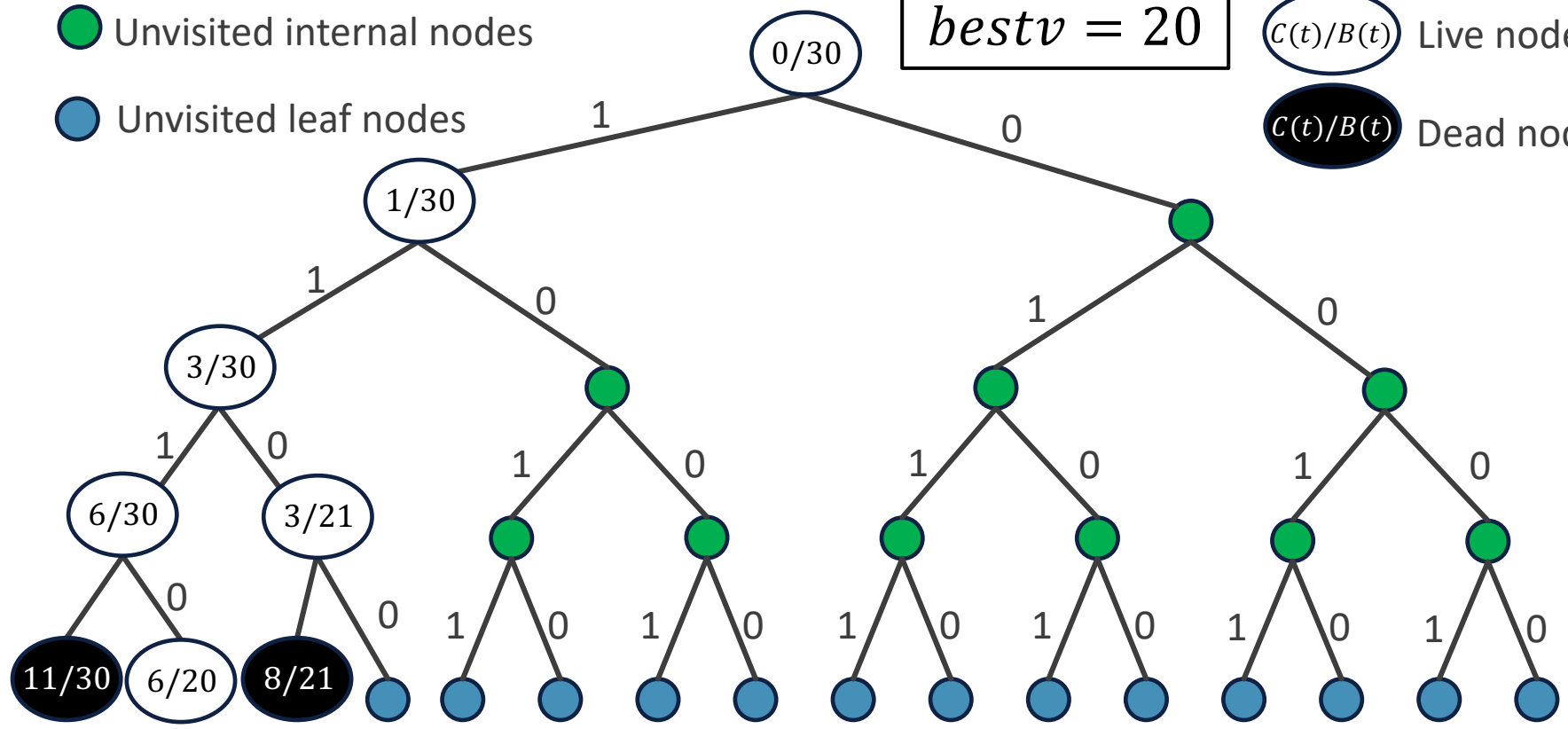
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 20$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, v = [4,7,9,10], w = [1,2,3,5], W = 7$

Example

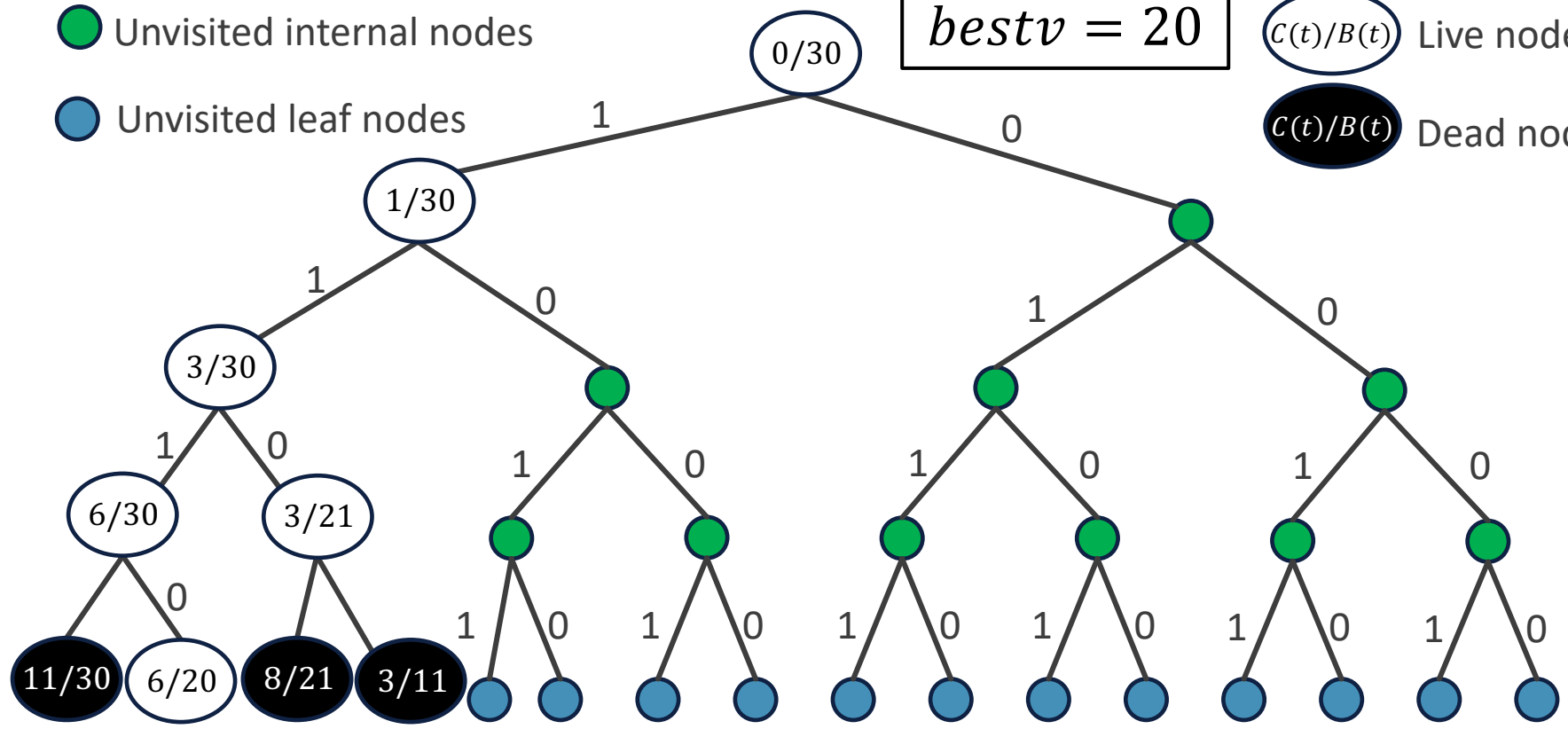
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 20$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, v = [4,7,9,10], w = [1,2,3,5], W = 7$

Example

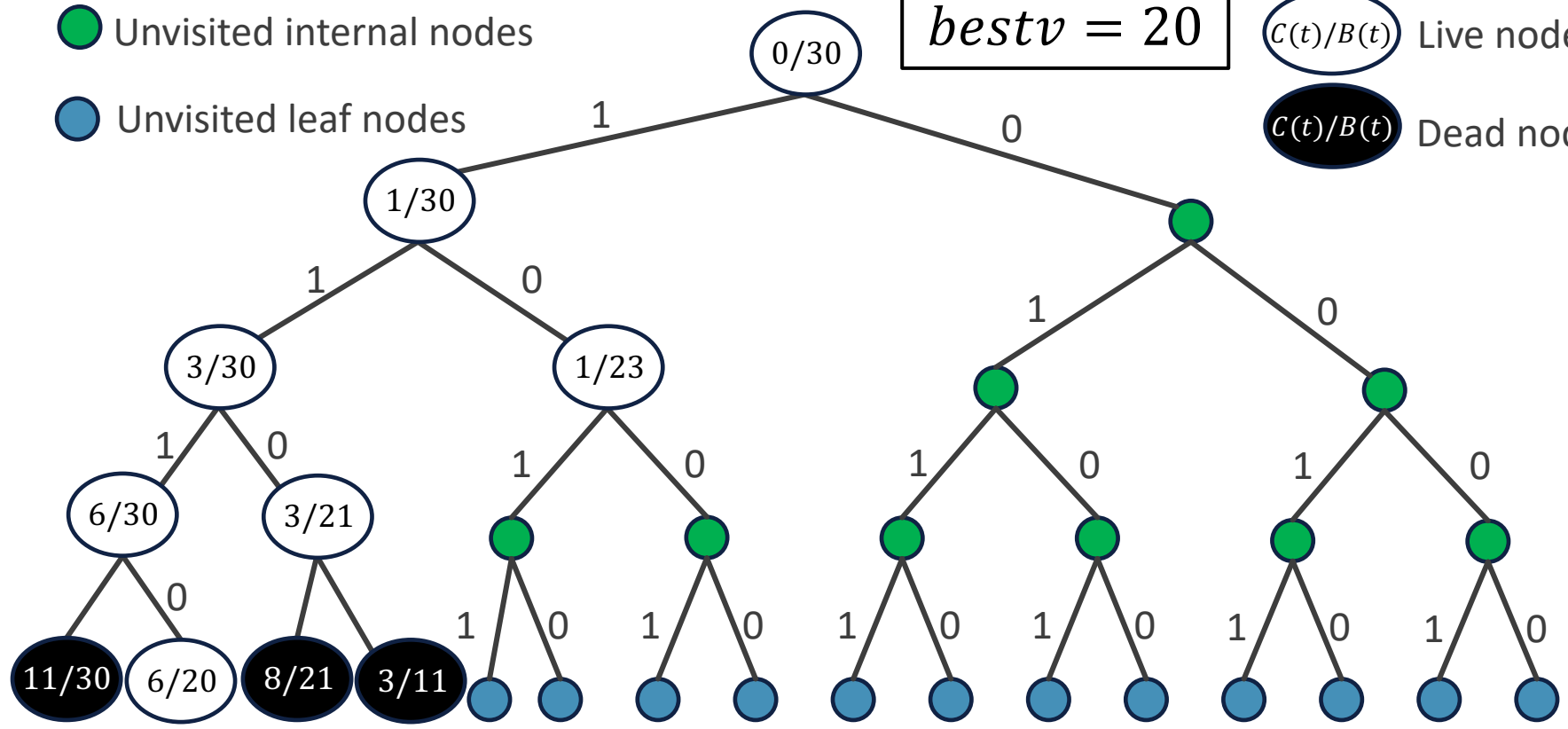
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 20$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, v = [4,7,9,10], w = [1,2,3,5], W = 7$

Example

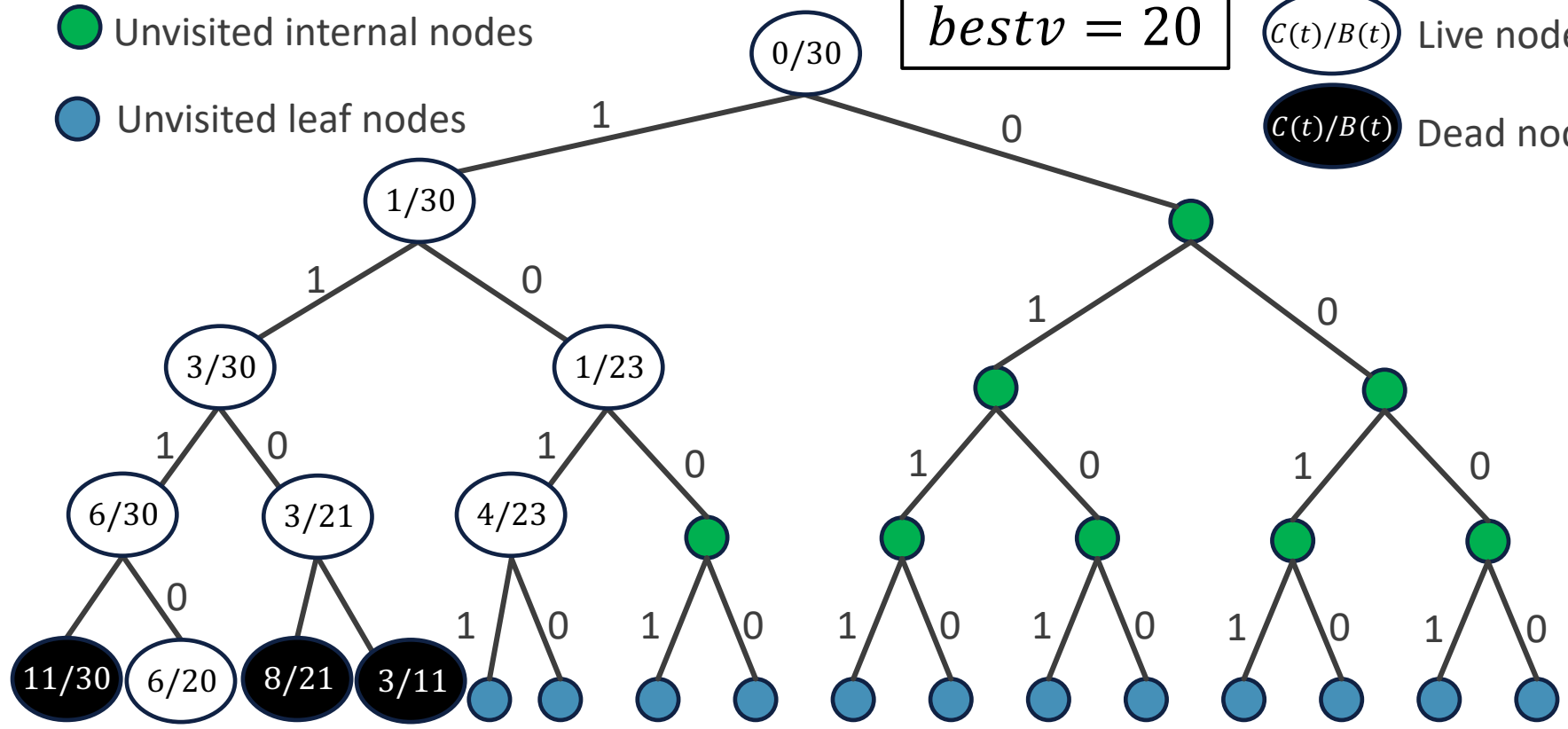
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 20$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, v = [4,7,9,10], w = [1,2,3,5], W = 7$

Example

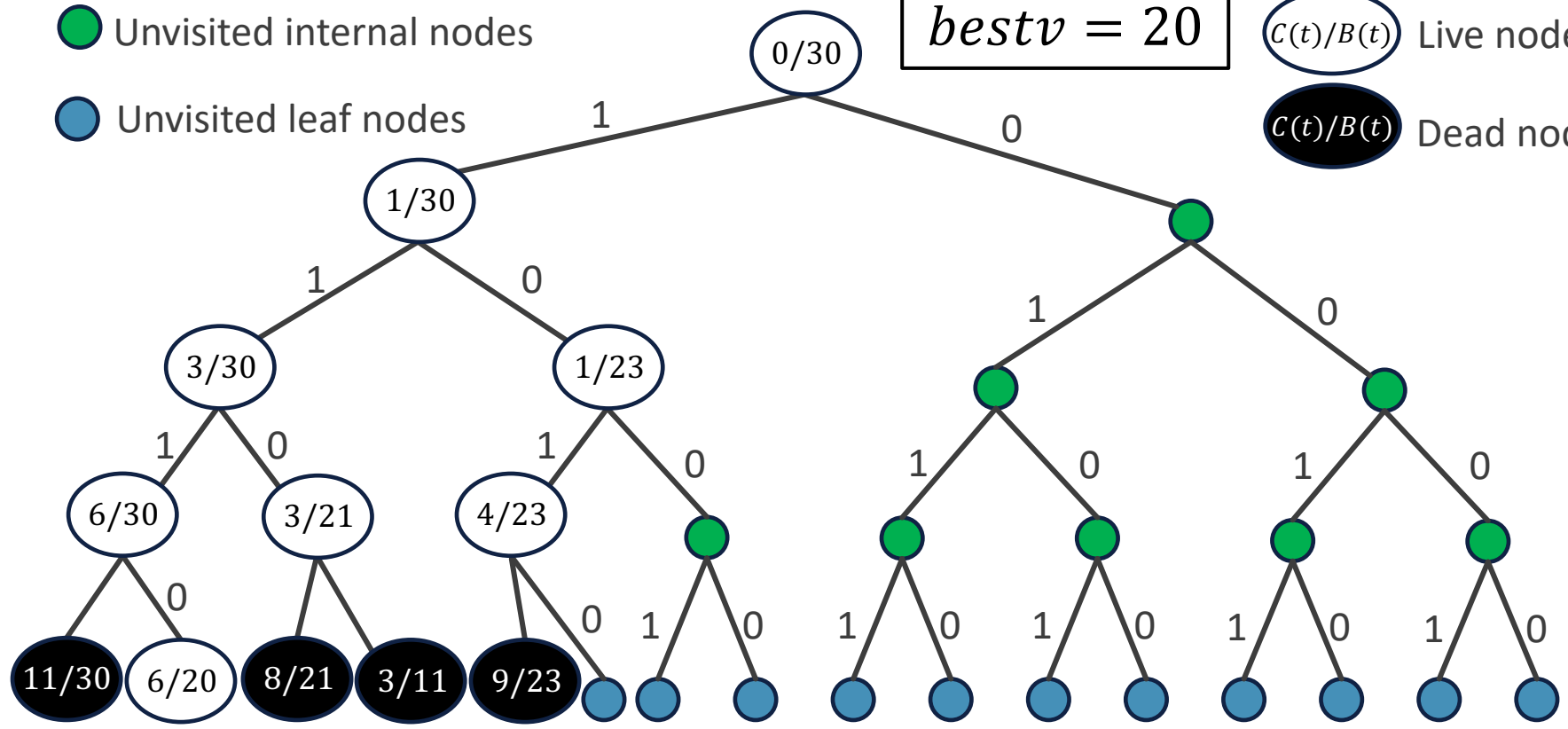
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 20$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, v = [4,7,9,10], w = [1,2,3,5], W = 7$

Example

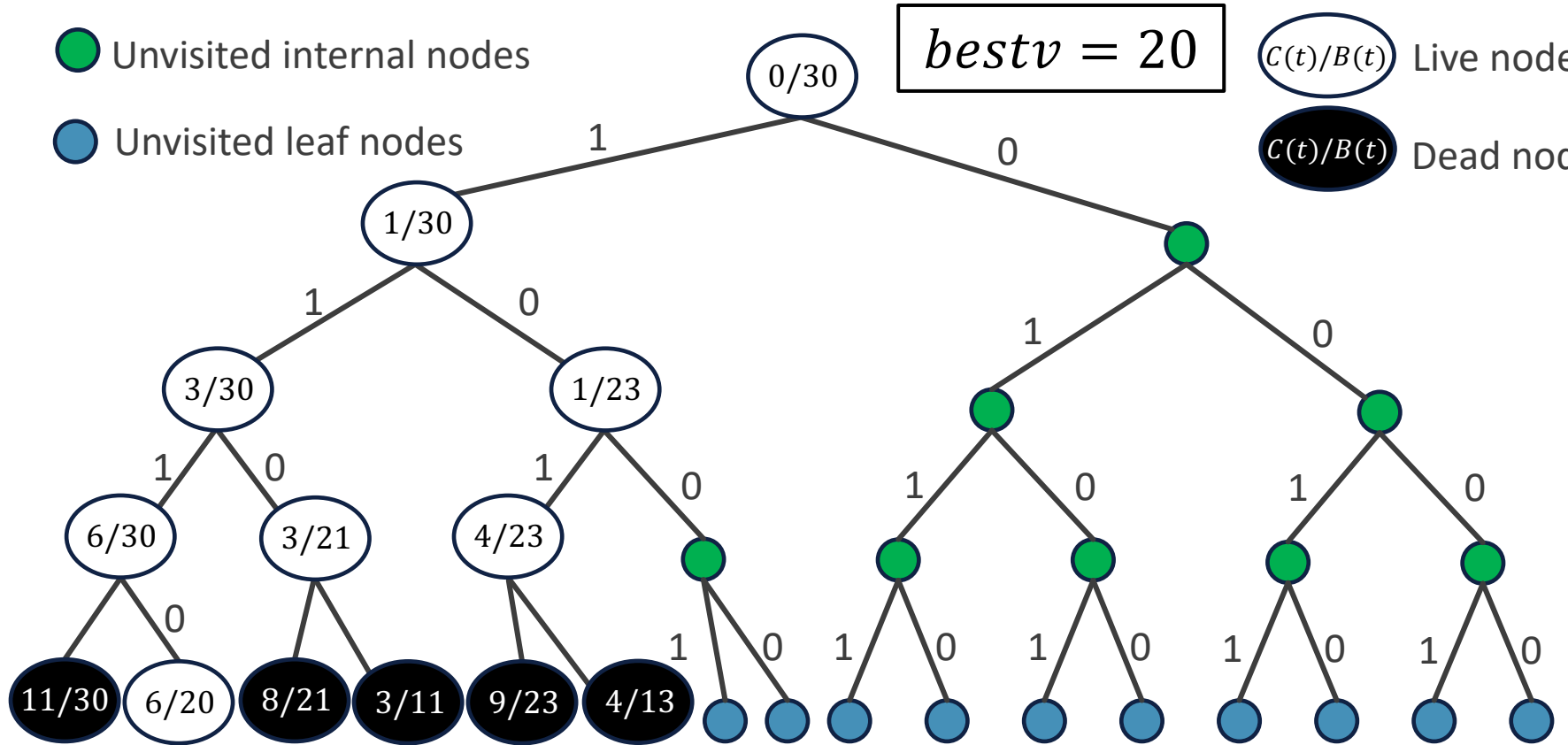
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 20$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, v = [4,7,9,10], w = [1,2,3,5], W = 7$



Example

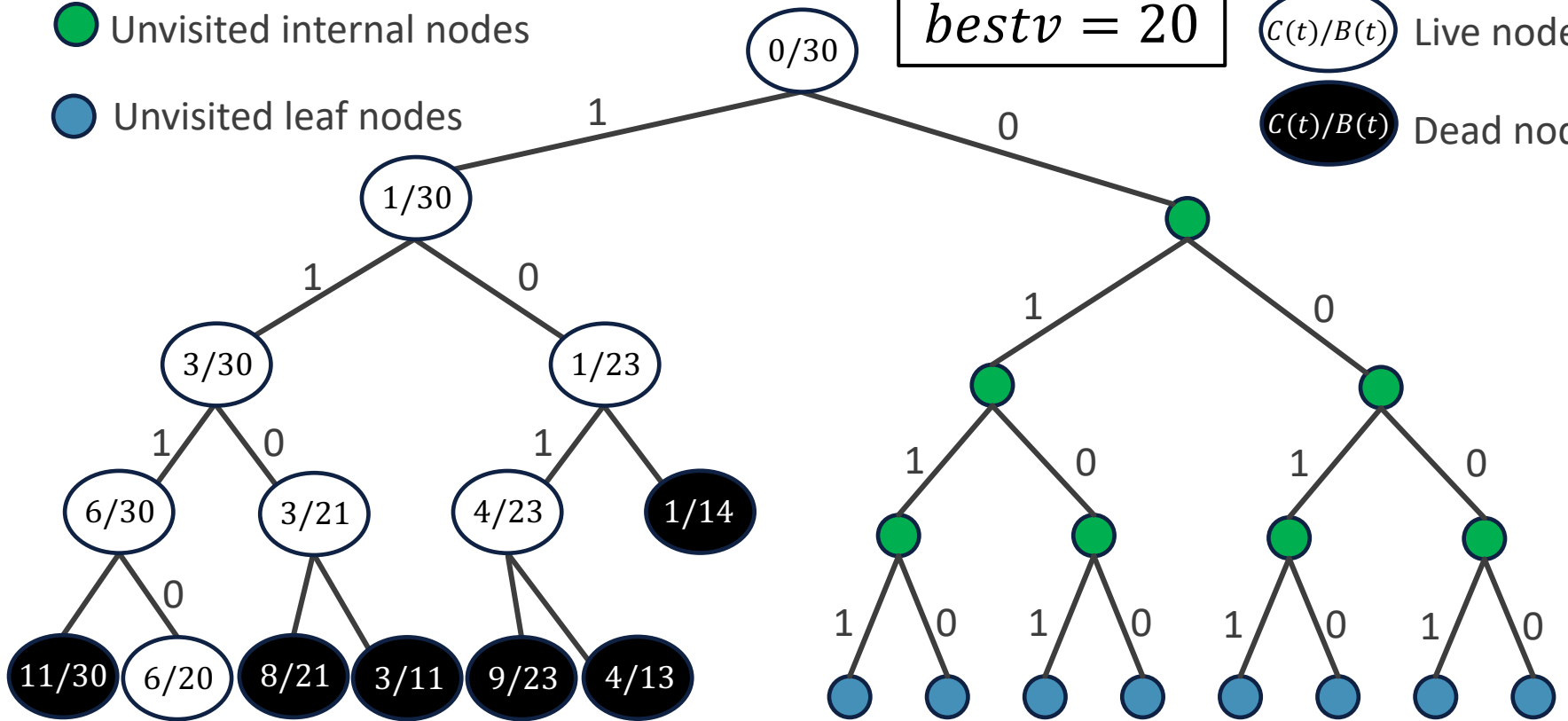
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 20$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4$, $v = [4, 7, 9, 10]$, $w = [1, 2, 3, 5]$, $W = 7$



Example

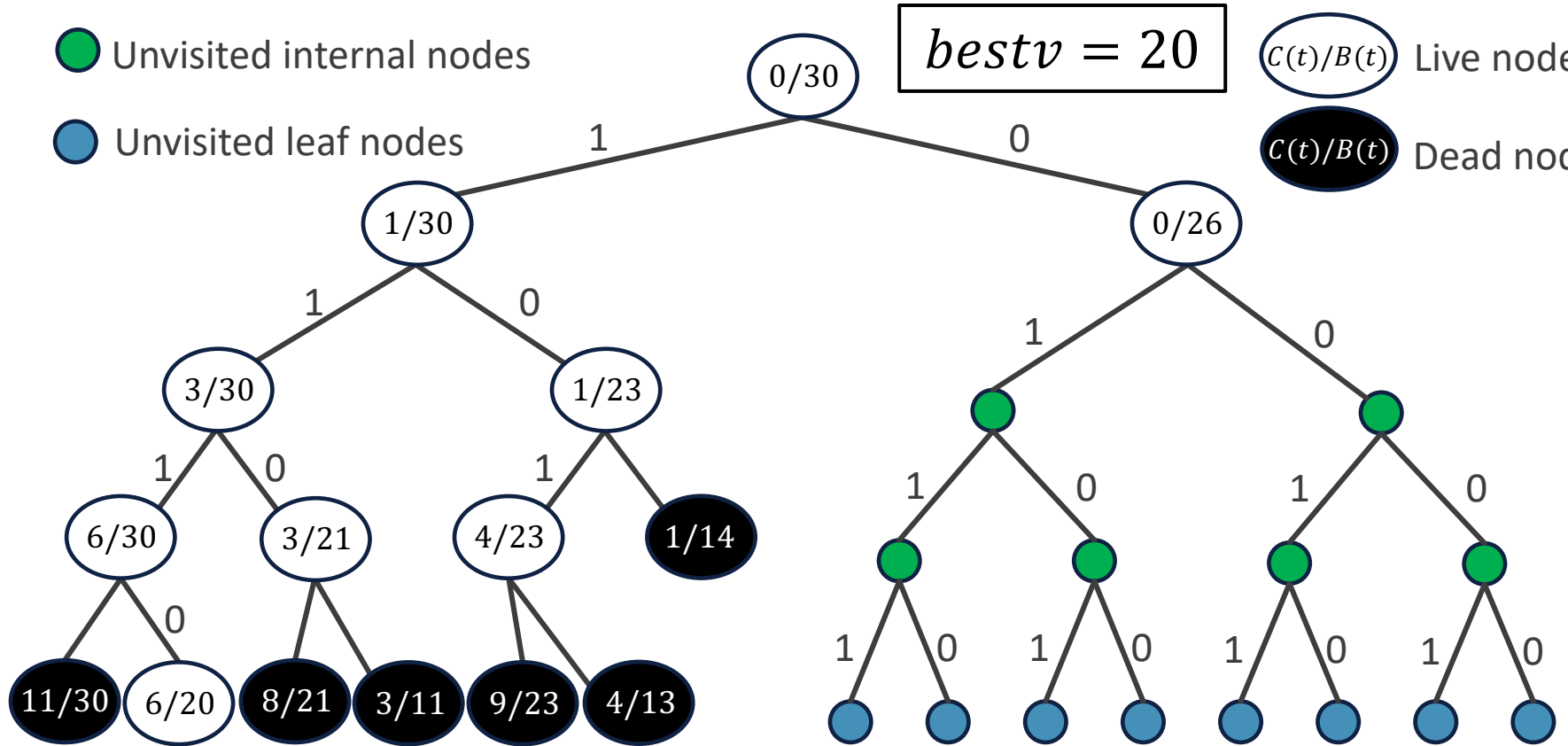
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 20$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4$, $v = [4, 7, 9, 10]$, $w = [1, 2, 3, 5]$, $W = 7$



Example

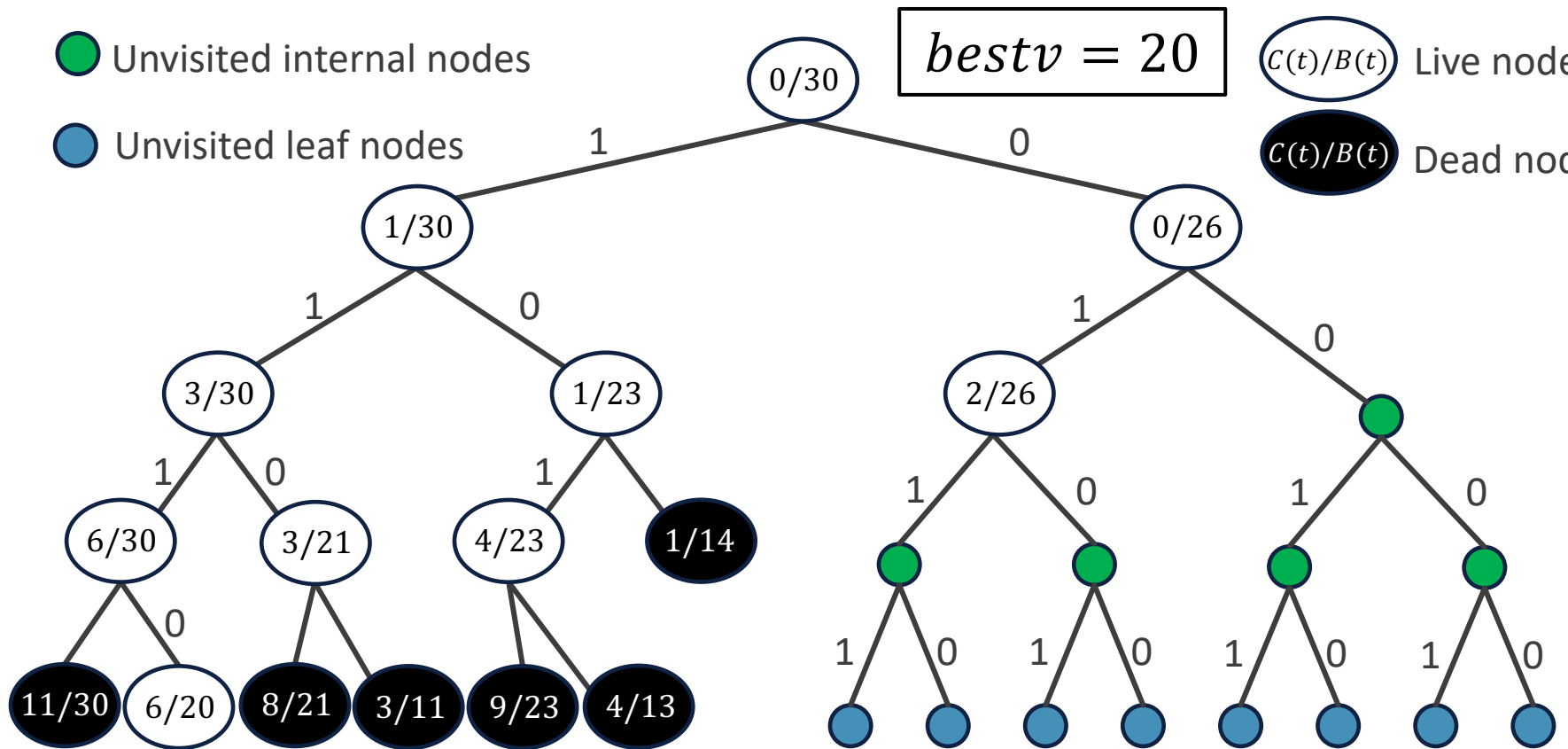
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 20$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4$, $v = [4, 7, 9, 10]$, $w = [1, 2, 3, 5]$, $W = 7$



Example

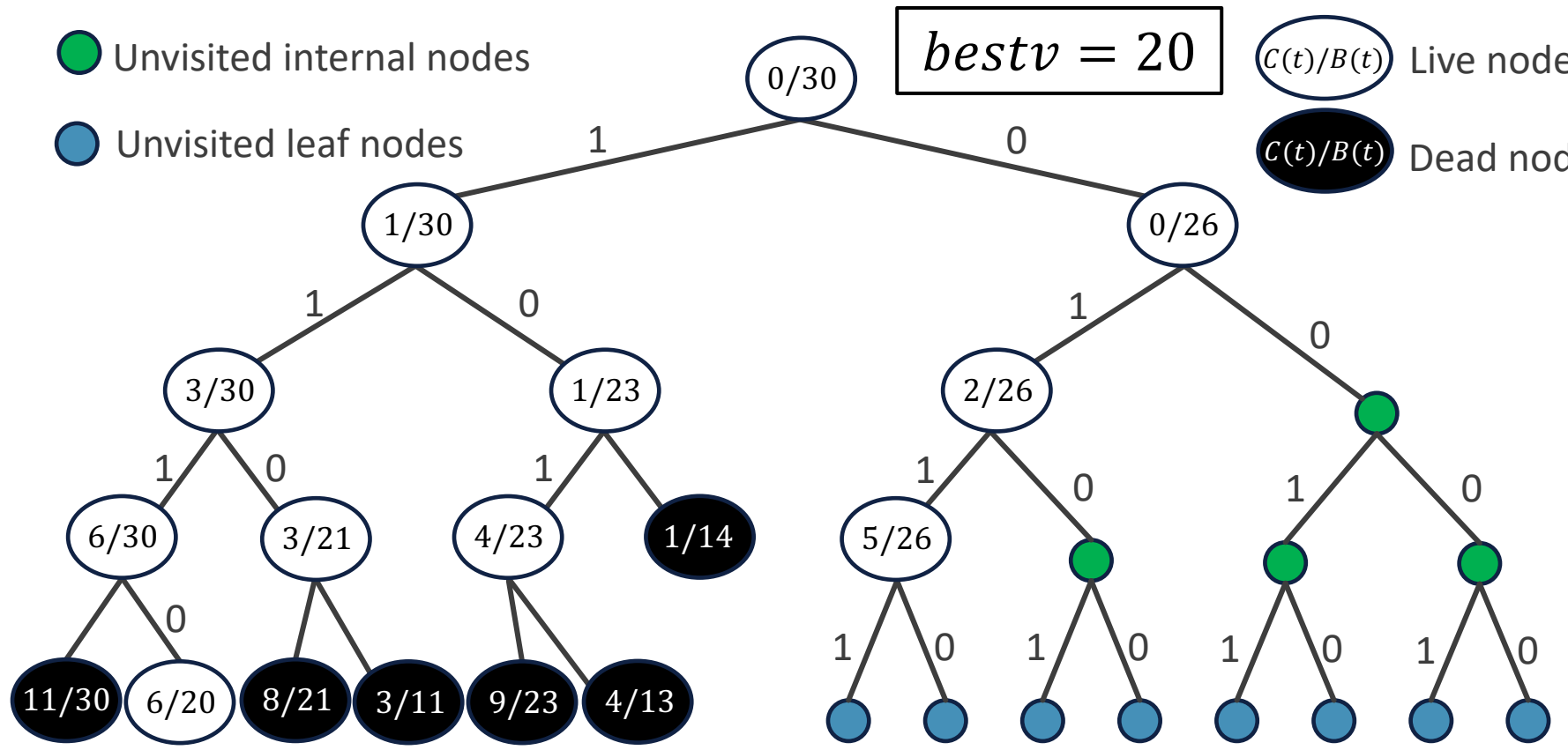
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 20$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, v = [4,7,9,10], w = [1,2,3,5], W = 7$

Example

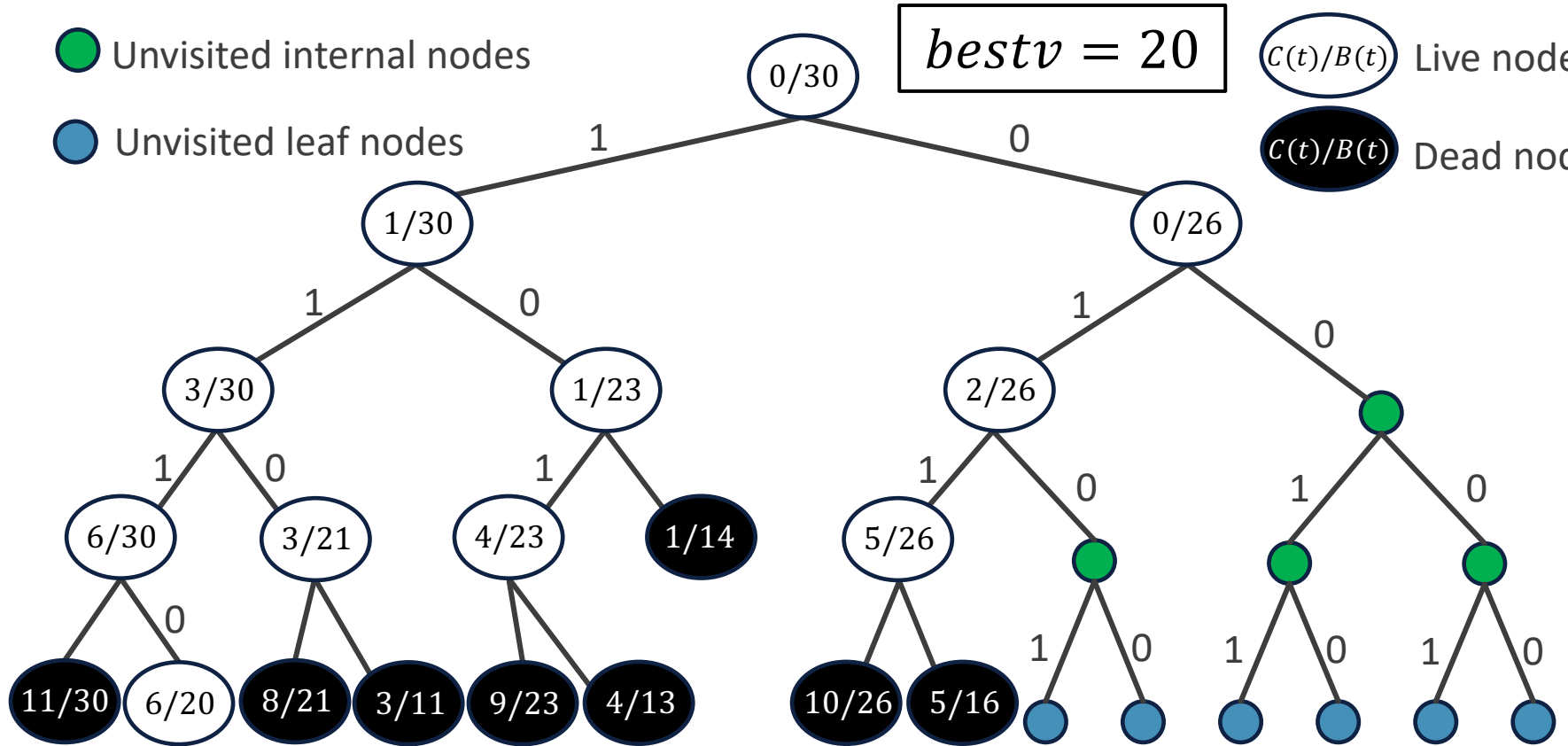
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 20$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4$, $v = [4,7,9,10]$, $w = [1,2,3,5]$, $W = 7$



Example

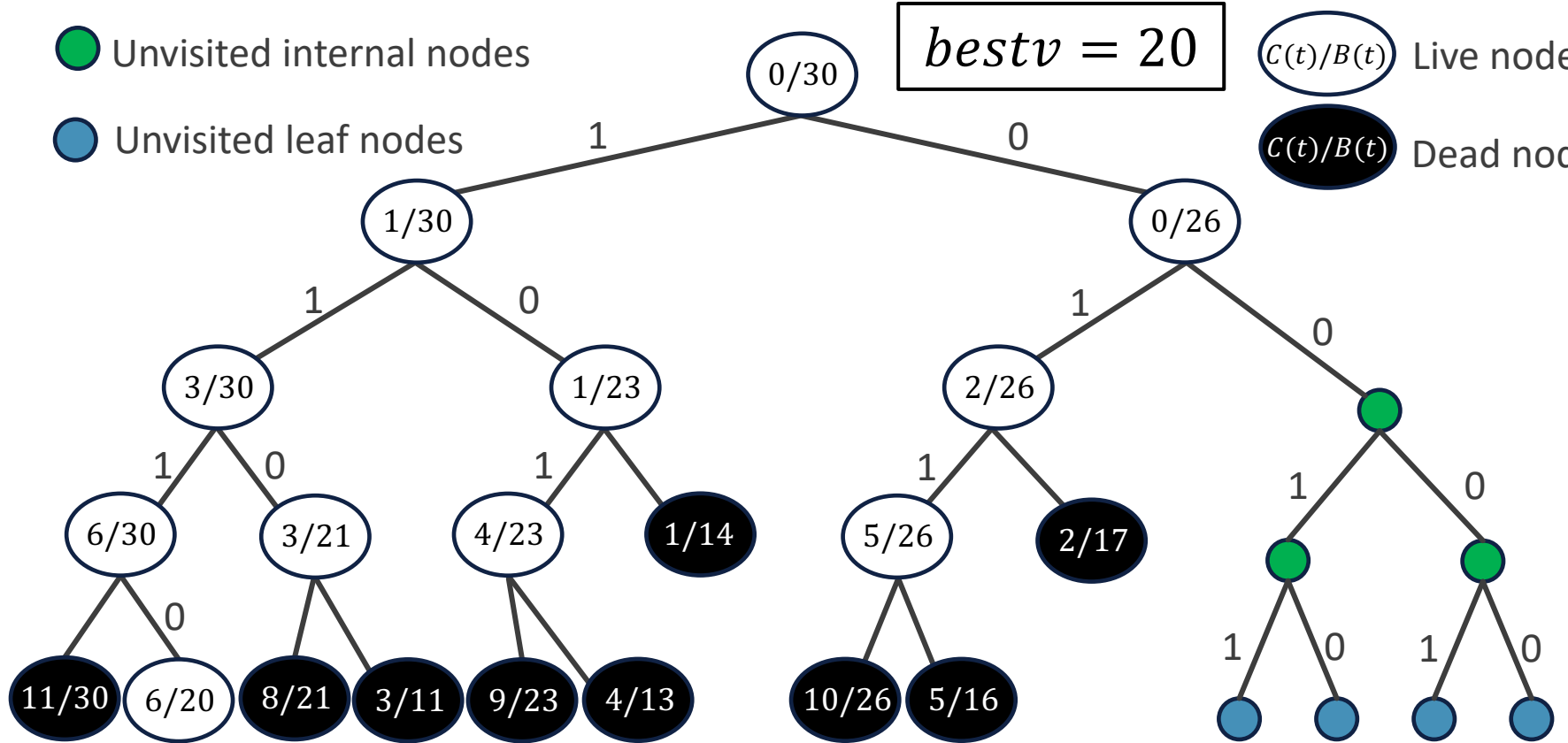
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 20$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, v = [4,7,9,10], w = [1,2,3,5], W = 7$



Example

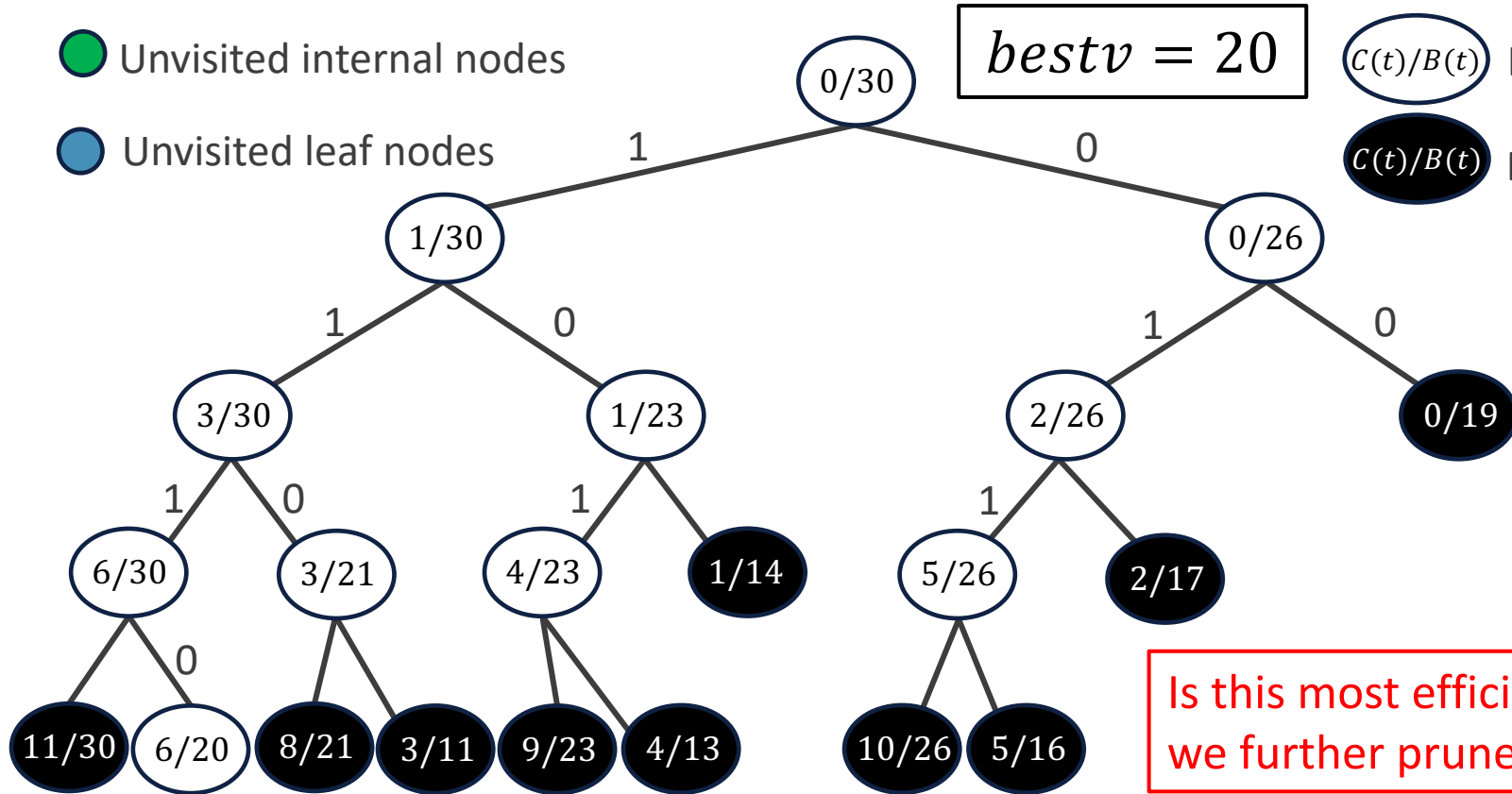
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 20$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, v = [4,7,9,10], w = [1,2,3,5], W = 7$



0/1 Knapsack Problem

- Let's look back at the bounding function

$$B(i) = cv(i) + r(i) \quad cv(i) = \sum_{j=1}^i v_j x_j \quad r(i) = \sum_{j=i+1}^n v_j$$

with the condition $B(i) \leq bestv$.

- What can we do if we want to prune more branches?

Make the bound tighter by decreasing the value of $B(i)$ (actually $r(i)$, because $C(i)$ is fixed at level i).



Example

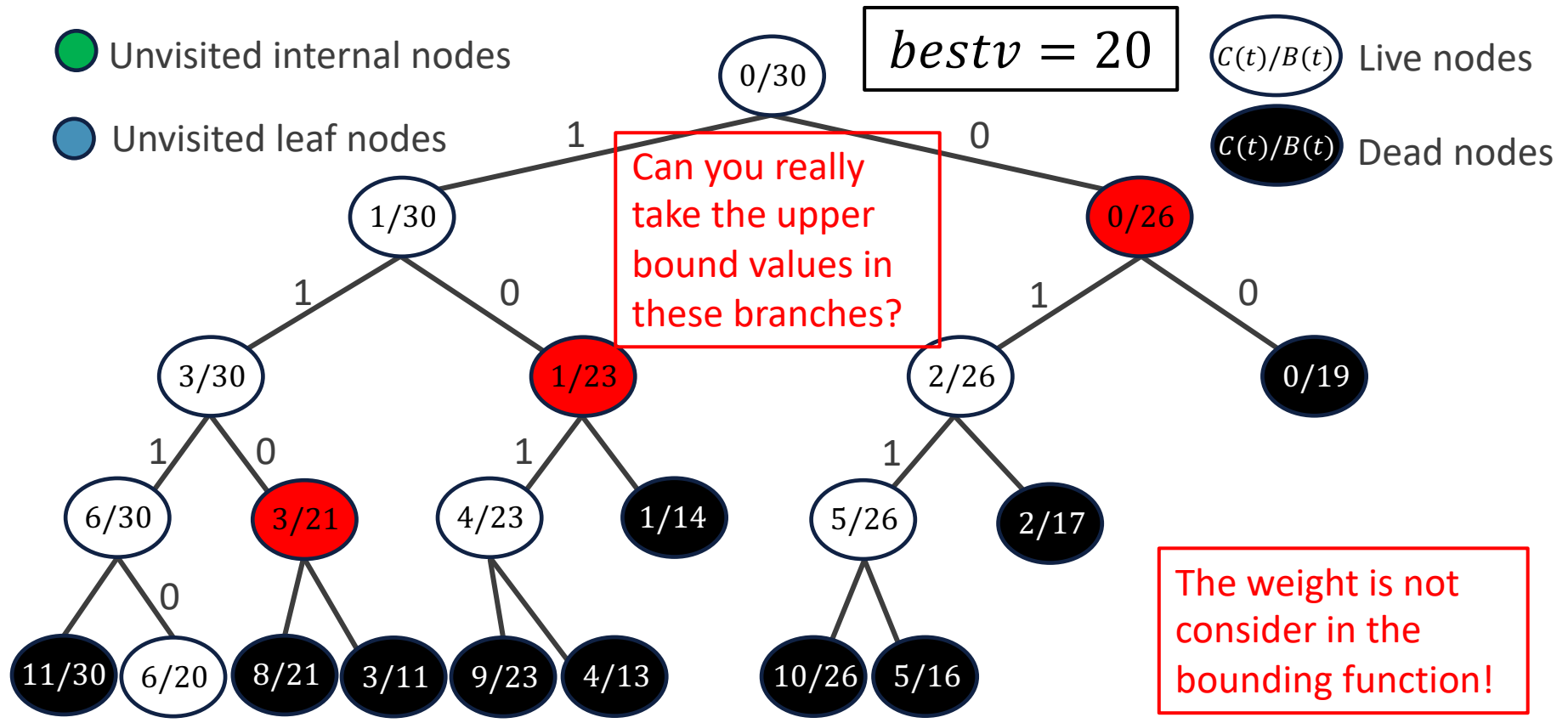
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 20$

$C(t)/B(t)$ Live nodes

$C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, v = [4, 7, 9, 10], w = [1, 2, 3, 5], W = 7$

0/1 Knapsack Problem

- Now, we consider the weight limit in the bounding function.
- Given the remaining capacity $W - cw(i)$, what is the maximum value can we get?
- We can use the following greedy strategy:
 - Take the most valuable remaining items until we can't take any more.
 - Take a fraction of the next item until fully loaded.
- It does not mean we can really take fraction of item. It is just the upper bound of the remaining value.



0/1 Knapsack Problem

- First, sort the objects in decreasing order of value/weight ahead of time, namely

$$v_1/w_1 \geq v_2/w_2 \geq \dots \geq v_n/w_n$$

- Now, we are at level i , which means we have made decision for the first i items.
- We continue to put from item $i + 1$ until item k . When put item k in, the load exceeds W .
- Then we take a fraction of item k for the remaining capacity.

$$r(i) = \underbrace{\sum_{j=i+1}^{k-1} v_j}_{\text{Total value from item } i+1 \text{ to } k-1} + \underbrace{\left(W - cw(i) - \sum_{j=i+1}^{k-1} w_j \right)}_{\text{Capacity available for item } k} \underbrace{\left(\frac{v_k}{w_k} \right)}_{\text{Value per unit weight for item } k}$$



Example

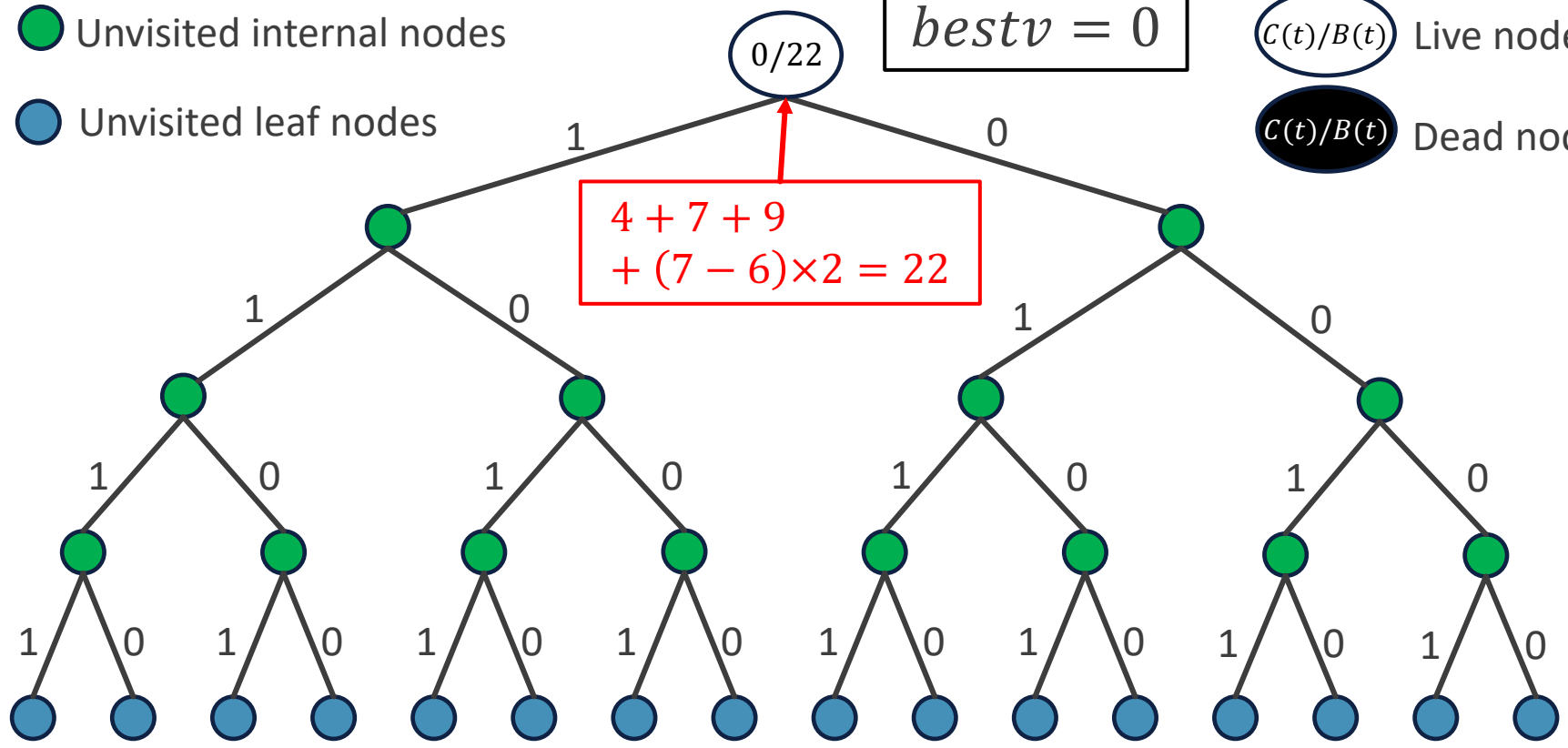
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 0$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, v = [4, 7, 9, 10], w = [1, 2, 3, 5], W = 7, v/w = [4, 3.5, 3, 2]$

Example

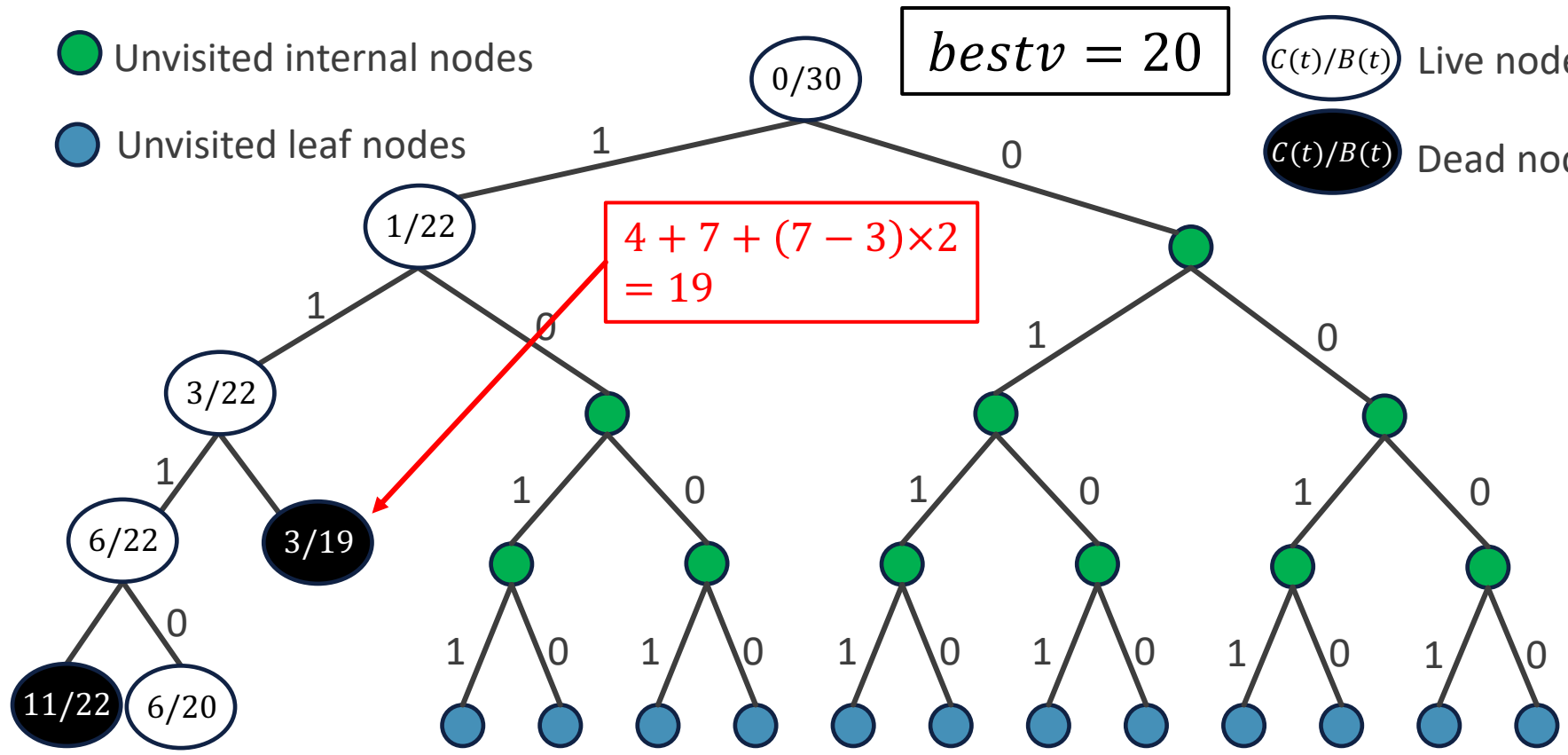
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 20$

$C(t)/B(t)$ Live nodes

$C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, v = [4, 7, 9, 10], w = [1, 2, 3, 5], W = 7, v/w = [4, 3.5, 3, 2]$

Example

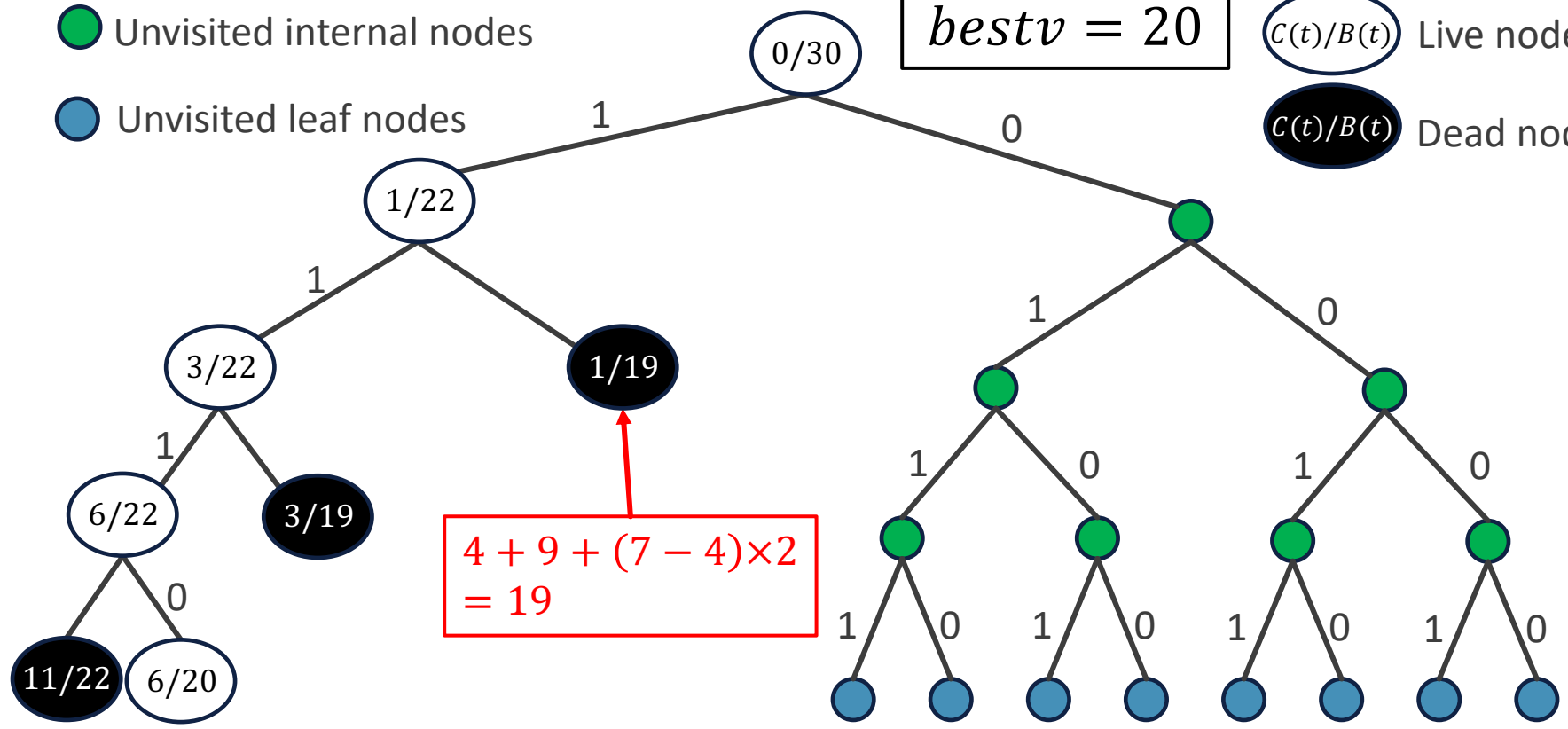
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 20$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 4, v = [4, 7, 9, 10], w = [1, 2, 3, 5], W = 7, v/w = [4, 3.5, 3, 2]$

Example

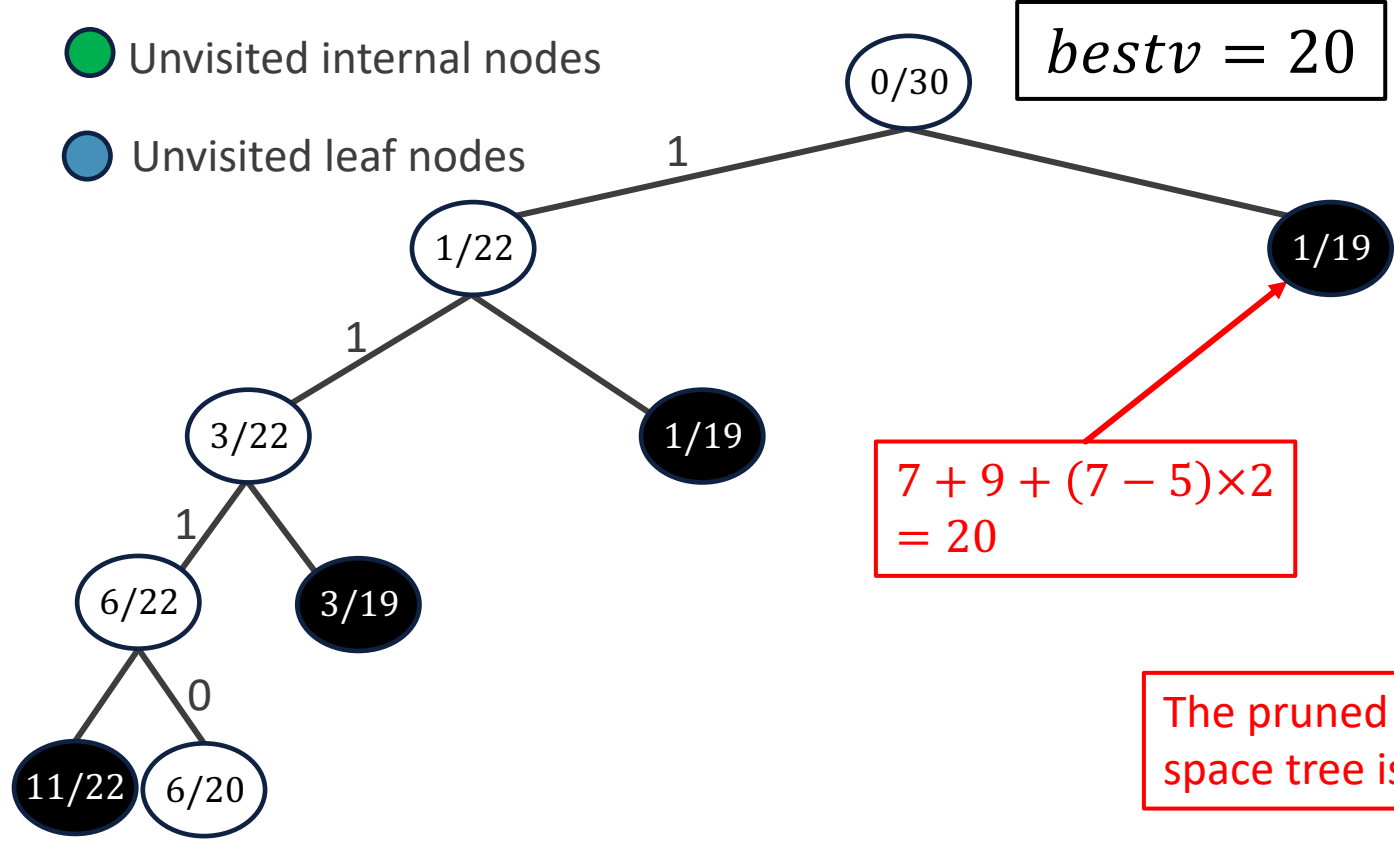
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 20$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



$$7 + 9 + (7 - 5) \times 2 = 20$$

The pruned solution space tree is much better!

Backtracking for $n = 4, v = [4, 7, 9, 10], w = [1, 2, 3, 5], W = 7, v/w = [4, 3.5, 3, 2]$

Pseudocode

BacktrackKnapsack(i)

```
1  if  $i > n$  then
2      if  $cv > bestv$  then
3           $bestv \leftarrow cv$ 
4          for  $j \leftarrow 1$  to  $n$  do
5               $bestx[j] \leftarrow x[j]$ 
6  else
7      if  $C(i) \leq W$  then  $x[i] \leftarrow 1$ 
8           $cw \leftarrow cw + w[i]; cv \leftarrow cv + v[i];$ 
9          BacktrackKnapsack( $i + 1$ )
10          $cw \leftarrow cw - w[i]; cv \leftarrow cv - v[i];$ 
11     if  $B(i) > bestv$  then  $x[i] \leftarrow 0$ 
12         BacktrackKnapsack( $i + 1$ )
```

We don't record the remaining value here and leave it in $B(i)$.

Nothing special compared with container loading problem. Just separate cw and cv .



Pseudocode

$r(i)$

1 $rw \leftarrow W - cw$ Remaining capacity

2 $b \leftarrow cv$ Total value

3 **while** $i + 1 \leq n$ and $w[i + 1] \leq rw$ **do** Loop until we can't take the whole item $i + 1$

4 $rw \leftarrow rw - w[i + 1]$

5 $b \leftarrow b + v[i + 1]$

6 $i \leftarrow i + 1$ Take a fraction of item $i + 1$

7 **if** $i + 1 \leq n$ **then** $b \leftarrow b + v[i + 1]/w[i + 1] \times rw$

8 **return** b



Classroom Exercise

- Draw the pruned solution space tree of 0/1 knapsack problem for the following problem instance:

$$n = 3, v = [4,3,1], w = [2,5,5], W = 6$$



Classroom Exercise

- First, rank the item by their value per unit weight:

$$n = 3, v = [40,30,20], w = [2,5,4], W = 6, v/w = [20,6,5]$$



Classroom Exercise

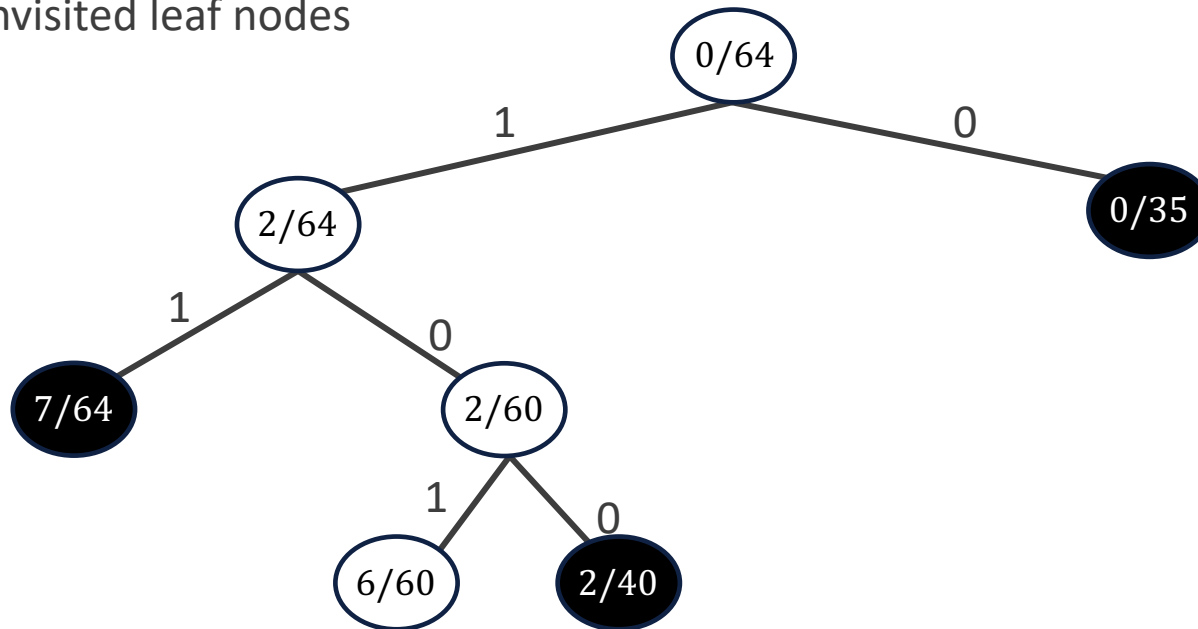
● Unvisited internal nodes

● Unvisited leaf nodes

$bestv = 60$

○ $C(t)/B(t)$ Live nodes

● $C(t)/B(t)$ Dead nodes



Backtracking for $n = 3, v = [40, 30, 20], w = [2, 5, 4], W = 6, v/w = [20, 6, 5]$

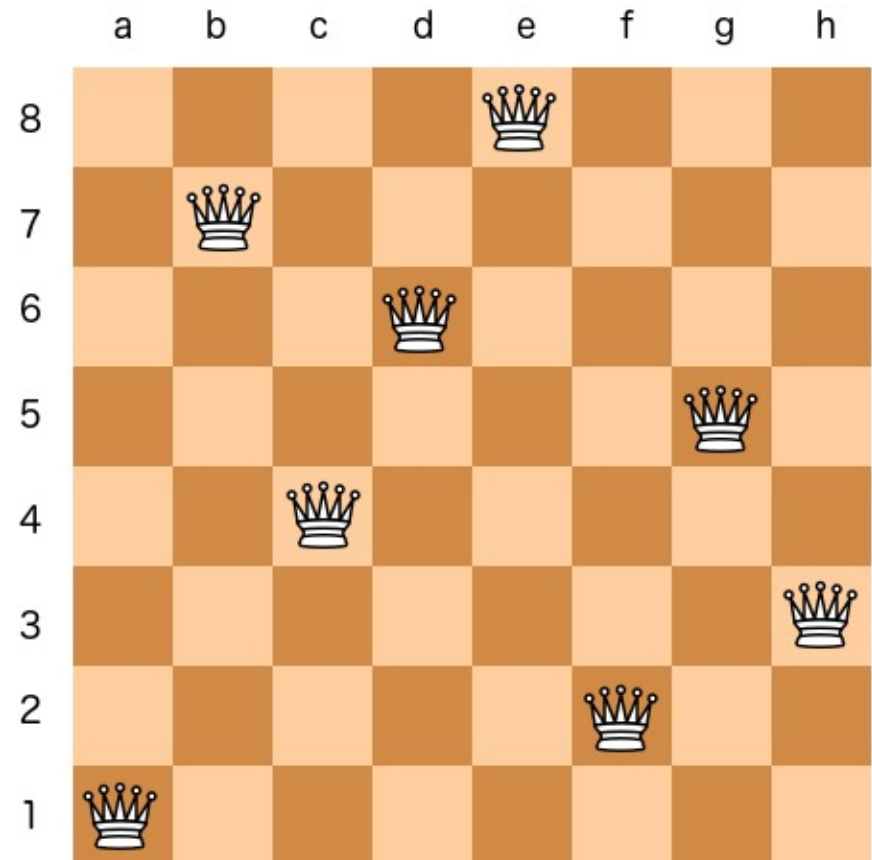




n QUEEN PROBLEM

n Queen Problem

- The goal of n queen problem (n 皇后问题) is to position n queens on an $n \times n$ chessboard so that no two queens threaten each other.
 - No two queens may be in the same row, column, or diagonal.

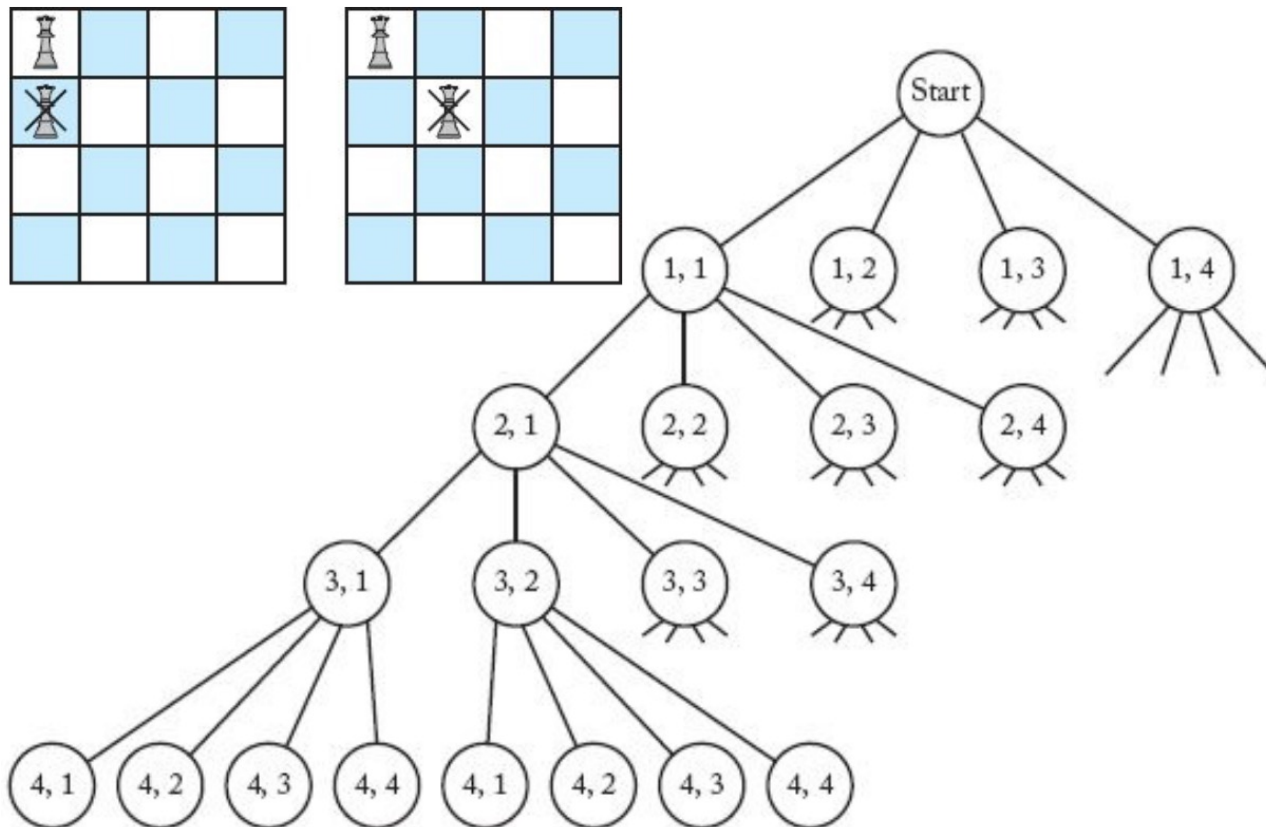


n Queen Problem

- What is the size of solution space for the i th queen?
- $n^2 - i + 1$? It is too large. We can limit it by considering the constraint.
 - Because two queens can't be put in the same row, we directly put each queen in different row.
 - Now, the solution space for the i th queen is n .
 - Thus, the constraint function only needs to check if two queens are in the same column or diagonal.



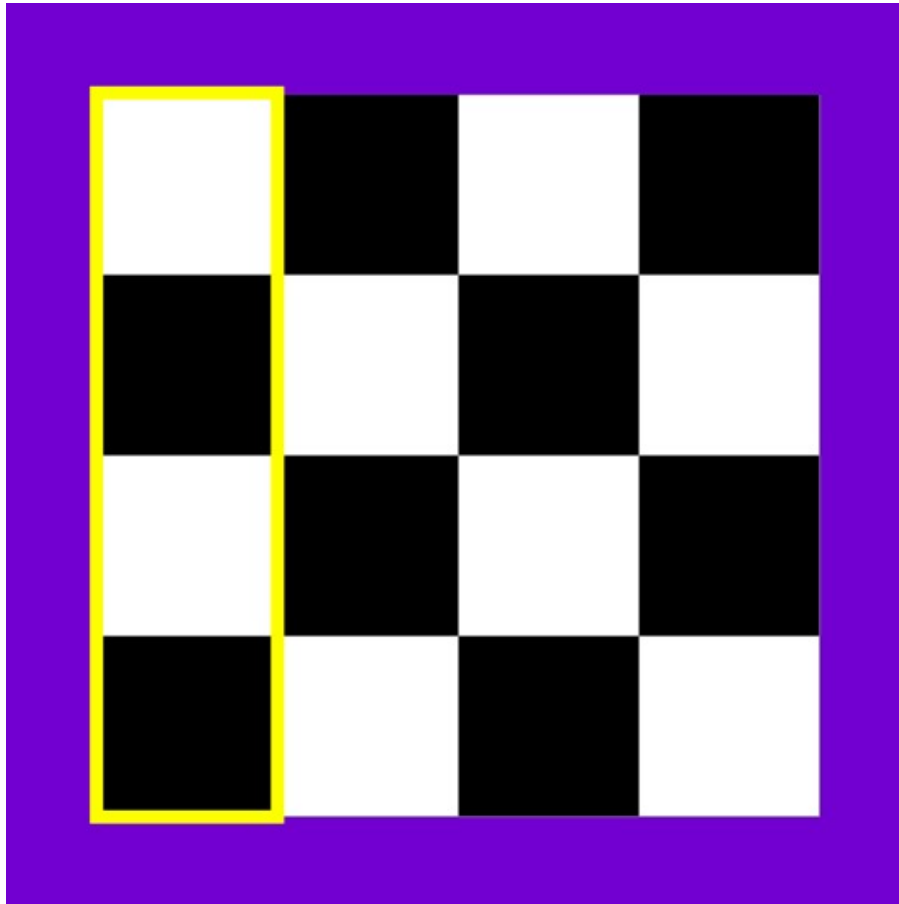
n Queen Problem



The solution space tree for $n = 4$



n Queen Problem



What is the
constraint function?



n Queen Problem

- The constraint function checks if the new added queen is in the same column, or along the same diagonal.
- Now, we know that the i th queen is in the i th row. Let x_i be the column of the i th queen.

- If the k th and j th queen are in the same column:

$$x_k = x_j$$

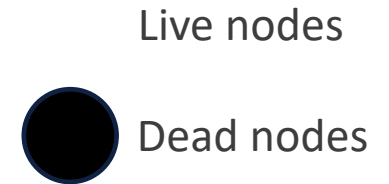
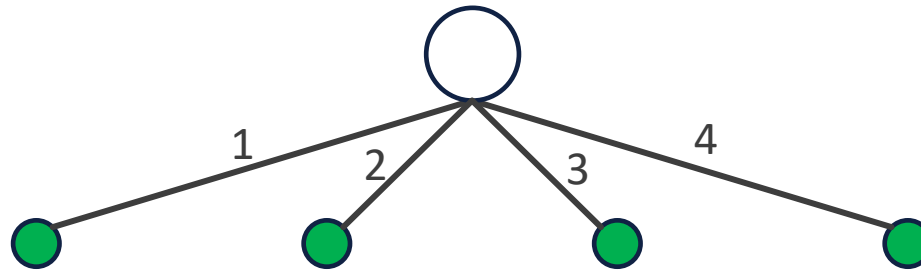
- If the k th and j th queen are along the same diagonal:

$$x_k - x_j = k - j \quad \text{or} \quad x_k - x_j = j - k$$

Namely: $|x_k - x_j| = |k - j|$.



Example

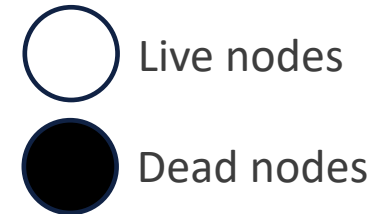
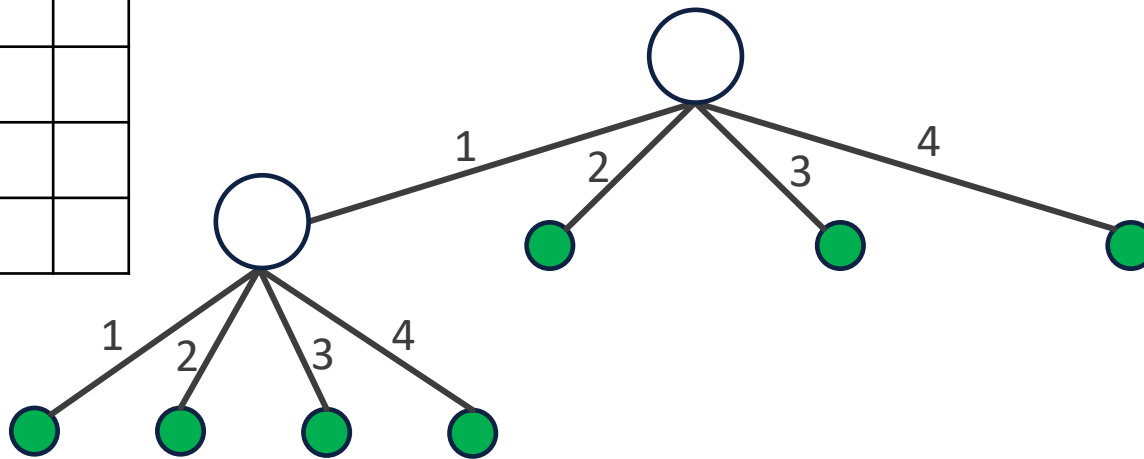


Backtracking for $n = 4$



Example

●			

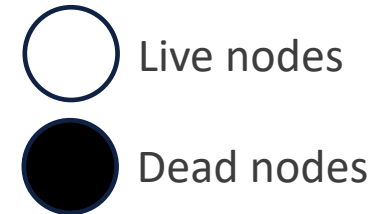
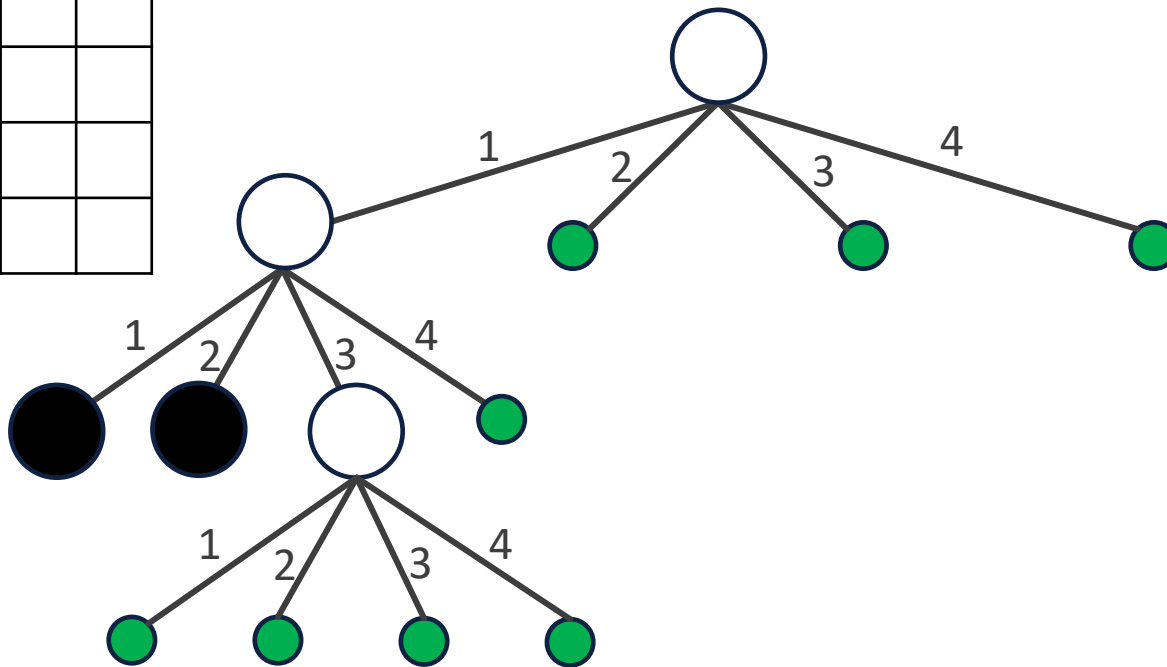


Backtracking for $n = 4$



Example

●	×		
	×		
	●		

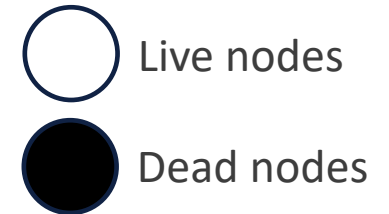
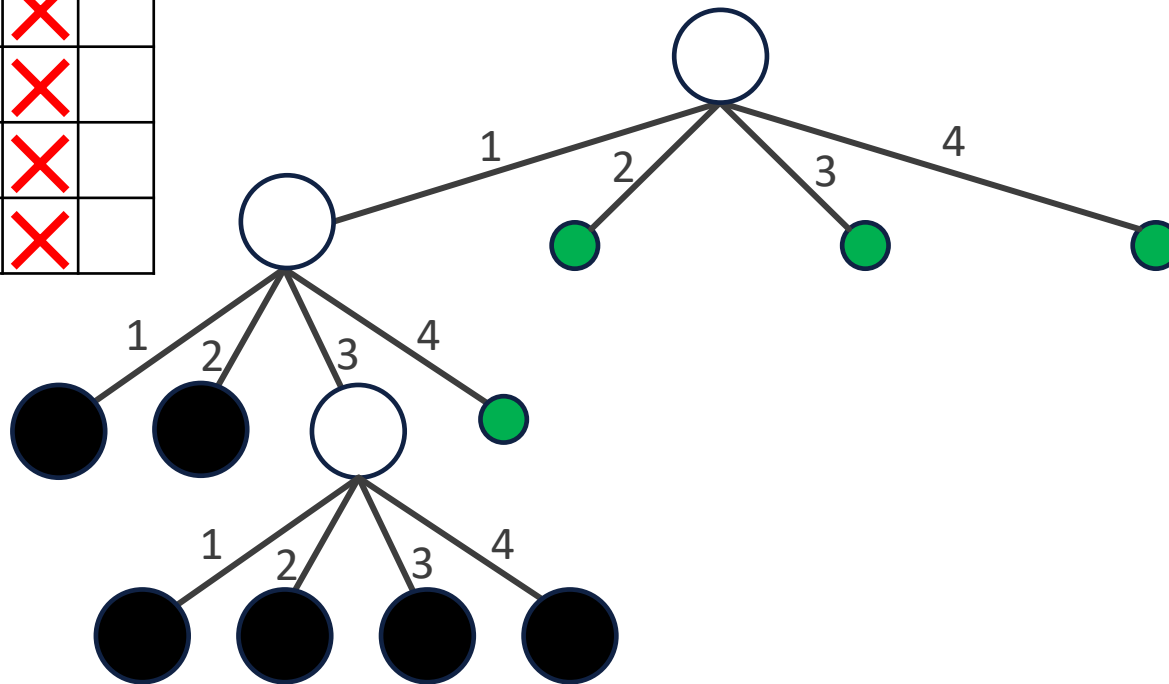


Backtracking for $n = 4$



Example

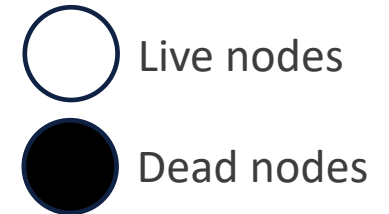
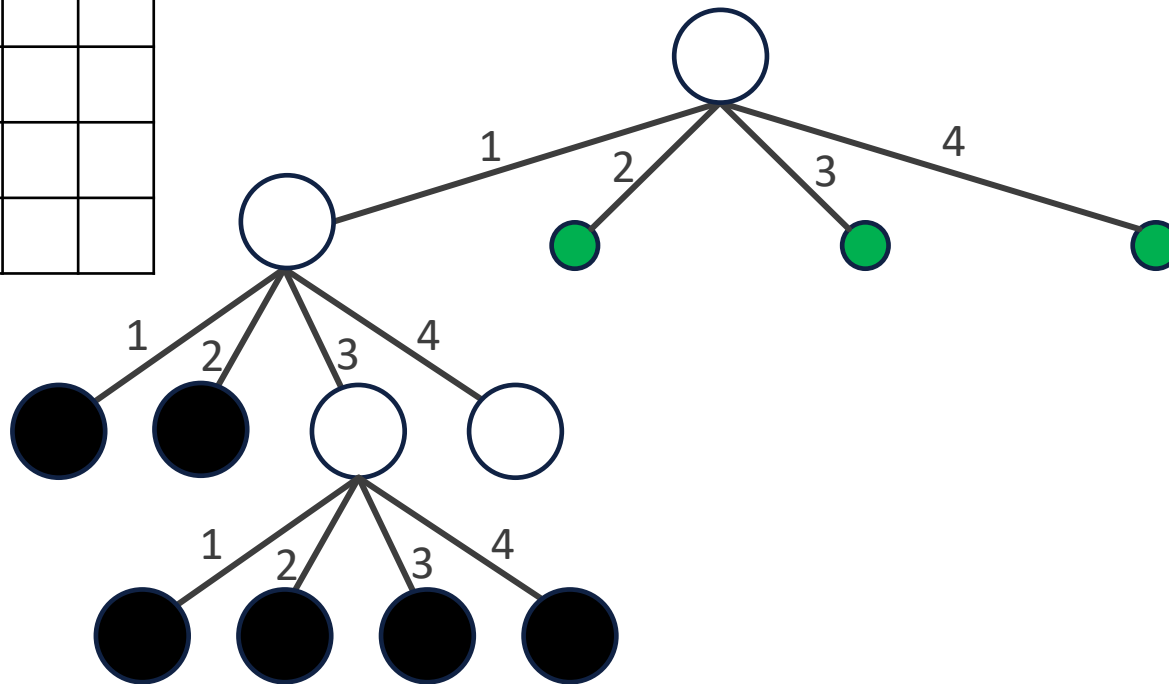
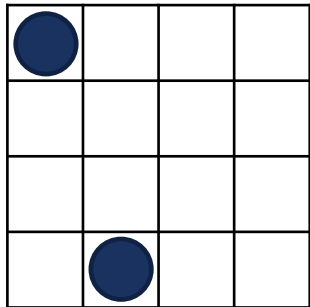
●	×	×	
	×	×	
	●	×	
		×	



Backtracking for $n = 4$



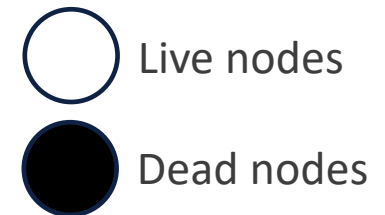
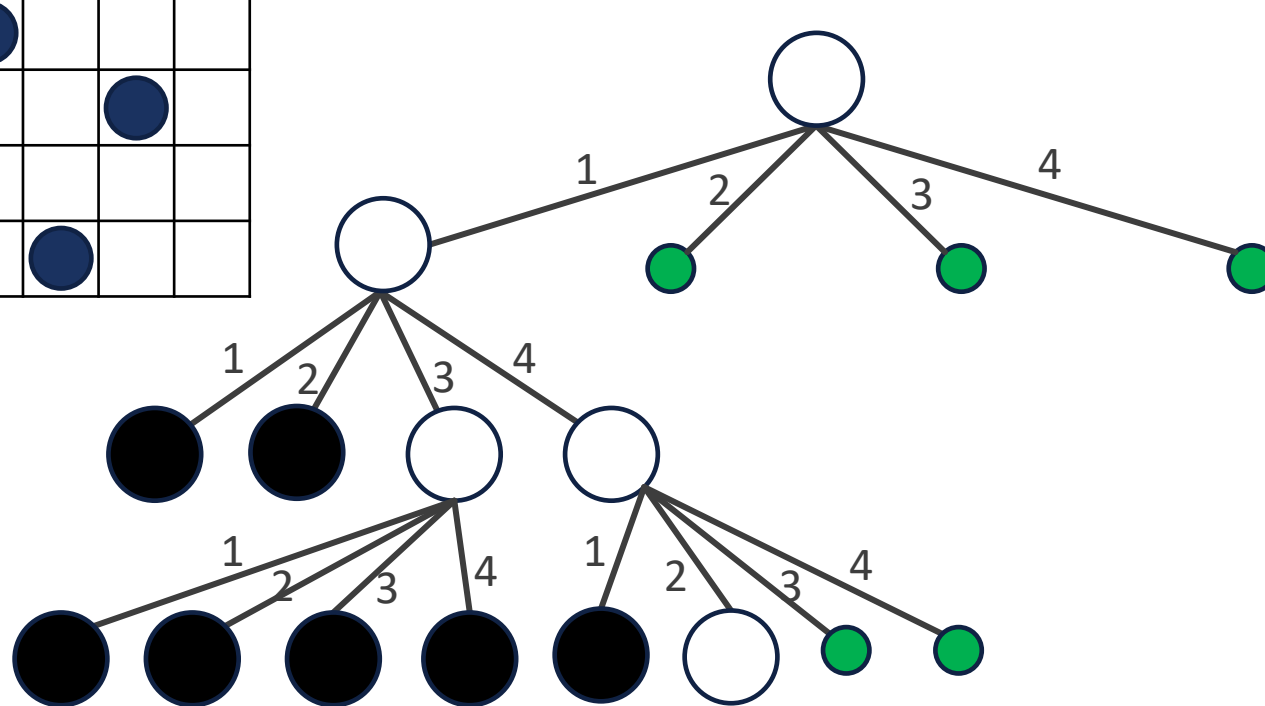
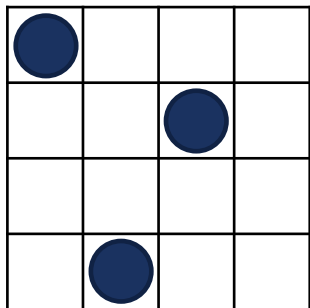
Example



Backtracking for $n = 4$



Example

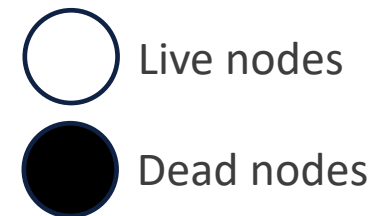
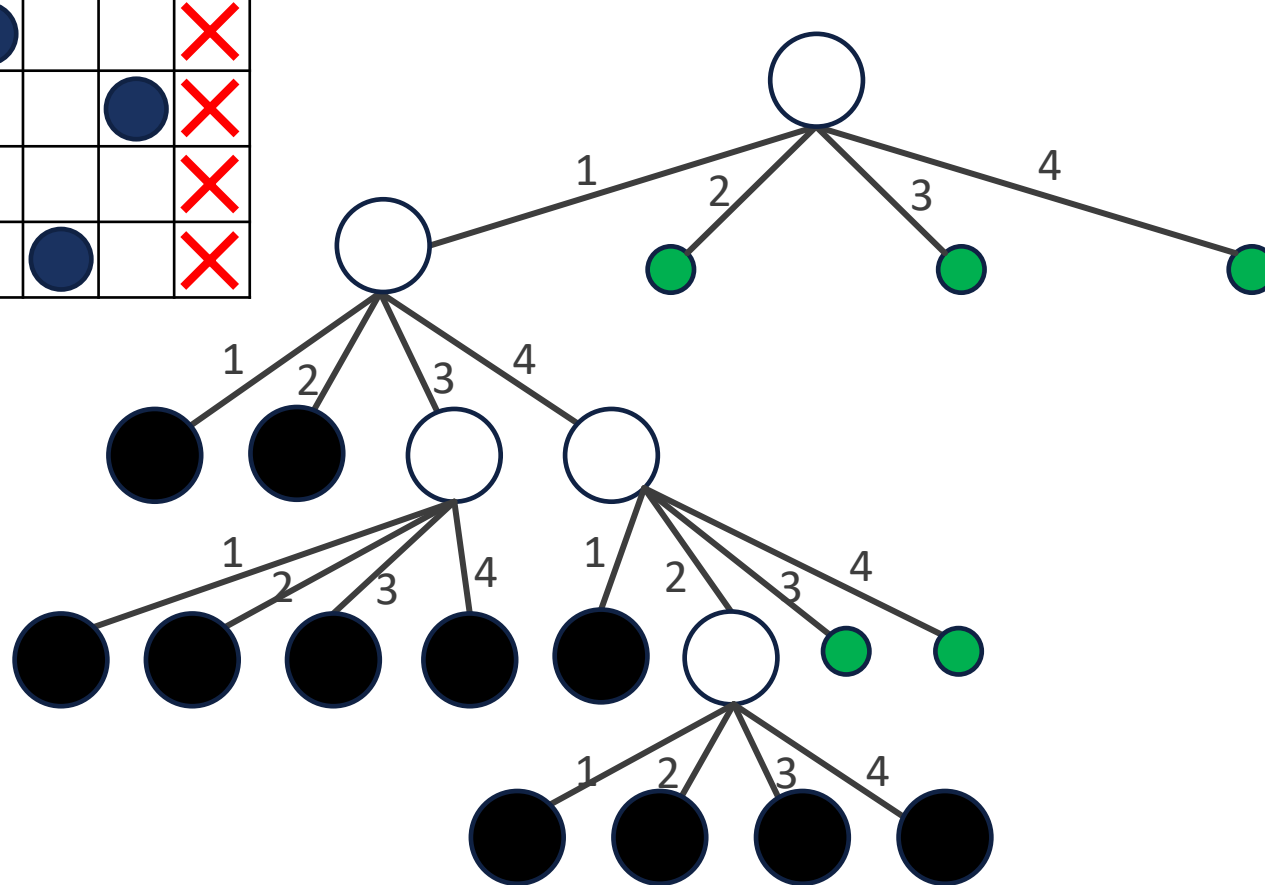


Backtracking for $n = 4$



Example

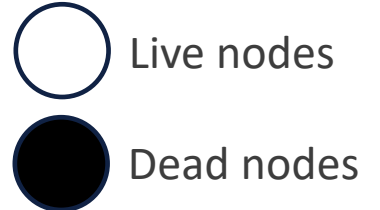
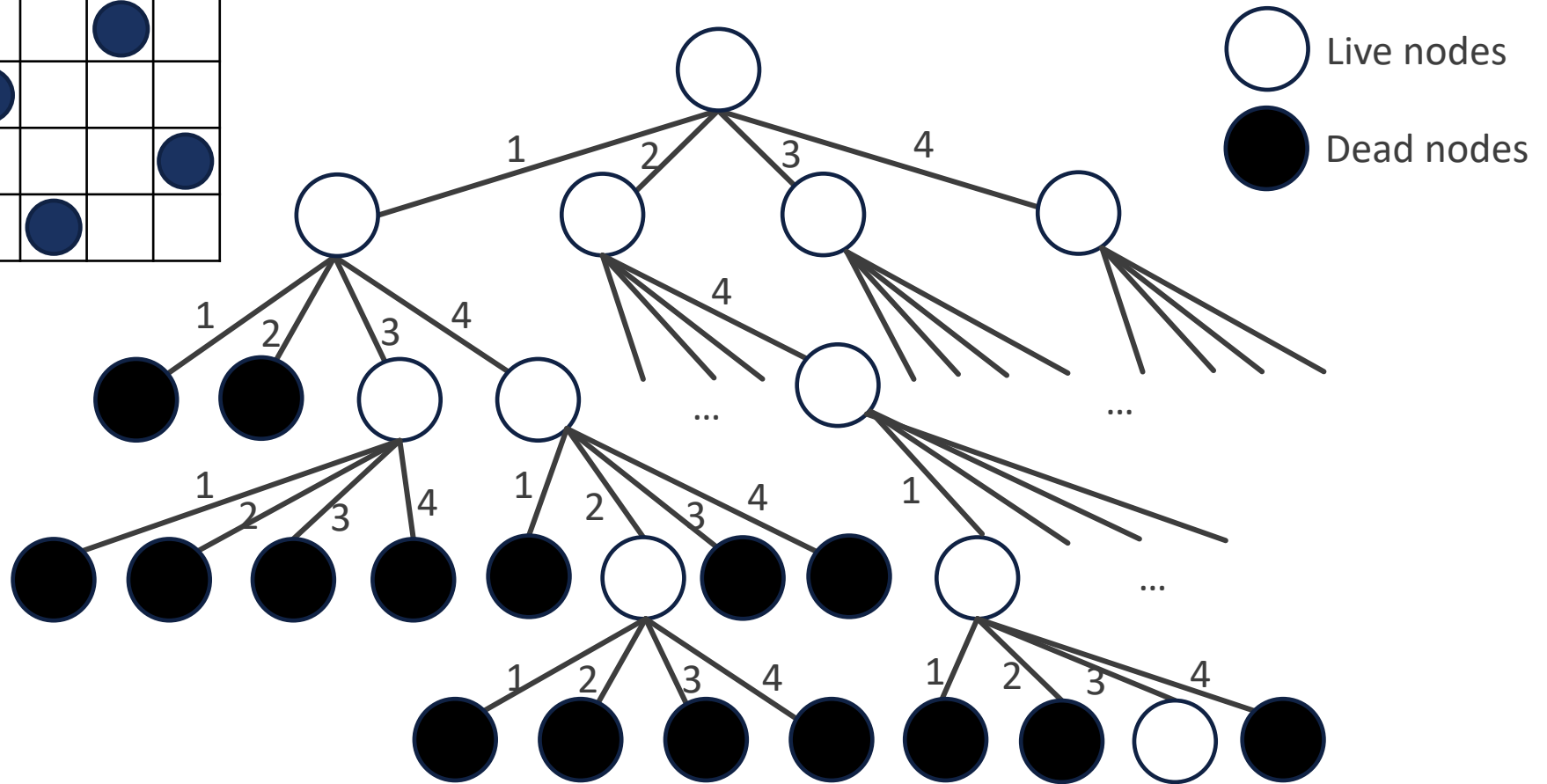
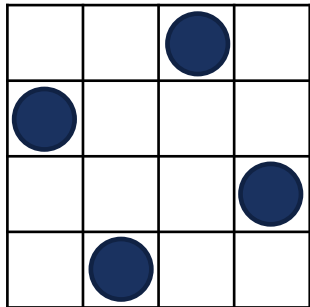
●			×
		●	×
			×
	●		×



Backtracking for $n = 4$



Example



Backtracking for $n = 4$



Pseudocode

BacktrackNQueens()

```
1   $x[1] \leftarrow 0$ 
2   $k \leftarrow 1$ 
3  while  $k > 0$  do
4      while  $x[k] \leq n - 1$  do
5           $x[k] \leftarrow x[k] + 1$ 
6          if Place( $k$ ) = True then
7              if  $k = n$  then  $SolNum \leftarrow SolNum + 1$ 
8              else
9                   $k \leftarrow k + 1$ 
10                  $x[k] \leftarrow 0$ 
11          $k \leftarrow k - 1$ 
```

Start from 0,
increment in the loop,
so the condition only
checks $\leq n - 1$

Place(k)

```
1  for  $j \leftarrow 1$  to  $k - 1$  do
2      if  $|k - j| = |x[k] - x[j]|$   
    or  $x[j] = x[k]$  then
3          return False
4  return True
```

Number of
valid solutions

No recursion is used here



Classroom Exercise

Write the pseudocode of the recursive version of n queen problem.



Classroom Exercise

```
RecursiveBacktrackNqueens(k) ← Start from 0
3  if Place(k) = True then
4    if k = n then SolNum ← SolNum + 1
5    else
        for j ← 1 to n do
5      x[k + 1] ← j
6      RecursiveBacktrackNqueens(k + 1)
```

```
Place(k)
1  for j ← 1 to k - 1 do
2    if  $|k - j| = |x[k] - x[j]|$  or  $x[j] = x[k]$  then
3      return False
4  return True
```



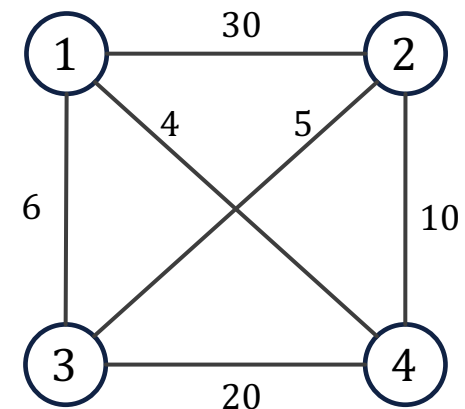


TRAVELING SALESPERSON PROBLEM



Traveling Salesperson Problem

- Given an n vertex network (undirected or directed), **traveling salesperson problem (旅行商问题, TSP)** is to find a cycle of minimum cost that includes all n vertices.
 - Hamiltonian cycle with minimum cost.
- Any cycle that includes all n vertices of a network is called a tour. In TSP, we are to find a least-cost tour. For example:
 - Tour (1,2,4,3,1) costs 66.
 - Tour (1,4,3,2,1) costs 59.
 - Tour (1,3,2,4,1) costs 25, optimal.



Traveling Salesperson Problem



Traveling Salesperson Problem

- Since a tour is a cycle that includes all vertices, we may pick any vertex as the start (and hence the end).
 - Usually we use vertex 1 as the start and end vertex.

- Each tour is then described by the vertex sequence:

$$(1, x_2, \dots, x_n, 1)$$

where x_2, \dots, x_n is a permutation of $(2, 3, \dots, n)$.

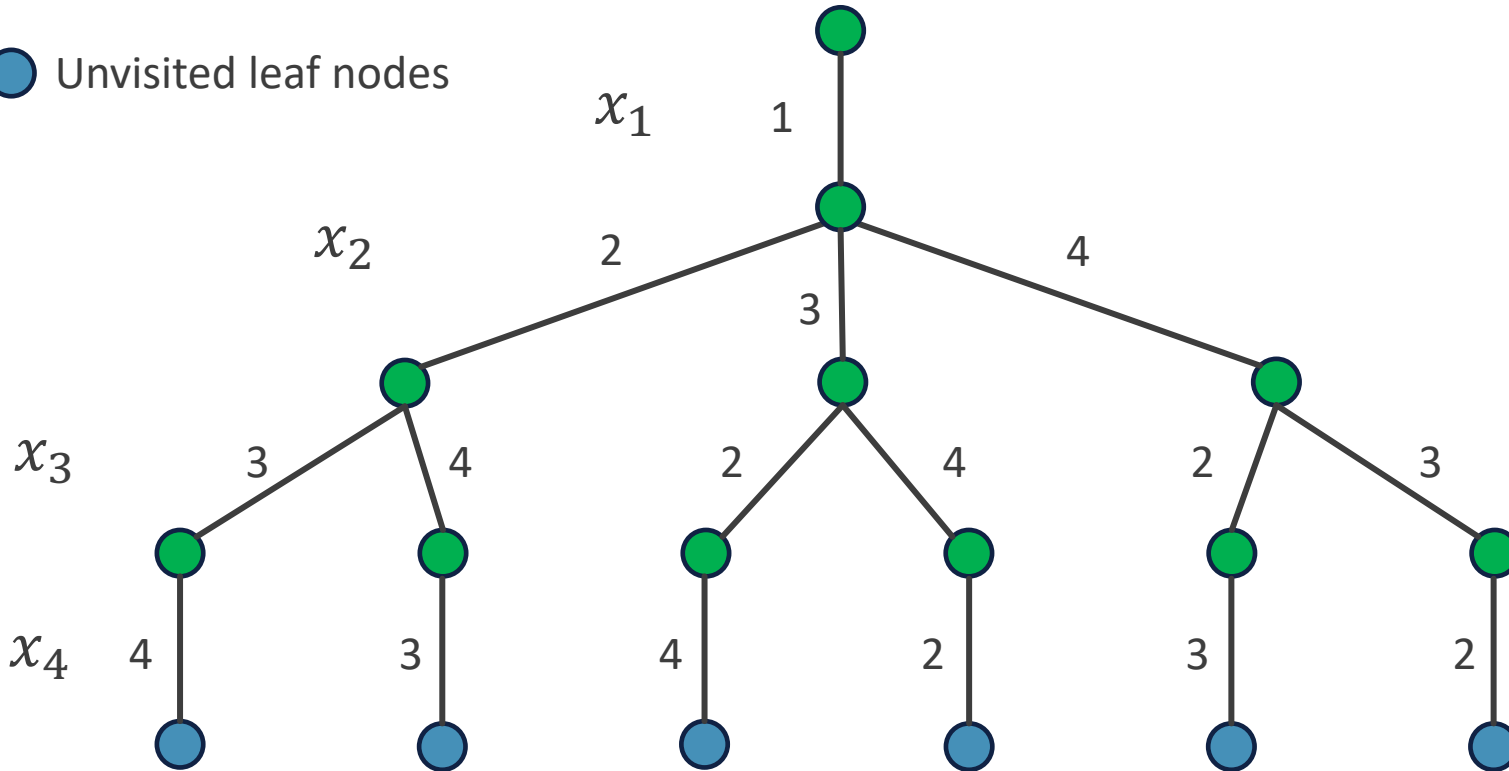
- The possible tours may be described by a permutation tree in which each root-to-leaf path defines a tour.



Traveling Salesperson Problem

● Unvisited internal nodes

● Unvisited leaf nodes



Permutation tree for TSP when $n = 4$



Traveling Salesperson Problem

- $w[i, j]$ denotes the weight of vertex i and vertex j .
- $w[i, j] = \infty$ denotes no edge between vertex i and vertex j .
- $x[i]$ denotes the vertex to be searched.
- What are the constraint function and bounding function?



Traveling Salesperson Problem

- Constraint function $C(i)$ is to simply check if the next vertex is connected to the current vertex:

$$C(i) = w[x[i], x[j]]$$

Check if $C(i) \neq \infty$.

- Bounding function $B(i)$ is the total weight if we connect $x[i]$:

$$B(i) = cw(i-1) + w[x[i-1], x[i]]$$

$$cw(i) = \sum_{j=2}^i w[x[j-1], x[j]]$$

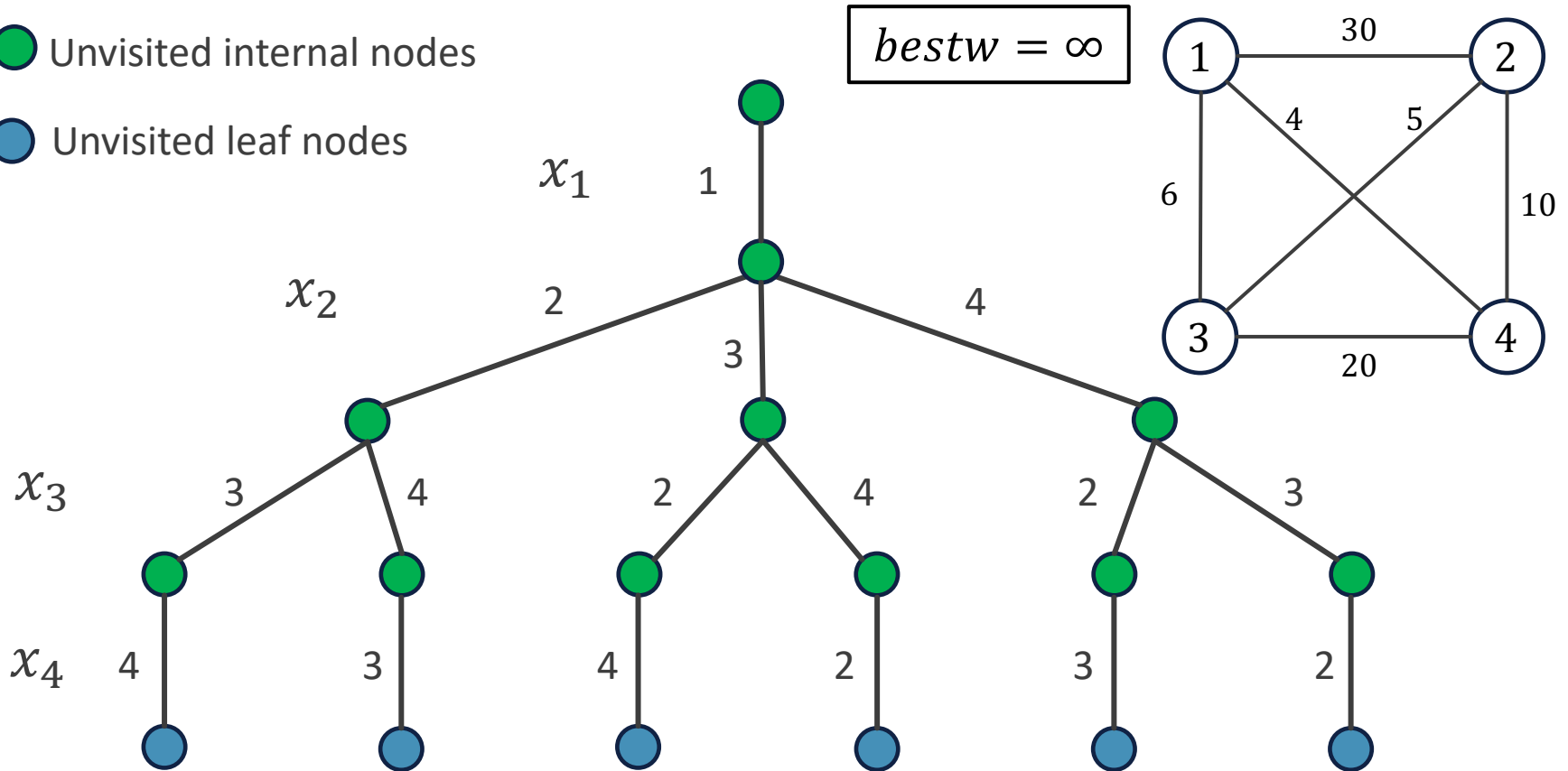
Check if $B(i) < bestw$.



Example

● Unvisited internal nodes

● Unvisited leaf nodes



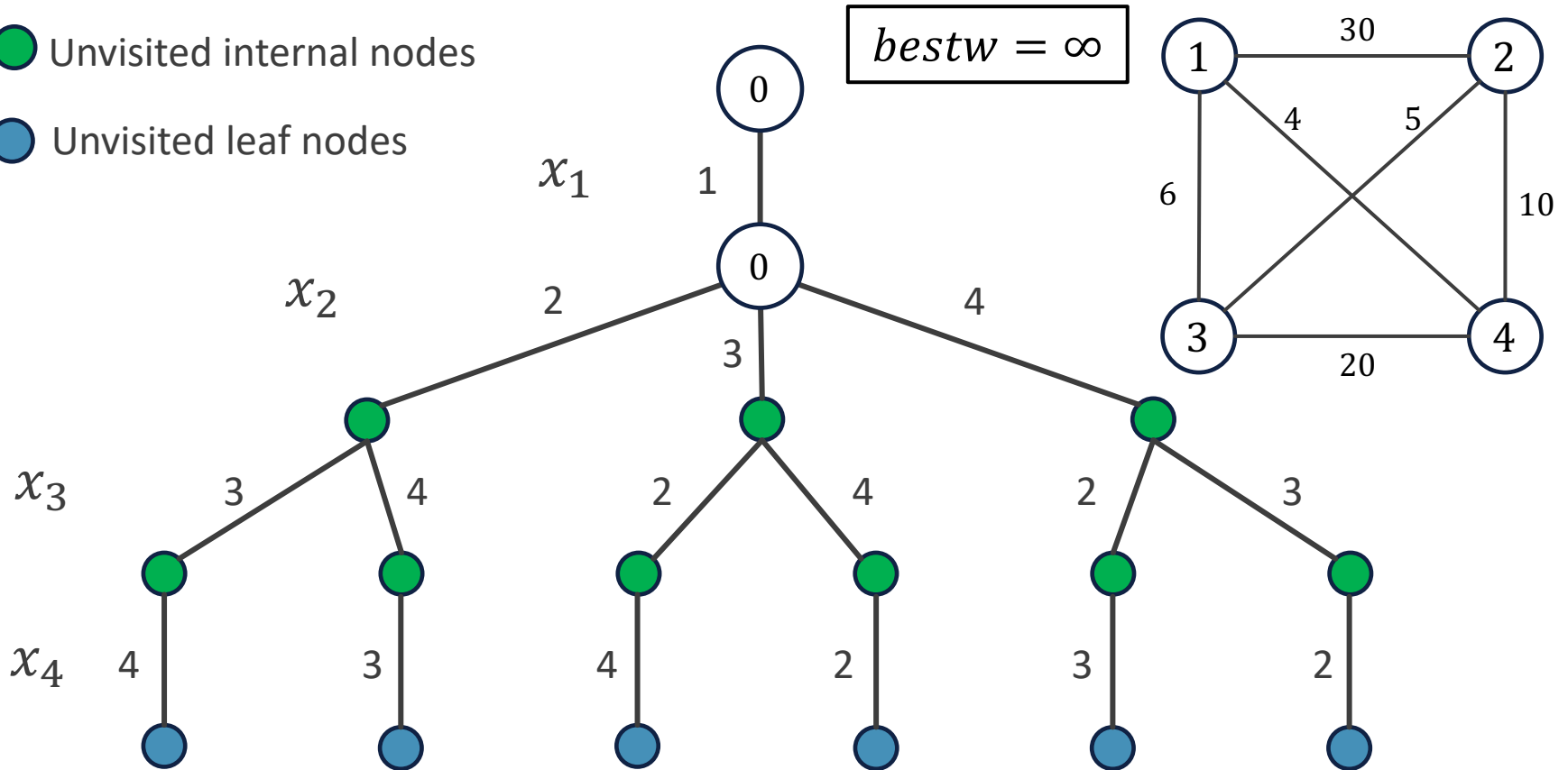
This graph is complete graph. Therefore the constraint function is useless.



Example

● Unvisited internal nodes

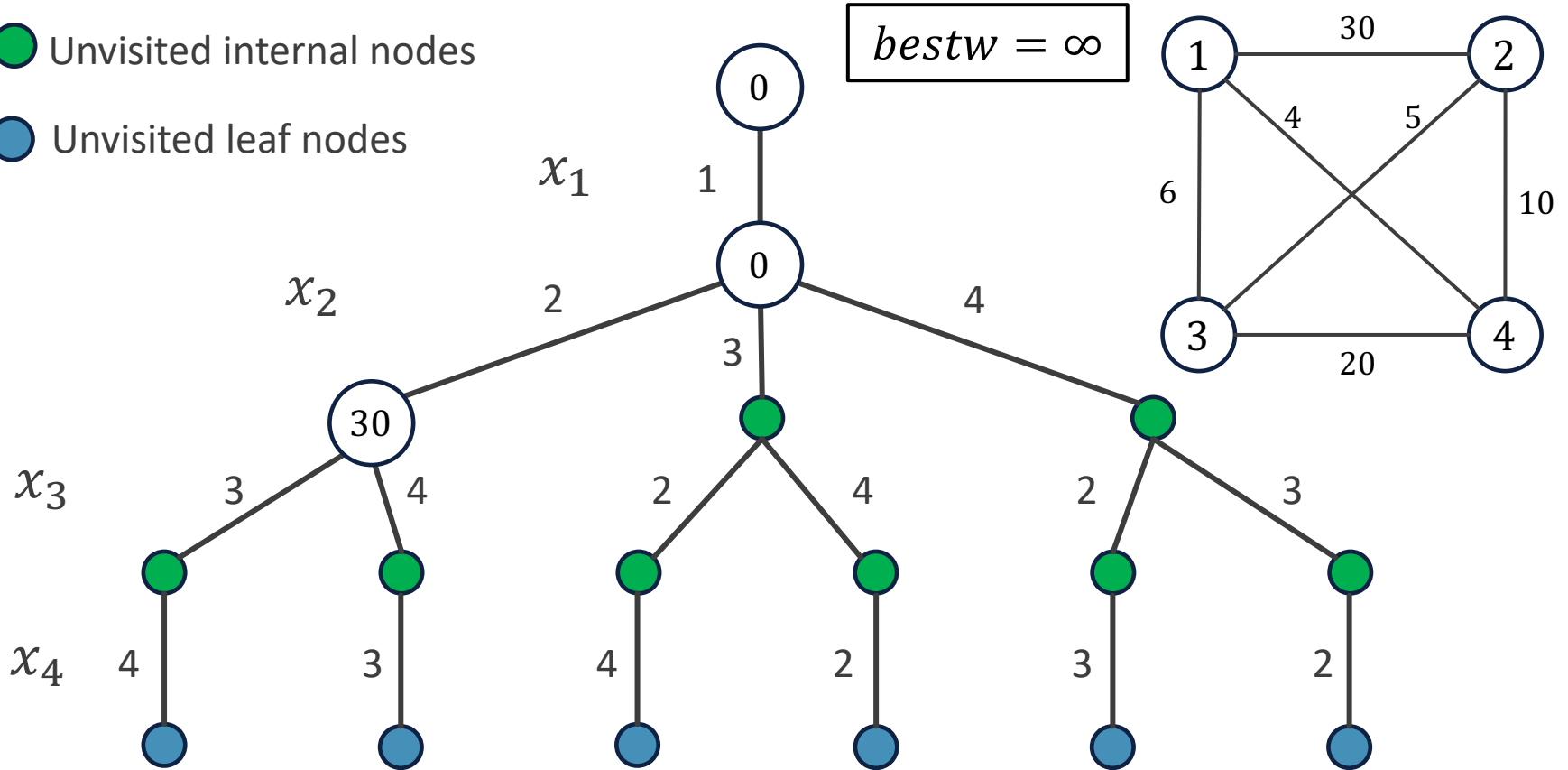
● Unvisited leaf nodes



Example

● Unvisited internal nodes

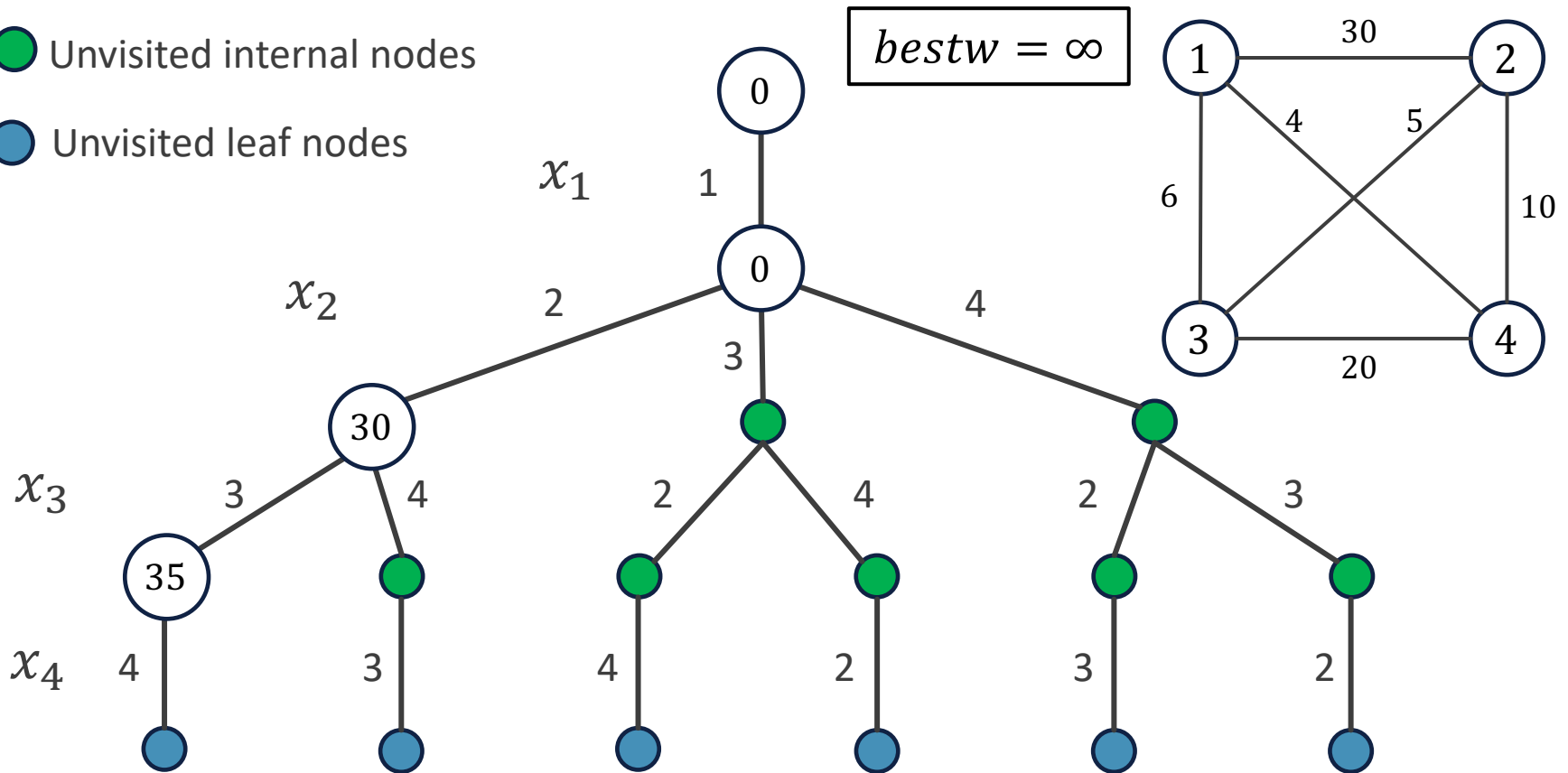
● Unvisited leaf nodes



Example

● Unvisited internal nodes

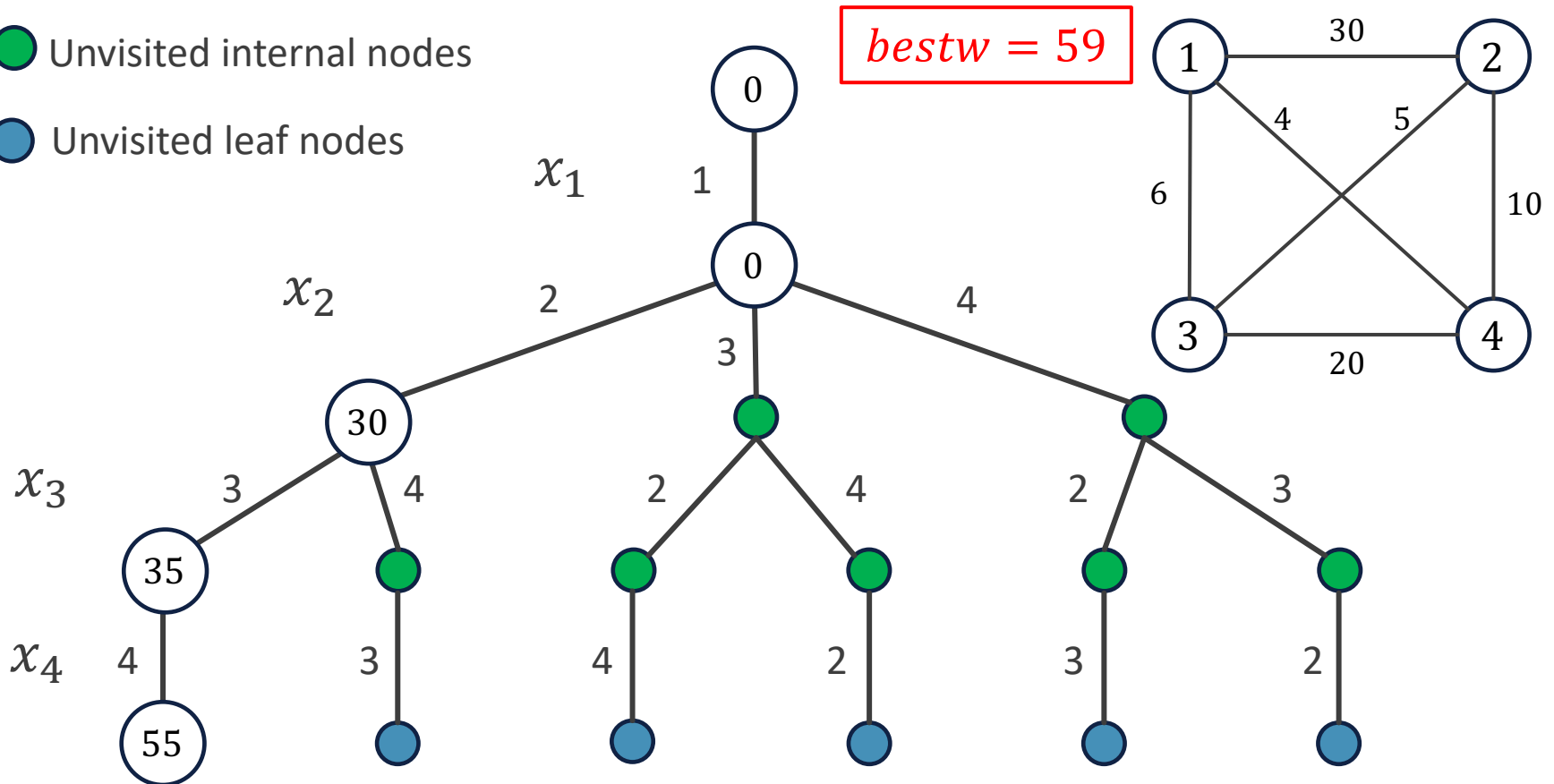
● Unvisited leaf nodes



Example

● Unvisited internal nodes

● Unvisited leaf nodes



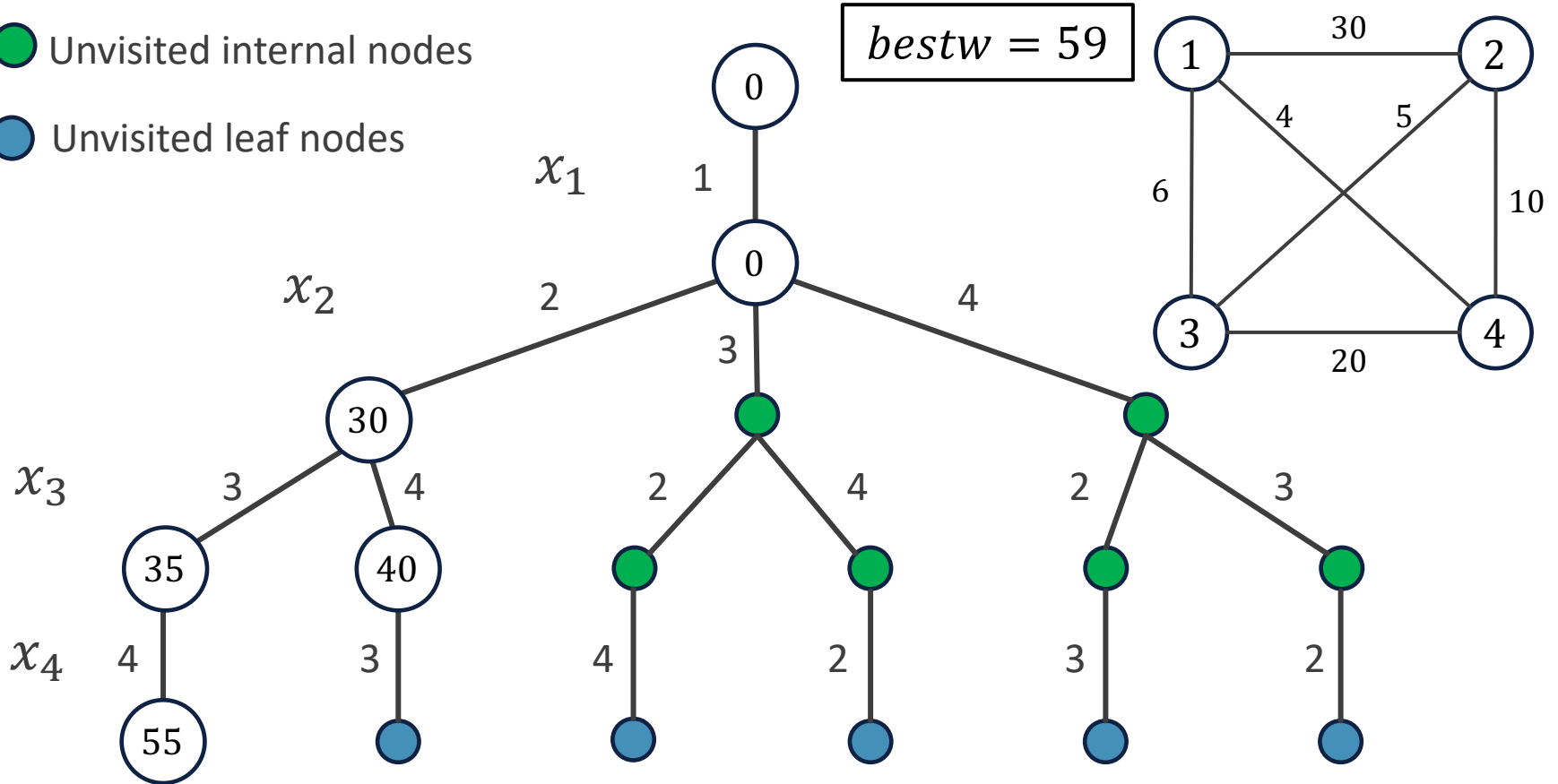
(1,2,3,4,1), 59



Example

● Unvisited internal nodes

● Unvisited leaf nodes



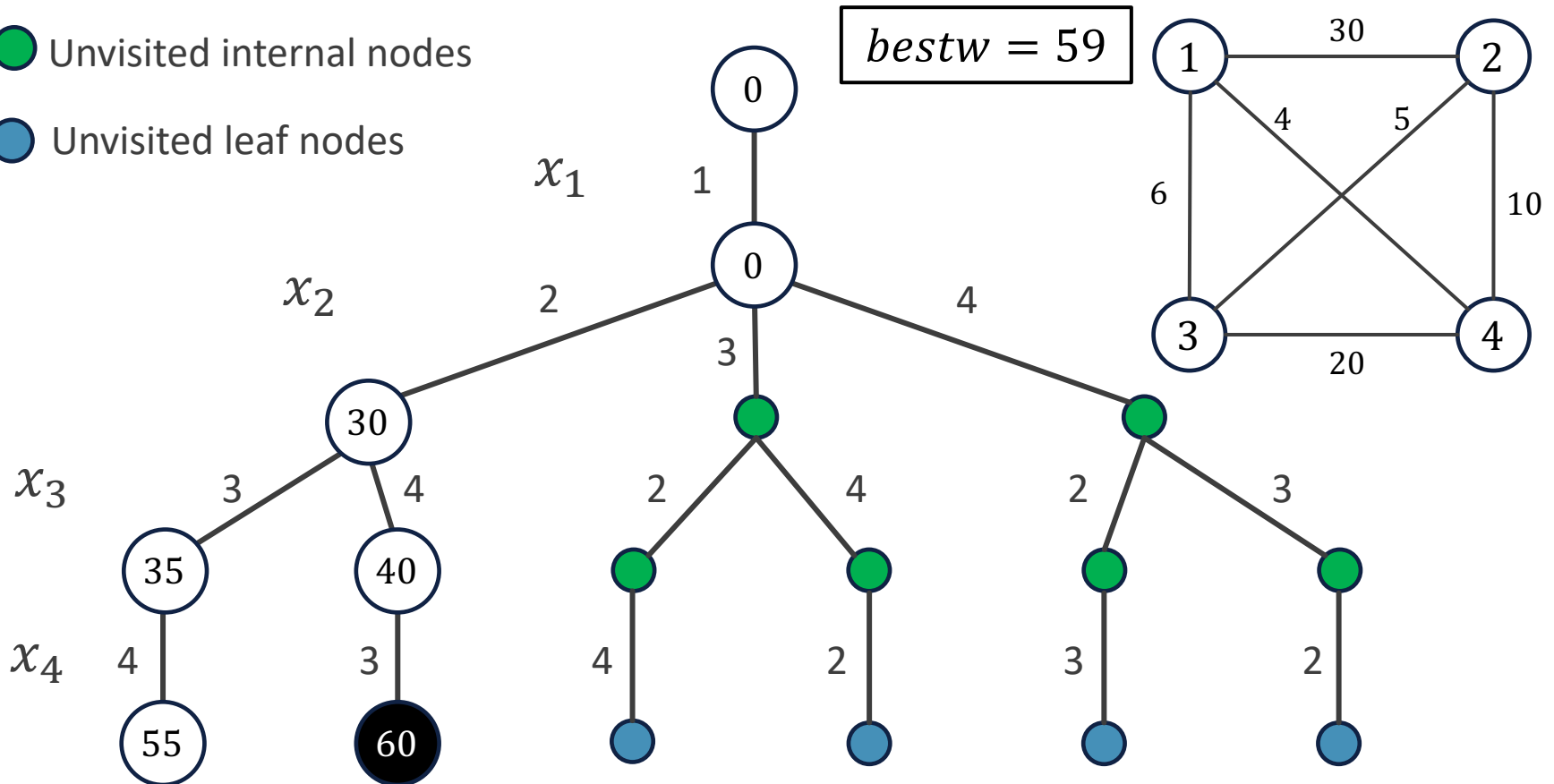
$(1,2,3,4,1), 59$



Example

● Unvisited internal nodes

● Unvisited leaf nodes



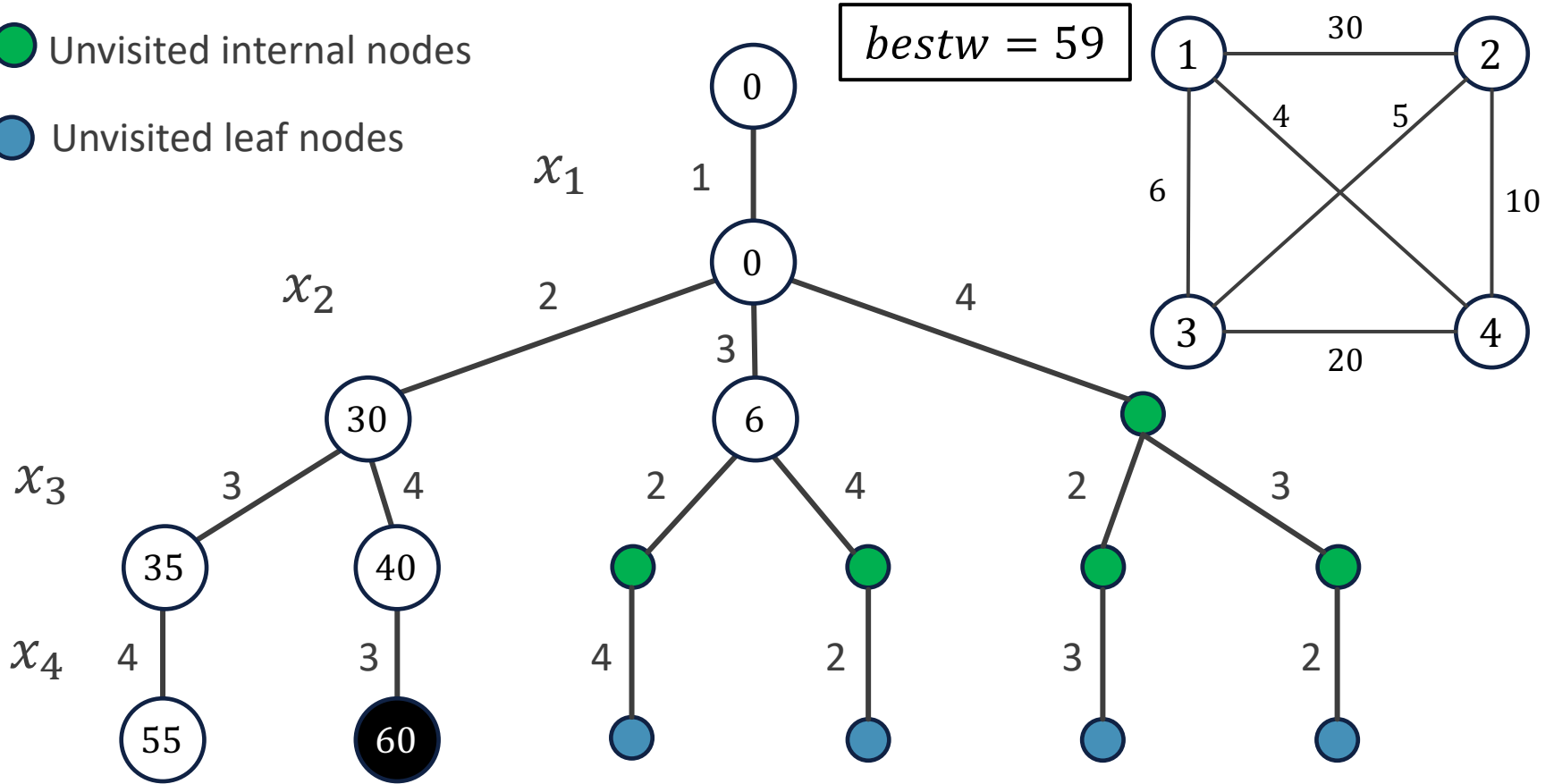
$(1,2,3,4,1), 59$



Example

● Unvisited internal nodes

● Unvisited leaf nodes



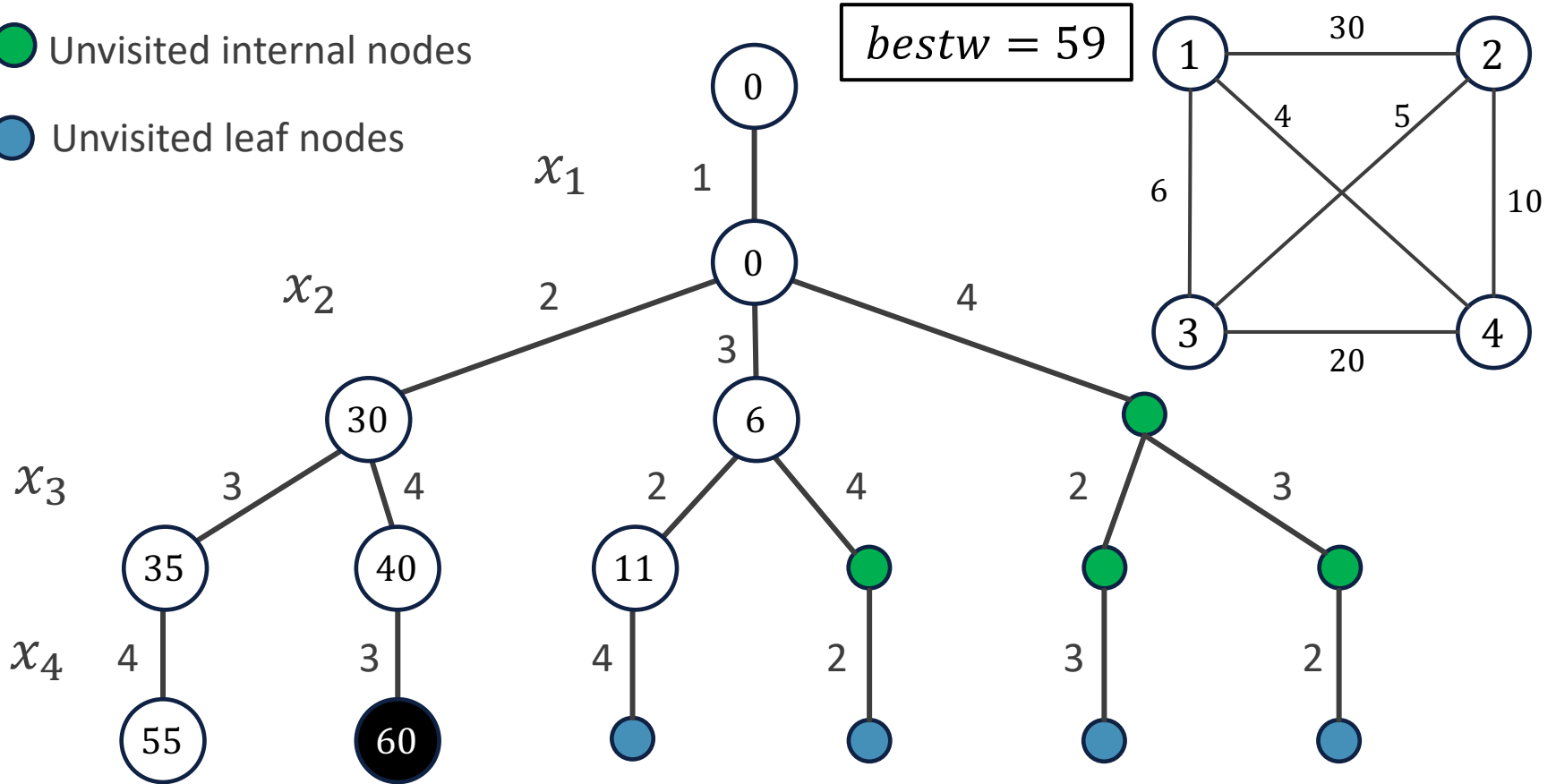
(1,2,3,4,1), 59



Example

● Unvisited internal nodes

● Unvisited leaf nodes



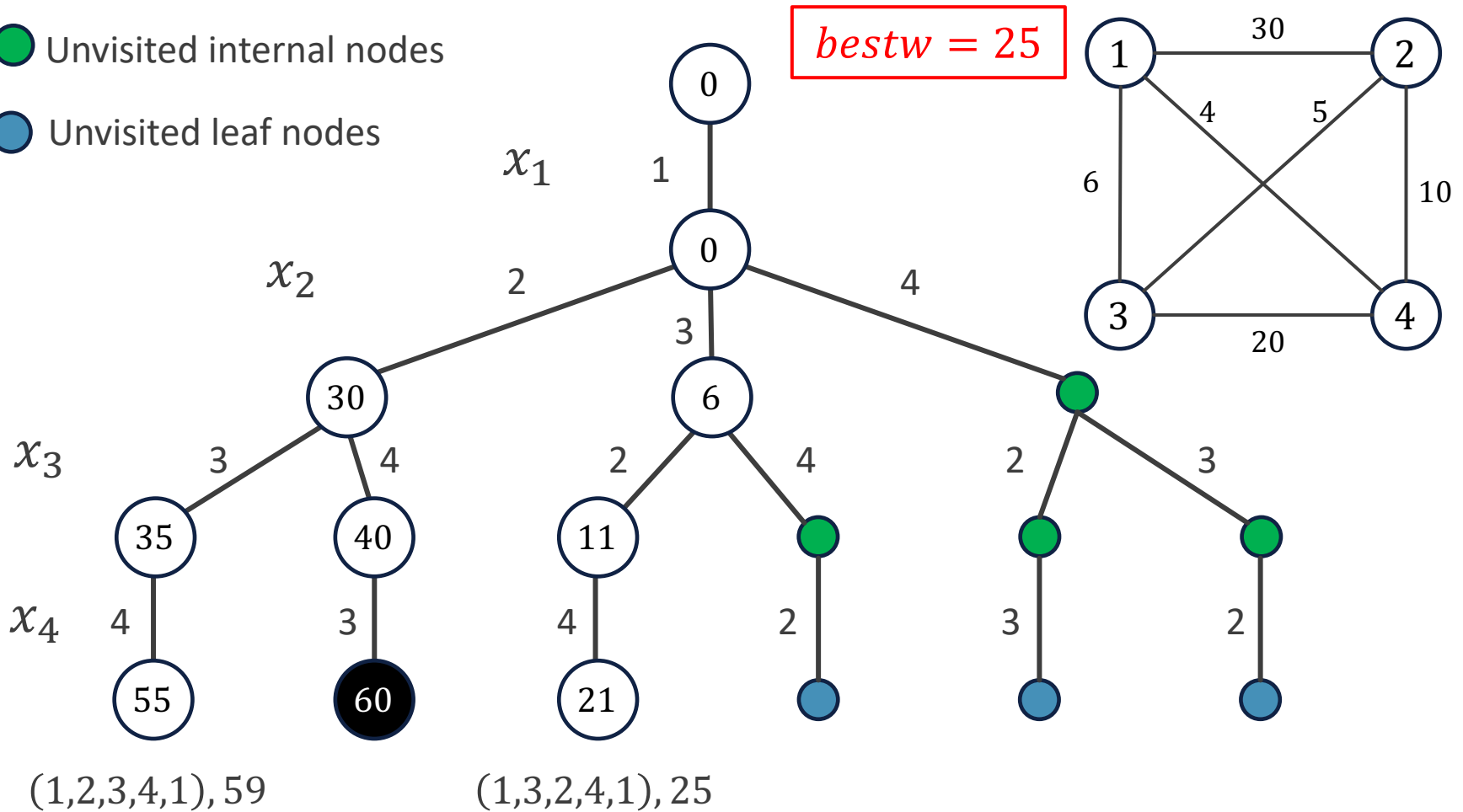
(1,2,3,4,1), 59



Example

● Unvisited internal nodes

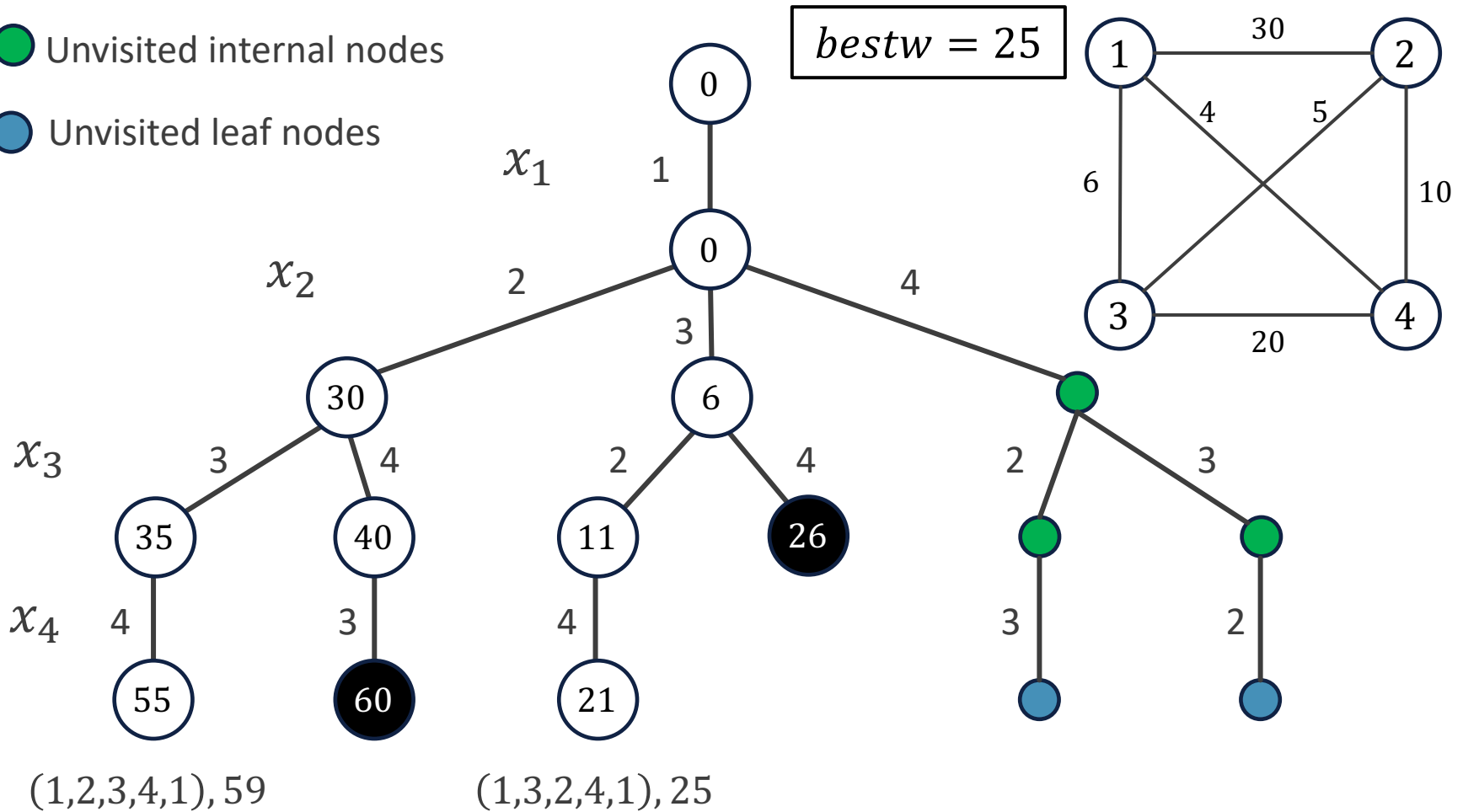
● Unvisited leaf nodes



Example

● Unvisited internal nodes

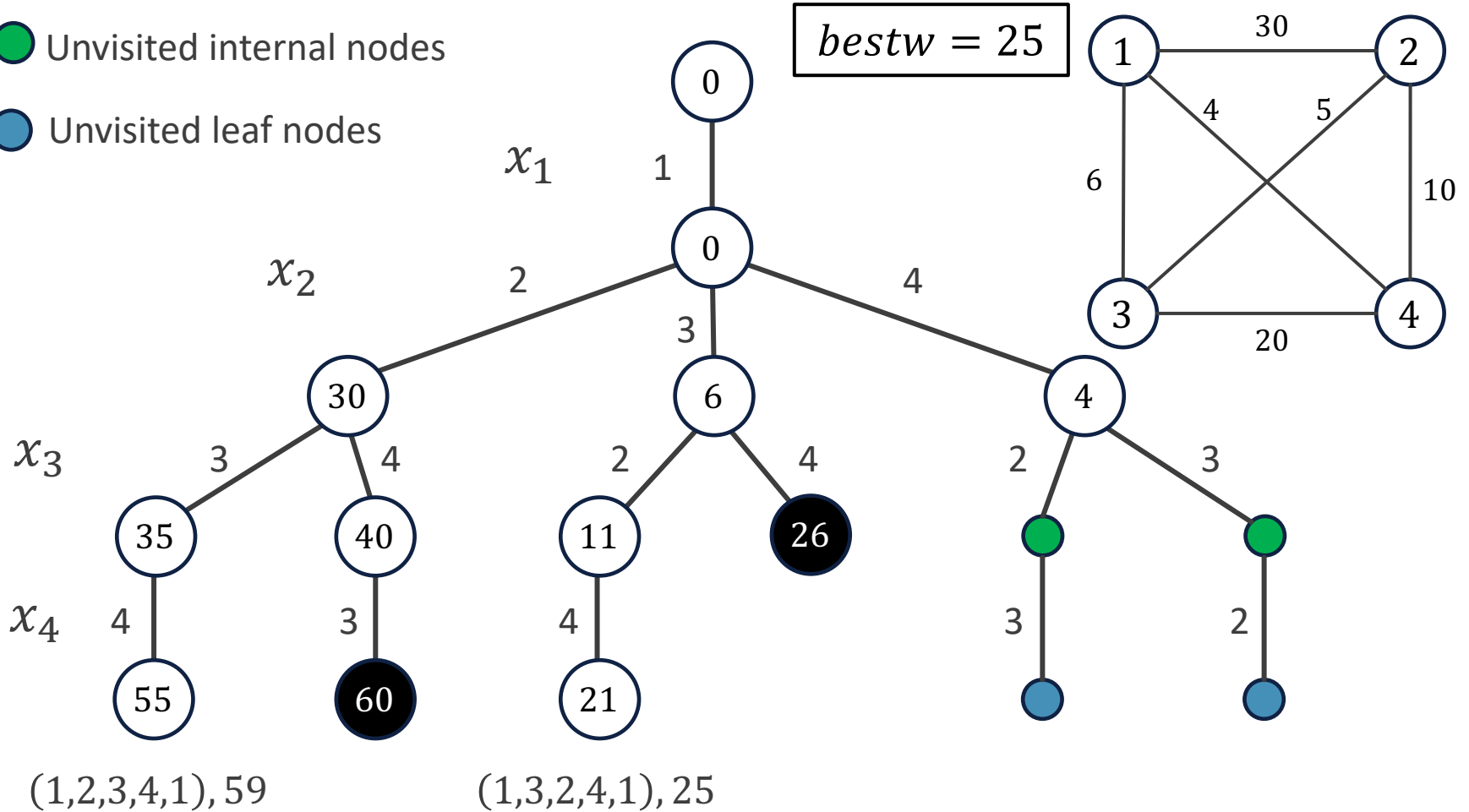
● Unvisited leaf nodes



Example

● Unvisited internal nodes

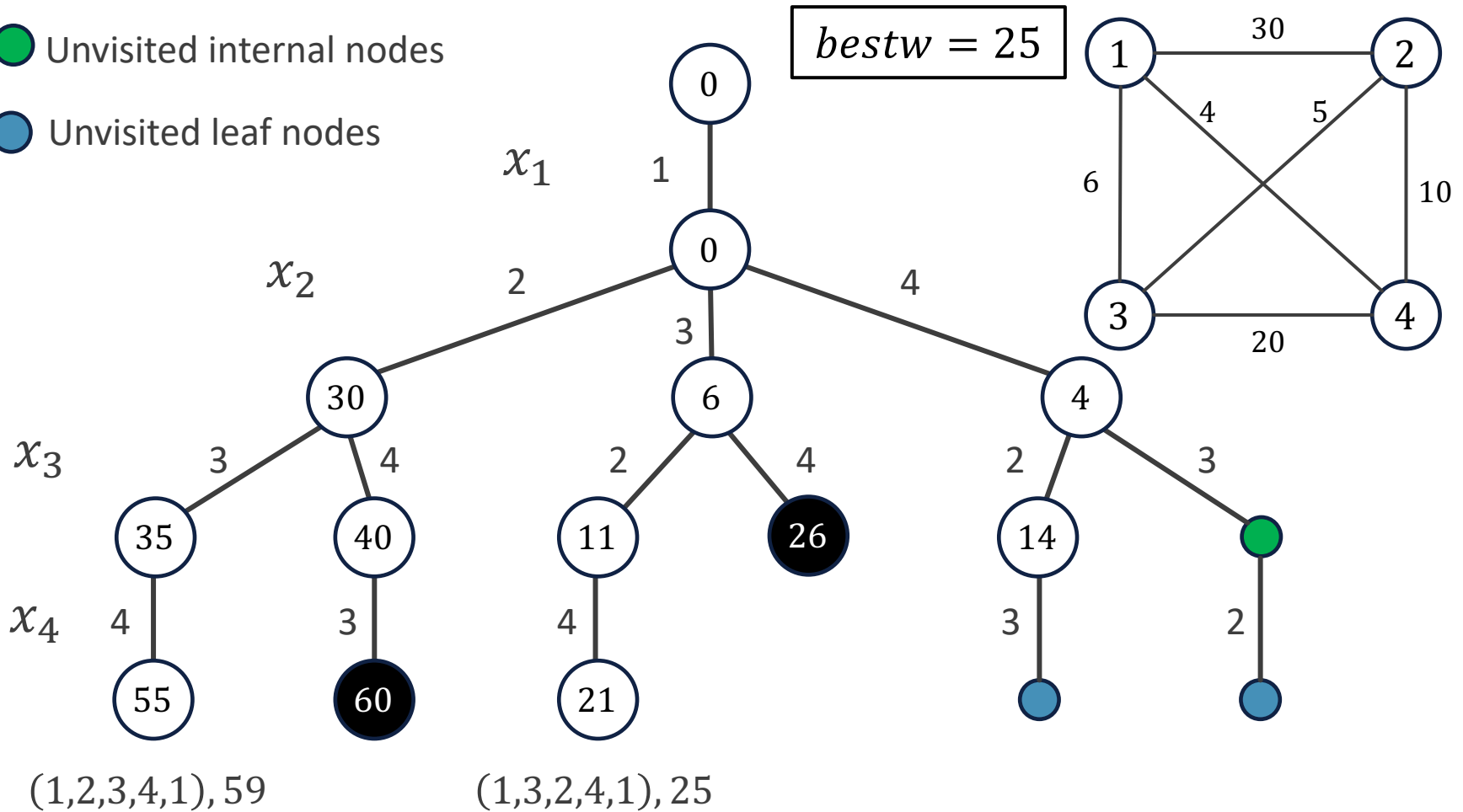
● Unvisited leaf nodes



Example

● Unvisited internal nodes

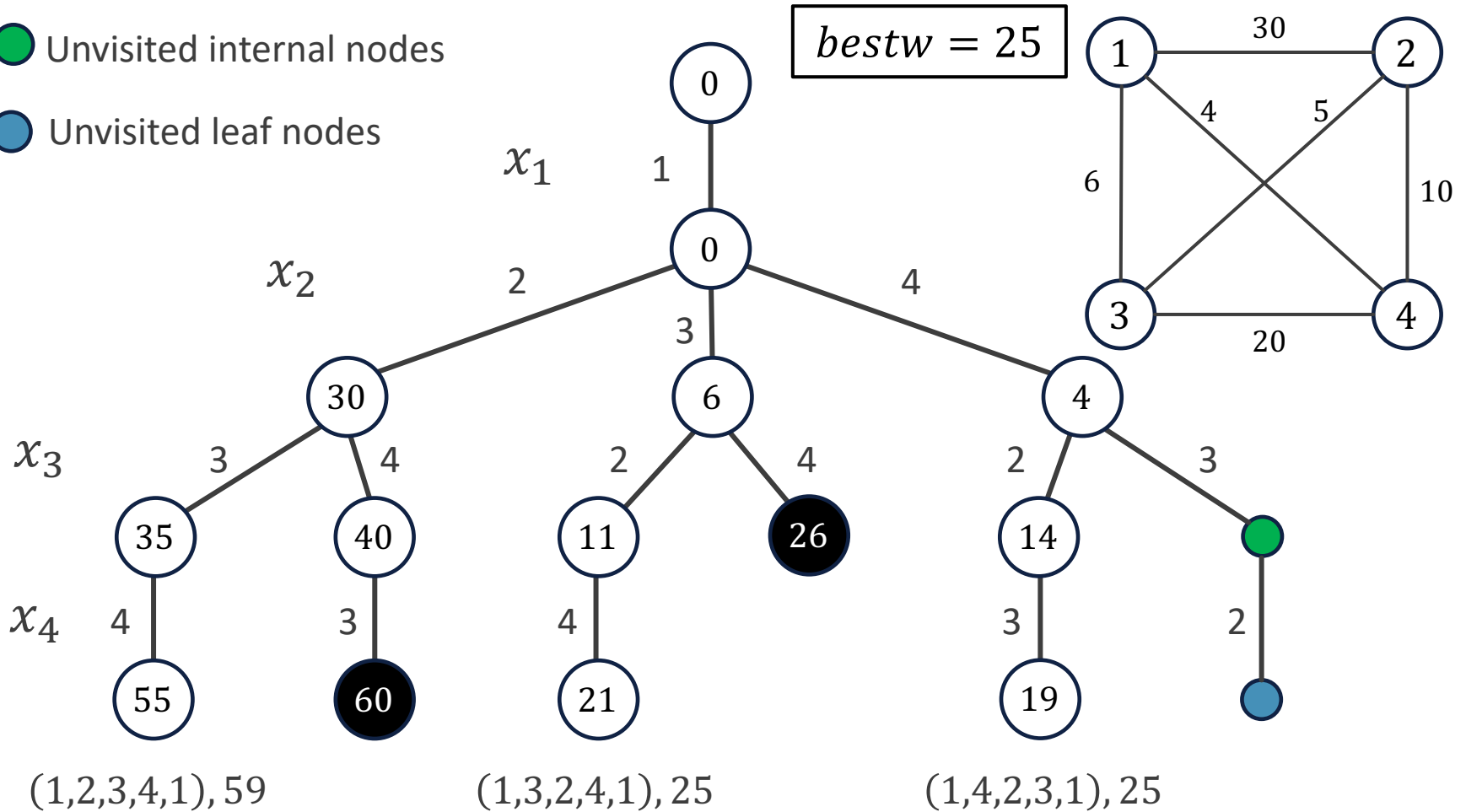
● Unvisited leaf nodes



Example

● Unvisited internal nodes

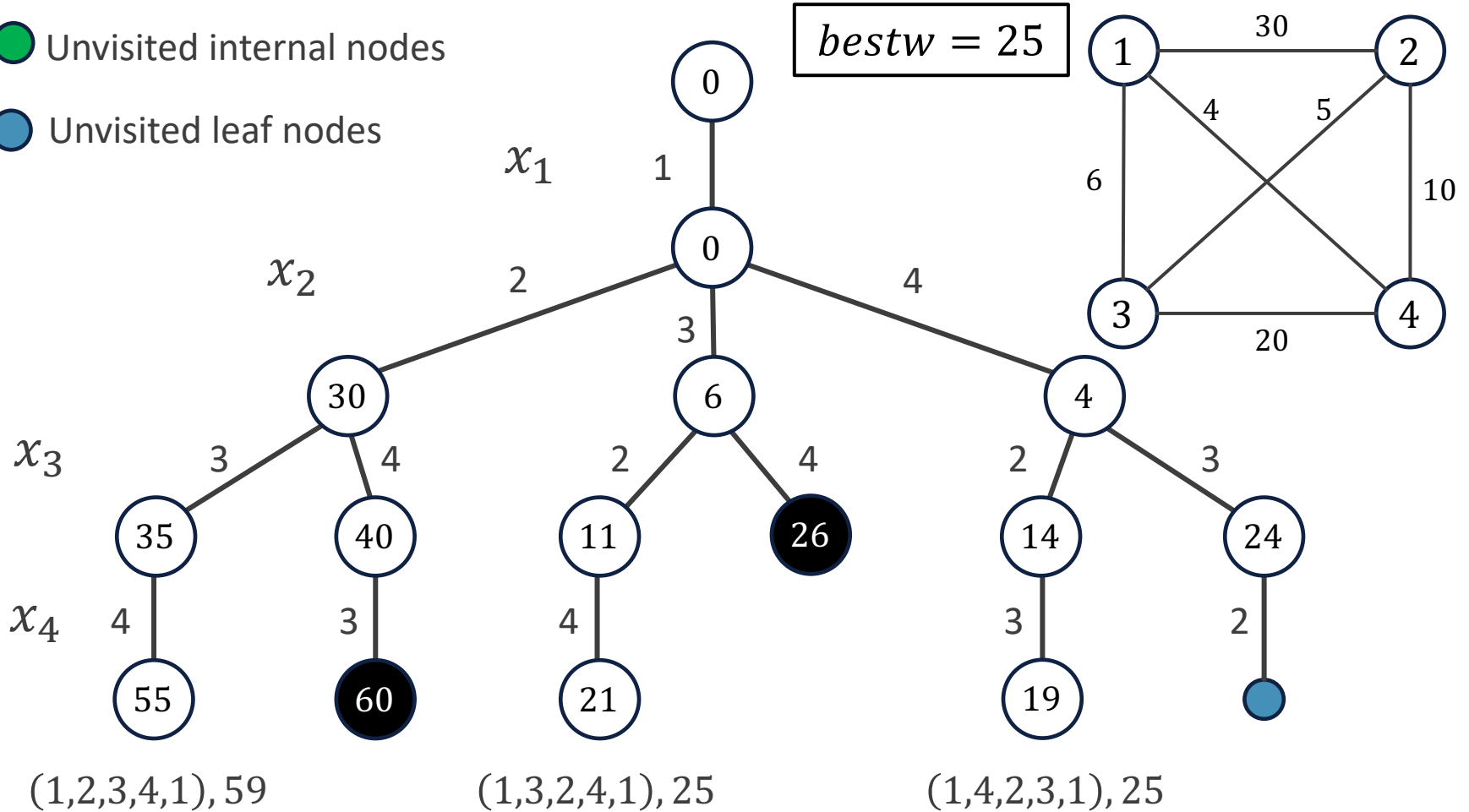
● Unvisited leaf nodes



Example

● Unvisited internal nodes

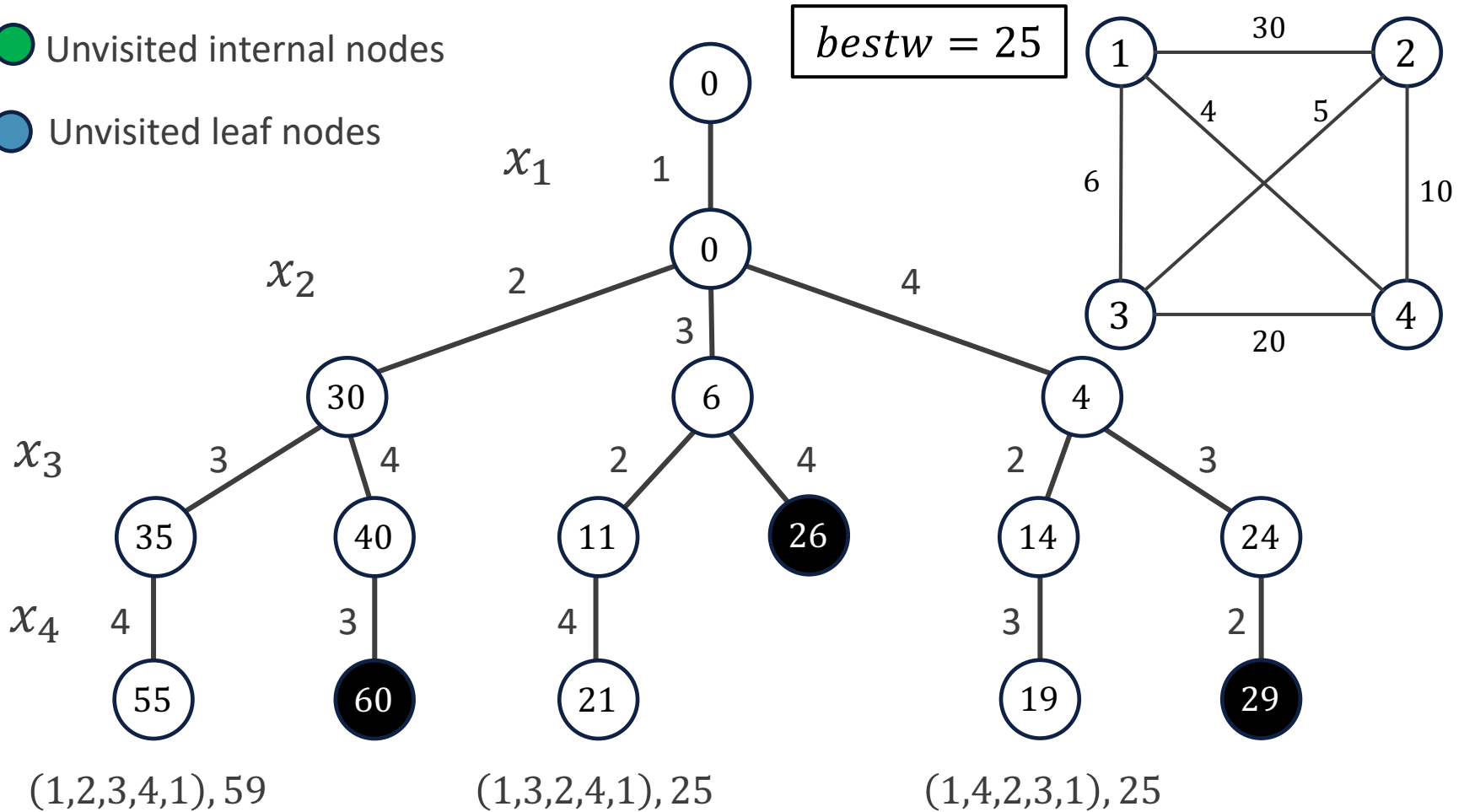
● Unvisited leaf nodes



Example

● Unvisited internal nodes

● Unvisited leaf nodes



Pseudocode

Call BacktrackTSP(2) with initialization $x[i] = i$.

BacktrackTSP(i)

1 **if** $i = n$ **then**

2 **if** $w[x[n-1], x[n]] \neq \infty$ and $w[x[n], 1] \neq \infty$ **then**

3 **if** $cw + w[x[n-1], x[n]] + w[x[n], 1] < bestw$ **then**

4 $bestw \leftarrow cw + w[x[n-1], x[n]] + w[x[n], 1]$

5 **for** $j \leftarrow 1$ **to** n **do**

6 $bestx[j] \leftarrow x[j]$

7 **else for** $j \leftarrow i$ **to** $n-1$ **do**

8 **if** $w[x[i-1], x[j]] \neq \infty$ and $cw + w[x[i-1], x[j]] < bestw$ **then**

9 $x[i] \leftrightarrow x[j]$

10 $cw \leftarrow cw + w[x[i-1], x[i]]$

11 BacktrackTSP($i+1$)

12 $cw \leftarrow cw - w[x[i-1], x[i]]$

13 $x[i] \leftrightarrow x[j]$

Connectivity between
the last two vertices

Connectivity between the
last and the first vertex

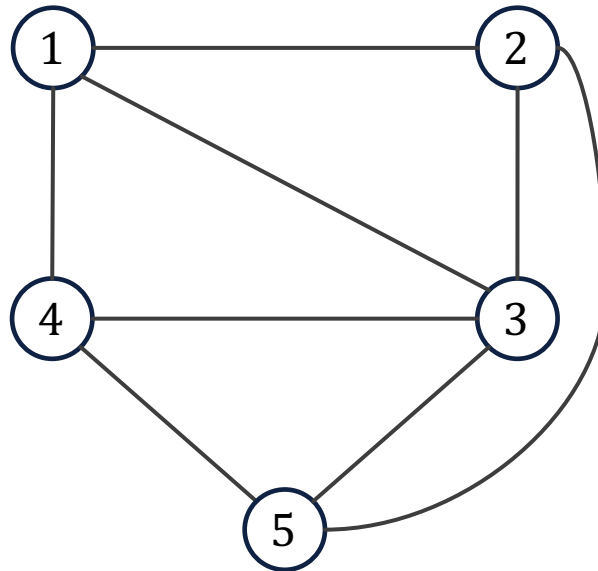
We don't iterate to n because
the last vertex is the only choice

We don't assign values
to $x[i]$, instead we use
permutation trick.



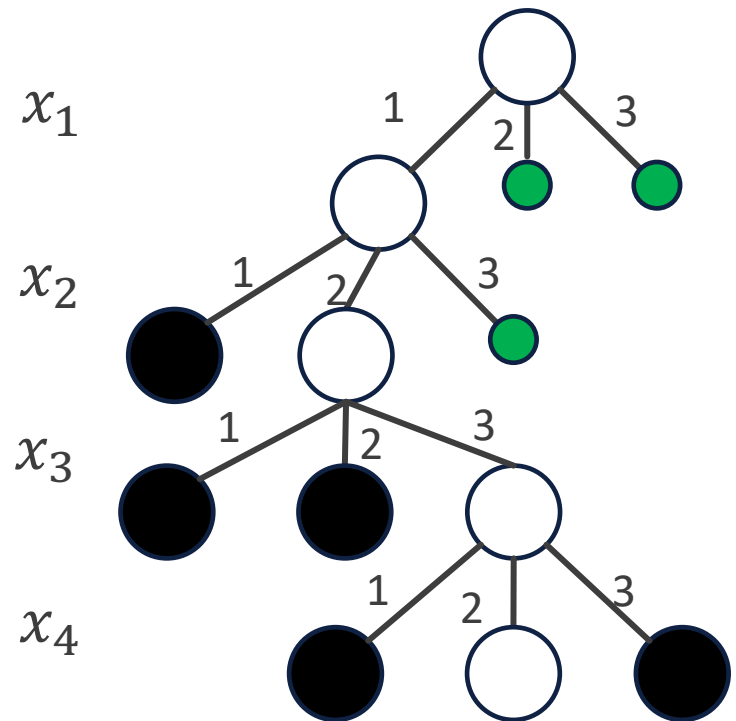
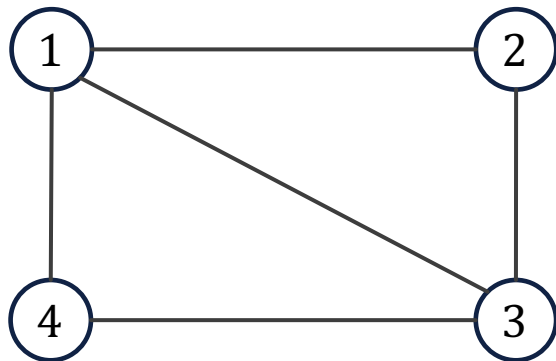
Classroom Exercise

Consider the 3-coloring problem for the given graph. Design constraint function and bounding function, and draw the pruned solution space tree to find a solution.



Classroom Exercise

- The constraint function is to check duplicated color.
- There is no bounding function for m-coloring problem.



Conclusion

After this lecture, you should know:

- What is the difference between DFS and backtracking.
- What is a solution space tree.
- What is constraint function and bounding function.
- What kind of problems can be solved by backtracking.



Homework

Page 238-240

12.7

12.8

12.10

- For these questions, you should describe the idea of how to design constraint function and bounding function. And then write down the pseudocode.



Experiment 1

- Write a program to solve a Sudoku puzzle by filling the empty cells.
- A sudoku solution must satisfy all of the following rules:
 - Each of the digits 1-9 must occur exactly once in each row.
 - Each of the digits 1-9 must occur exactly once in each column.
 - Each of the the digits 1-9 must occur exactly once in each of the 9 3x3 sub-boxes of the grid.
- Empty cells are indicated by the character ‘.’.

5	3	.	.	7
6	.	.	1	9	5	.	.	.
.	9	8	6	.
8	.	.	.	6	.	.	.	3
4	.	.	8	.	3	.	.	1
7	.	.	.	2	.	.	.	6
.	6	2	8	.
.	.	.	4	1	9	.	.	5
.	.	.	.	8	.	.	7	9

5	3	4	6	7	8	9	1	2
6	7	2	1	9	5	3	4	8
1	9	8	3	4	2	5	6	7
8	5	9	7	6	1	4	2	3
4	2	6	8	5	3	7	9	1
7	1	3	9	2	4	8	5	6
9	6	1	5	3	7	2	8	4
2	8	7	4	1	9	6	3	5
3	4	5	2	8	6	1	7	9



Experiment 2

- 使用回溯解决石材切割问题.



谢谢

有问题欢迎随时跟我讨论



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